

Overall Impact of the Programming Problem

1. Cost (to users) of programming.
2. APAR cost.
3. Delay in implementing applications.
4. Unpredictability of large projects.

Difficulty of programming is the main obstacle to the application of computers.

An obvious technological imbalance:

We are rapidly approaching a situation in which 4th generation hardware will be available -- but programming techniques are only 2nd generation.

Conclusions

Substantial improvements in all these respects are attainable

- 4'. Improved project predictability
- 2'. Debugging methods reducing APAR fix cost
- 1', 3'. Reduced programming costs
(Higher level language systems;
hardware support to be worked out).

Response to this problem:

'Modularization'

-- combat all pressures which lead to
interrelatedness of elements.

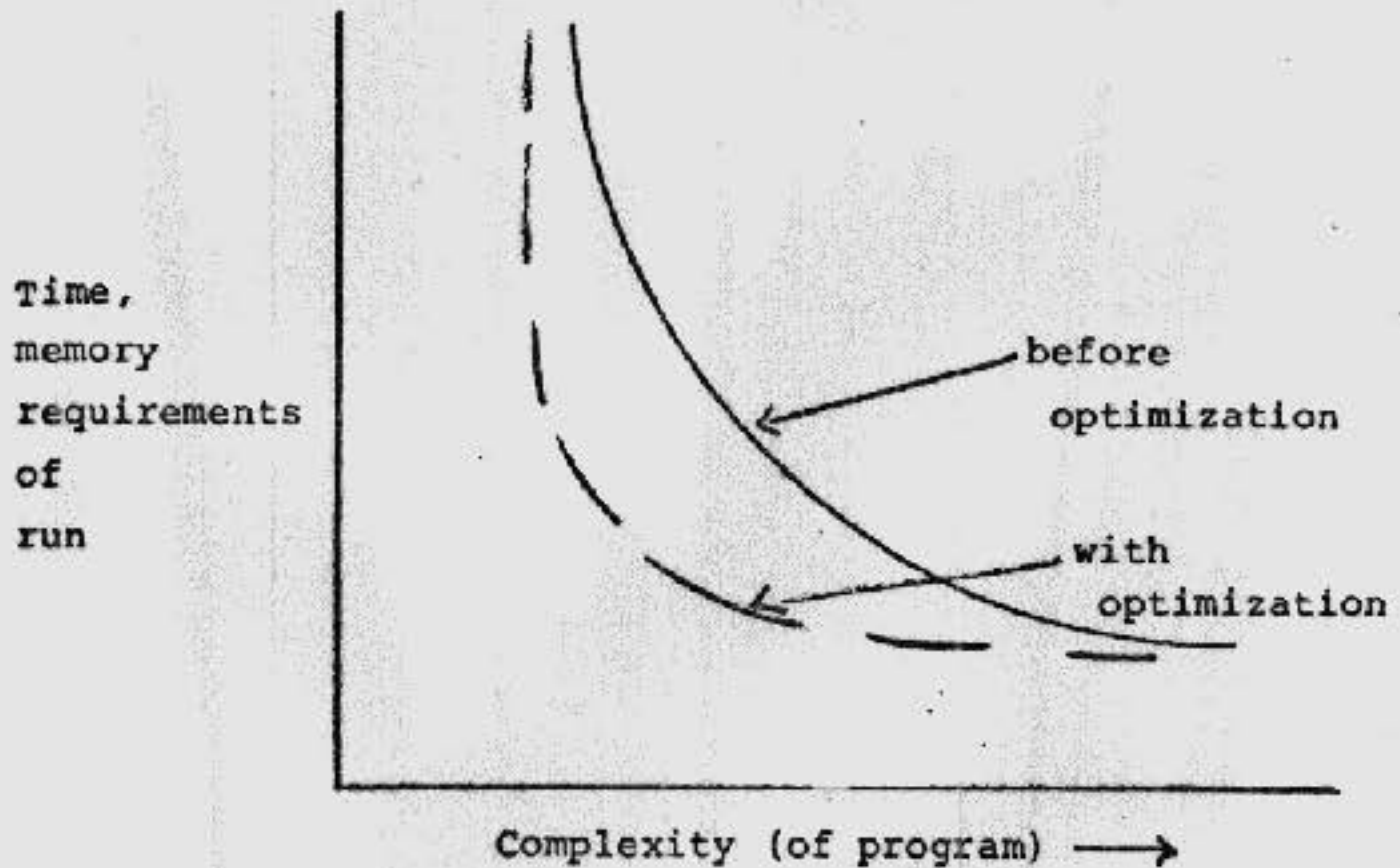
Use small number of powerful elements governed
by uniform simple conventions.

'Language of maximum expressivity'.

However:

Systematic modularization leads to diminished efficiency.

Expressivity-efficiency tradeoff.



