

SSSSSSSS	VV	VV	WW	WW	MM	MM	CCCCCCCC	HH	HH	MM	MM	AAAAAA	SSSSSSSS
SSSSSSSS	VV	VV	WW	WW	MM	MM	CCCCCCCC	HH	HH	MM	MM	AAAAAA	SSSSSSSS
SS	VV	VV	WW	WW	MMMM	MMMM	CC	HH	HH	MMMM	MMMM	AA	AA SS
SS	VV	VV	WW	WW	MM	MM	CC	HH	HH	MMMM	NMMM	AA	AA SS
SS	VV	VV	WW	WW	MM	MM	CC	HH	HH	MM	MM	AA	AA SS
SS	VV	VV	WW	WW	MM	MM	CC	HH	HH	MM	MM	AA	AA SS
SSSSSS	VV	VV	WW	WW	MM	MM	CC	HHHHHHHHHH		MM	MM	AA	AA SSSSS
SSSSSS	VV	VV	WW	WW	MM	MM	CC	HHHHHHHHHH		MM	MM	AA	AA SSSSS
SS	VV	VV	WW	WW	MM	MM	CC	HH	HH	MM	MM	AAAAAAA	SS
SS	VV	VV	WW	WW	MM	MM	CC	HH	HH	MM	MM	AAAAAAA	SS
SS	VV	VV	WWWW	WWWW	MM	MM	CC	HH	HH	MM	MM	AA	AA SS
SS	VV	VV	WWWW	WWWW	MM	MM	CC	HH	HH	MM	MM	AA	AA SS
SSSSSSSS	VV	WW	WW	WW	MM	MM	CCCCCCCC	HH	HH	MM	MM	AA	AA SSSSSSS
SSSSSSSS	VV	WW	WW	WW	MM	MM	CCCCCCCC	HH	HH	MM	MM	AA	AA SSSSSSS

44	44	000000	000000	44	44	000000	5555555555
44	44	000000	000000	44	44	000000	5555555555
44	44	00	00	44	44	00	55
44	44	00	00	44	44	00	55
44	44	00	0000	44	44	00	555555
44	44	00	0000	44	44	00	555555
4444444444	00	00	00	4444444444	00	00	55
4444444444	00	00	00	4444444444	00	00	55
44	0000	00	0000	44	0000	00	55
44	0000	00	0000	44	0000	00	55
44	00	00	00	44	00	00	55
44	00	00	00	44	00	00	55
44	000000	000000	..	44	000000	555555	
44	000000	000000	..	44	000000	555555	

BBBB	U	U	N	N	DDDD	Y	Y	AAA
B	BU	U	N	N	D	Y	Y	A A
B	BU	U	NN	N	D	Y	Y	A A
BBBB	U	U	NN	N	D	Y		A A
B	BU	U	N	NN	D	Y		AAAAA
B	BU	U	N	N	D	Y		A A
BBBB	UUUUU	U	N	DDDD	Y			A A

LPTSPL VERSION 6(344) RUNNING ON LPT500  
 \*START\* USER BUNDY A [400,405] JOB SVWMCH SEQ. 672 DATE 20-APR-77 10:49:21 MONITOR 6.02A/RP04/DN67 \*START\*  
 REQUEST CREATED: 20-APR-77 10:50:08  
 FILE: DSKA2:SVWMCH.MAS[400,405] CREATED: 20-APR-77 10:47:00 <155> PRINTED: 20-APR-77 10:49:28  
 QUEUE SWITCHES: /PRINT:ARROW /FILE:ASCII /COPIES:1 /SPACING:1 /LIMIT:74 /FORMS:NORMAL

%%%%%SVWMCH . CMD @10:47 20-APR-1977 <055> (20)