Sources of difficulty in programming

Programming is a construction process

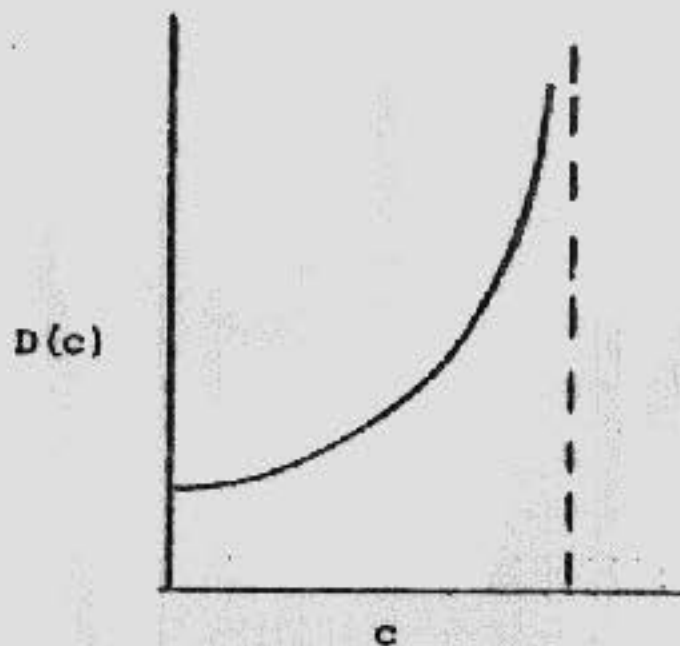
Elements E_1, \dots, E_n successively chosen

Local context of element E_j :

all aspects of other E 's affecting choice of E_j .

'Complexity' of local context of E_j --- $c(E_j)$.

Difficulty rises steeply with $c(E_j)$.



Total difficulty of completing program

$$DTOT = D(c(E_1)) + \dots + D(c(E_n))$$

Inefficient but highly expressive language
can be useful as prototyping tool

Two-stage programming technique.

Stage 1: Develop, debug algorithm using highly expressive algorithm-oriented language

Stage 2: Transcribe algorithm to production language, using higher level version as 'development matrix'.

Advantages

Function known in advance.

Able to test function adequacy.

Customer exposure to function.

Design known to be consistent.

Greatly improved implementation predictability.

B. Uses in University or Laboratory Environment

Non-production experimental programs

Algorithm modeling and measurement

Programs used for bootstrapping

Documentation of algorithms for instruction.

Possible Mode of Application.

The 'programming test stand':

50 million inst / sec micromachine with

16 million memory bytes

would appear as

computer of 7094 class with 1 million bytes of storage

on which

programming was speeded up by factor of 10

Successful data structure elaborations would

give practical programming tool for commercial

programming range.

Sources of Amodularity and Responses

Problem 1: 'All at once' design of function, logical structure, efficient encoding;

Response: 'decision postponement':
break development into orderly stages:
solve initial parts of problem without foreclosing possible approaches to remaining parts.
postpone choice of encoding until logical structure is worked out.

Problem 2: Common relationship of many processes to a smaller number of data structures.

Rigidity and specificity of code which reflects data structure details.

Response: Use logically powerful family of default data structures which enable many others to be modeled..
Develop declaratory approach to details of data structuring.
Allow functional treatment of storage sequences corresponding to presently available functional treatment of access sequences.
Allow declaratory specification of a variety of data objects to which operators apply in an object-dependent manner.

Problem 3: Present techniques require code to be written in order of eventual execution, rather than in logically most transparent arrangement.

Response: Break with linear coding style, and allow:
'footnoted style'
'remote code' dictions
Study 'whenever' dictions
'non-deterministic branch' dictions

Problem 4: Repetition of detail, with obligatory small variations, because of language-problem mismatch.

Response: Develop extension mechanisms, especially to allow:
extensions of semantic object classes
available declarations
global, rather than merely local, transformations
of source text
Develop mechanisms for reference resolution

7

Problem 5: Insufficiency of presently available
 debugging tools.

Response: Develop disciplined approach to statement
 of programmer assumptions.

Develop program-event oriented debugging language

Use high-level language to debug

lower-level production programs.

Attainable tradeoffs:

FORTTRAN - PL/1 Standard

| | |
|--------------------|-----|
| Data expansion | 1/1 |
| Execution slowdown | 1/1 |
| Programming effort | 1/1 |

High-Level Algorithm Oriented Language

A. Without 'data strategy' elaborations
or hardware enhancement

| | |
|---------------------|------|
| Data expansion | 8/1 |
| Execution slowdown | 30/1 |
| Programming speedup | 10/1 |

B. With 'data strategy' elaborations, but
no hardware enhancement

| | |
|---------------------|-----|
| Data expansion | 1/1 |
| Execution slowdown | 5/1 |
| Programming speedup | 5/1 |

C. With elaborations and hardware enhancement

| | |
|---------------------|-------|
| Data expansion | 1/1 |
| Execution slowdown | 1.5/1 |
| Programming speedup | 5/1 |

Basic objects: Sets and atoms. Sets may have atoms or sets as members.

Atoms may be: Integer, real, bitstring, charstring, label, subroutine, function

or: Blank. newat is blank atom creator.
Special undefined Ω

All standard operations provided for atoms

Operations for sets. $\{x\}$, $\{x,y,z\}$, etc.

| | | | |
|-------------------|---|---------------------|-----------|
| $x \in a$ | <u>nl</u> | $\ni a$ | <u>fa</u> |
| $a \text{ eq } b$ | $a \text{ ne } b$ | $a \text{ incs } b$ | , etc. |
| $a \text{ u } b$ | $a \text{ u } \{x\} \equiv a \text{ with } x$ | | |
| | $a - \{x\} \equiv a \text{ less } x$ | | |
| $\text{pow}(a)$ | | | |

Tuples: $\langle x,y,z \rangle$ $\langle x_1, \dots, x_n \rangle$
 $t(i)$ hd $t \equiv t(1)$ tl t .
tuple x pair x

Set former: $\{x \in a \mid C(x)\}$
 $\{e(x), x \in a \mid C(x)\}$
 $\{e(x,y), x \in a, y \in b(x) \mid C(x,y)\}$, etc.
 $\{e(n), m \leq n \leq mm \mid C(n)\}$

Functional application:

$f(x) = \{ \text{tl } x, x \in f \mid \text{pair } x \}$
 $f(x) = \text{if } \#f(x) \text{ eq } 1 \text{ then } \ni f(x) \text{ else } \Omega$

Compound operator:

[op: $x \in a$] $e(x)$

Example: [$+$: $x \in a$] $e(x) \equiv \sum_{x \in a} e(x)$

Quantifiers:

$\exists x \in a \mid C(x)$

$m \leq \exists n \leq mn \mid C(n)$

$\exists [x] \in a \mid C(x)$

$m \leq \exists [n] \leq mn \mid C(n)$

$\forall x \in a \mid C(x)$

Algol 60 conditional expressions.

Statement forms: statements punctuated with semicolons.

$a = \text{expn};$

$\langle a, b \rangle = \text{expn};$

$f(a) = \text{expn};$

means: remove all tuples with first component a
from set f ; then re-insert $\langle a, \text{expn} \rangle$

Algol 60 if-then-else

go to $\langle \text{label} \rangle;$

iteration headers:

(while $\langle \text{cond} \rangle$) $\langle \text{block} \rangle;$

or (while $\langle \text{cond} \rangle$) $\langle \text{block} \rangle$ end while;

($\forall x \in a \mid C(x)$) $\langle \text{block} \rangle;$

($m \leq \forall n \leq mn \mid C(n)$) $\langle \text{block} \rangle;$

($mn \geq \forall n \geq m \mid C(n)$) $\langle \text{block} \rangle;$

quit $\forall x;$ continue $\forall x;$

counting sort:

```
place = nℓ; (∀x ∈ set) place(x) = # {y ∈ set | f(y) ≤ f(x)};
end ∀x;
```

Huffman encode:

```
huffcode = [+ : 1 ≤ n ≤ #cstring] hufc(cstring(n));
```

Huffman decode:

```
dehuf = nulc; node = top;
(1 ≤ ∀n ≤ #bstring)
newnode = if bstring(n) eq 1 then l(node) else r(node);
if newnode eq Ω then
  dehuf = dehuf + node; node = top;
else node = newnode; end if; end ∀n;
```

Huffman tree:

```
work=chars; wfreq=freq; ℓ=nℓ, r=nℓ;
(while #work gt 1)
  c1 = getmin work; c2 = getmin work;
  nd = newat; ℓ(nd) = c1; r(nd) = c2;
  wfreq(nd) = wfreq(c1) + wfreq(c2);
  work = work with nd;
end while;
top = >work;
definef getmin set; external wfreq;
minfreq = [min: x ∈ set] wfreq(x);
xmin = ∃(x ∈ set | wfreq(x) eq minfreq);
set = set less xmin; return xmin; end getmin;
```

TOPOLOGICAL SORT

Problem

Suppose we are given a set S of arbitrary objects together with a partial ordering P on S . Suppose P is given as a set of pairs $\langle a, b \rangle$ with $a, b \in S$.

Arrange the members of S into a tuple T such that if $a = T(i)$ and $b = T(j)$, and $\langle a, b \rangle \in P$ (meaning $a \leq b$), then $i \leq j$.