SVWMCH.CMD  
USVW.OLD  
XTRACT.OLD  
MOTION.OLD  
SCHEMA.OLD  
FUNCC.OLD  
CNVERT.OLD  
II  
OLDXRT

\\\\\\\\

Old SVW Mechs program

Kentuk

%%%USVW . OLD 014:17 19-APR-1977 <055> (964)

```
/*USVW*/
/*UTILITIES FOR SVW PROLOG*/
/*BUNDY JAN 1976*/
```

```
/*OPERATOR DECLARATIONS*/
```

```
:= OP(200,FY,"-"). /*UNARY MINUS*/
:= OP(300,XFY,":"). /*EXPONENTIATION*/
:= OP(410,XFY,"."). /*LIST CONS*/
:= OP(490,XFY,"%"). /*BINARY MINUS*/
:= OP(700,XFX,>"). /*GREATER THAN*/
:= OP(700,XFX,>="). /*GREATER THAN OR EQUAL TO*/
:= OP(850,XFY,"&"). /*CONJUNCTION*/
:= OP(950,XFY,"#"). /*DISJUNCTION*/
/* *, +, /, = ARE ALREADY DECLARED*/
```

```
/*TRACING*/
PR(-MES) :- WRITE(-MES), NEWLINE.
```

```
PPR(TRUE).
```

```
PPR(-E->EC) :- TRACE(-E,2), PPR(-EC),
```

```
TRACE(-MES,-N) :- TFLAG(-M), -M<-N, !.
```

```
TRACE(-MES,-N) :- WRITE(-MES), NEWLINE,
```

```
TFLAG(3),
```

```
TLIM(-N) :- ASSERTD(TFLAG(-N)).
```

```
/* CONVENTIONS 0. NO PRINTING
   1. BARE MINIMUM
   2. NORMAL PROTOCOL (DEFAULT)
   3. GENERAL DEBUGGING
   > 3. SPECIAL DEBUGGING*/
```

```
/*SETS*/
MEMBER(+X,+X,+YS) :- !.
MEMBER(+X,+Y,+YS) :- MEMBER(+X,+YS).
SUBSET(NIL,+YS) .
SUBSET(+X,+XS,+YS) :- MEMBER(+X,+YS), SUBSET(+XS,+YS),
UNION(NIL,+YS,+YS) .
UNION(+X,+XS,+YS,+ZS) :- MEMBER(+X,+YS), !, UNION(+XS,+YS,+ZS).
UNION(+X,+XS,+YS,+X,+ZS) :- UNION(+XS,+YS,+ZS).
SUBTRACT(NIL,+YS,NIL) .
SUBTRACT(+X,+XS,+YS,+ZS) :- MEMBER(+X,+YS), !, SUBTRACT(+XS,+YS,+ZS),
SUBTRACT(+X,+XS,+YS,+X,+ZS) :- SUBTRACT(+XS,+YS,+ZS),
SETEQ(+SET1,+SET2) :- SUBSET(+SET1), SUBSET(+SET2).
```

```
/*WORDS AND NUMBERS*/
INTEGER(+N) :- NATNUM(+N), !,
INTEGER(+N) :- +N =,, ",",+M, NATNUM(+M),
NATNUM(+N) :- +N =,, +M,NIL, CHECKLIST(DIGIT,+M),
BOUND(+X) :- THNOT(VAR(+X)),
NONVAR(+X) :- THNOT(VAR(+X)),
WORD(+X) :- +X =,, (+H.+T).NIL, LETTER(+H),
CONCAT(+W1,+W2,+W3) :- +W1 =,, +LS1,NIL, +W2 =,, +LS2,NIL,
APPEND(+LS1,+LS2,+LS3), +W3 =,, +LS3,NIL,
```

```
/*MISC*/
/*IF THEN ELSE*/
COND(+P,+Q,+R) :- +P, !, +Q,
COND(+P,+Q,+R) :- +R.
```

```
/*PREDICATE APPLICATION*/
APPLY(+P,+ARGS1) :-
+P =,, +LS,+ARGS2, APPEND(+ARGS1,+ARGS2,+ARGS),
+Q =,, +LS,+ARGS, !, +Q,
/*X AND Y ARE DIFFERENT SYMBOLS*/
DIFF(+X,+X) :- !, FAIL,
DIFF(+X,+Y) .
```

```
/* GENERATES NEW SYMBOL Q WITH PREFIX PREF */
GENSYM(-PREF,-Q) :- VAR(-Q), CURRENT(-PREF,+N),
    DENY(COUNT(-PREF,+N)), +(N,1,-N1), ASSERT(COUNT(+PREF,+N1)),
    CONCAT(+PREF,-N1,-Q), !.

CURRENT(-PREF,+N) :- COUNT(-PREF,+N), !.
CURRENT(-PREF,0).

/* CONDITIONAL GENSYM */
CGENSYM(-PREF,-X) :- GENSYM(-PREF,-X), !,
CGENSYM(-PREF,-X).

/* FIND ALL XS OBEDIING P */
FOUND(NIL).

FINDALL(-P,+DUM) :-
    APPLY(-P,-X,NIL), FOUND(-XL),
    DENY(FOUND(-XL)), ASSERT(FOUND(-X,-XL)), FAIL.

FINDALL(-P,-XL) :- FOUND(-XL),
    DENY(FOUND(-XL)), ASSERT(FOUND(NIL)), !.

/* FUNNY CALLS */

/* JUST CALL */
CALL(-L) :- +L.

/* GARBAGE COLLECT CALL */
GCC(-L) :- ONCEANDFAIL(-L).
GCC(-L) :- RETRIEVE(-L).

ONCEANDFAIL(-L) :- -L, ASSERT(RETRIEVE(-L)), !, FAIL.

/* LIT ASSUMED FALSE SINCE NOT PROVABLE */
THNOT(+LIT) :- +LIT, !, FAIL.
THNOT(+LIT).

NLC(-L) :- SUBGOAL+OF(-L), !, FAIL. /* NON LOOP CALL */

NLC(-L) :- -L.

CC(-L) :- FPC(-L), !, /* CREATIVE CALL */
CC(-L) :- CCFLAG(ON), DECLARE(-L), !.

CCFLAG(ON).

/* L CALLED REPEATEDLY */
AGAIN(-L) :- -L, PR(-L), FAIL.

AGAIN(-L) :- PR(THATS-ALL-FOLKS).

/* FUNNY ASSERTS */
```

```
/*ASSERTION REMOVABLE ON BACKUP*/
POSTULATE(+L) :- ASSERT(+L).
POSTULATE(+L) :- DENY(+L),FAIL.

PASSERT(+ASS) :- ASSERT(+ASS), TRACE(+ASS,6). /*PRINT ASSERT*/

/*PRINT ASSERT AT BOTTOM*/
PASSERTC(+ASS) :- ASSERTC(+ASS), TRACE(+ASS,6).

CASSERTC(+L) :- +L,! . /*CONDITIONAL ASSERT*/
CASSERTC(+L) :- ASSERTC(+L),!.

TRUE .
```