Solution

1. We select an arbitrary member x of S which has no predecessor, and append that to T (T is initially null).
2. Having successfully placed x in T , we delete x from S and also delete all pairs beginning with x from P (if any exist).
3. We continue this process until S is null.

SETL Code

```

T = null;
(while S ne nl)
  x = s{y ∈ S | not(∃ pair ∈ P | pair(2) eq y)};
  T(#T+1) = x;
  S = S less x;
  P = P - {pair ∈ P | pair(1) = x};
end while;

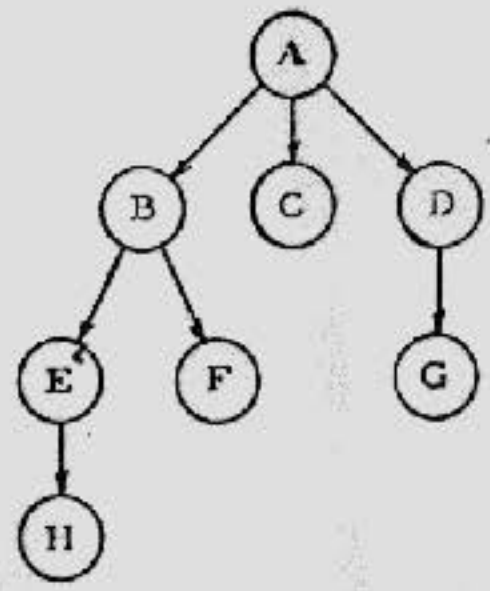
```

An ordered tree is a descendent function $\text{desc}(\text{node}, j)$ defined for j in some finite (possibly null) range.

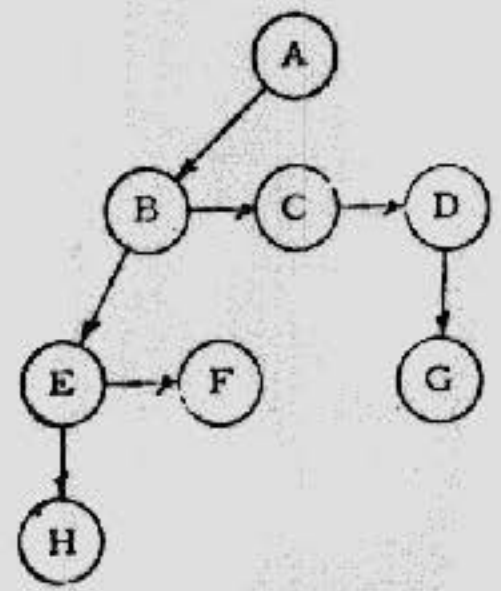
A binary tree is a pair of descendent functions L and R (left and right descendents).

The ordered and binary trees stand in an interesting 1-1 relationship that is illustrated below.

Ordered Tree



Binary Tree



Descendent Function

- A 1 B
- A 2 C
- A 3 D
- B 1 E
- B 2 F
- D 1 G
- E 1 H

Descendent Functions

| <u>L</u> | <u>R</u> |
|----------|----------|
| A B | B C |
| B E | C D |
| D G | E F |
| E H | |

Ordered To Binary Tree Transformation

```

define OTB(desc, L, R);
L = {<x(1), x(3)>, x ε desc | x(2) eq 1};
R = {<x(3), y(3)>, x ε desc, y ε desc | x(1) eq y(1) and
(x(2) + 1) eq y(2)};
return;
end OTB;

```

```

OTB:  PROCEDURE(DISC, L, #L, R, #R);
      DECLARE 1 DESC(*),
             2 DESC1 CHAR(50) VARYING,
             2 DESC2 FIXED BINARY,
             2 DESC3 CHAR(50) VARYING;
      DECLARE 1 L(*) CONTROLLED,
             2 (L1, L2) CHAR(50) VARYING;
      DECLARE 1 R(*) CONTROLLED,
             2 (R1, R2) CHAR(50) VARYING;
      DECLARE (#L, #R) FIXED BINARY;

BEGIN:  ALLOCATE L(DIM(DISC1, 1)); L1, L2 = ""; #L = 0;
        ALLOCATE R(DIM(DISC1, 1)); R1, R2 = ""; #R = 0;
        DO I = 1 TO DIM(DISC1, 1);
          IF DESC2(I) = 1 THEN DO; #L = #L + 1;
                                  L1(#L) = DESC1(I);
                                  L2(#L) = DESC3(I);
                                  END;
          DO J = 1 TO DIM(DISC1, 1);
            IF DESC1(J) = DESC1(I) & DESC2(J) = DESC2(I) + 1
              THEN DO; #R = #R + 1;
                      R1(#R) = DESC3(I);
                      R2(#R) = DESC3(J);
                      GO TO BUMP_I;
                      END;
          END /* DO J */;
        END /* DO I */;
BUMP_I;  END OTB;

```