\\\\\\

%%%XTRACT . OLD @16:30 19-APR-1977 <055> (2477)

```
/* XTRACT */
/* MECHANICS EQUATION EXTRACTION ROUTINES */
/* GATHERED BY ALAN BUNDY 8/9/76 */

/* ABSENT FRIENDS */

CONVERT(←X, ←X).
SIMPLIFY(←X, ←X).
SIMSOLVE(←E, ←X, ←E).

/* MARPLES ALGORITHM */

/* BASIS CASE */
GETEQNS(NIL, ←GS, ←US, TRUE, NIL).

/* GET EQUATIONS WITH NO INTERMEDIATES */
GETEQNS(←X, ←XS, ←GS, ←US, ←E&←ES, ←X, ←XS1)
  :- MAKESL(←X, ←SL), CHOOSEQN(←SL, ←E, ←U, ←US, OFF),
   TRACE(EQUATION-←U-FORMED, 6),
   WORDSIN(←E, ←VS), MEMBER(←X, ←VS),
   UNION(←X, ←XS, ←GS, ←YS), SUBSET(←VS, ←YS),
   TRACE(←E-SOLVES-FOR-←X, 5),
   GETEQNS(←XS, ←X, ←GS, ←U, ←US, ←ES, ←XS1).

/* GET EQUATIONS WITH INTERMEDIATES */
GETEQNS(←X, ←XS, ←GS, ←US, ←E&←ES, ←X, ←XS1)
  :- MAKESL(←X, ←SL), CHOOSEQN(←SL, ←E, ←U, ←US, ON),
   TRACE(EQUATION-←U-FORMED, 6),
   WORDSIN(←E, ←VS), MEMBER(←X, ←VS),
   UNION(←X, ←XS, ←GS, ←YS), SUBTRACT(←VS, ←YS, ←ZS), DIFF(←ZS, NIL),
   APPEND(←XS, ←ZS, ←WS),
   TRACE(←E-SOLVES-FOR-←X-BUT-INTRODUCES-←ZS, 5),
   GETEQNS(←WS, ←X, ←GS, ←U, ←US, ←ES, ←XS1).

/* ASSUME X IS ELIMINABLE */
GETEQNS(←X, ←XS, ←GS, ←US, ←ES, ←X, ←XS1)
  :- TRACE(I-ASSUME-←X-I-S-ELIMINABLE, 2),
   GETEQNS(←XS, ←X, ←GS, ←US, ←ES, ←XS1).

PASS(←N, ←S, ←US) :- OLDEQN(←E, ←N, ←S), !, FAIL.
PASS(←N, ←S, ←US) :- UNUSED(←N, ←S, ←US), !.

UNUSED(←NAME, ←SIT, ←US) :- MEMBER(←NAME--SIT, ←US), !, FAIL.

UNUSED(CONSTACCEL-←N1, ←SIT, ←US) :- MEMBER((CONSTACCEL-←N2)--SIT, ←US),
  MEMBER((CONSTACCEL-←N3)--SIT, ←US), DIFF(←N2, ←N3), !, FAIL.
```

```

UNUSED(RESOLVE,(+PART,+PER,+DIR1),+US) :-  

    MEMBER(RESOLVE-(+PART-+PER-+DIR2),+US),  

    MEMBER(RESOLVE-(+PART-+PER-+DIR3),+US),  

    DIFF(-DIR2,-DIR3), !, FAIL.  

UNUSED(VEL, +PSET1--TIME, +US) :-  

    MEMBER(VEL-(+PSET2--TIME), +US), SETEQ(+PSET1,+PSET2), !, FAIL.  

UNUSED(ACCEL,+PSET1--TIME,+US) :-  

    MEMBER(ACCEL-(+PSET2--TIME),+US),  

    SETEQ(+PSET1,+PSET2), !, FAIL.  

UNUSED(+NAME,+SIT,+US).  

CHOOSEQN(+C1,+REST,+E,+C1--S,+US,+SW) :-  

    MAKEEQN(+E,+C1--S,+US,+SW).  

CHOOSEQN(+C1,+REST,+E,+U,+US,+SW) :-  

    CHOOSEQN(+REST,+E,+U,+US,+SW).  

MAKESL(+X,+SL) :- EQNSLIST(+EQNS), TYPE(+X,+XTYPE),  

    SUBLIST(TEST(+XTYPE),+EQNS,+SL),  

    TRACE(SHORTLIST-IS--SL,7).  

TEST(+EQN,+XTYPE) :- RELATES(+EQN,+VTYPES), MEMBER(+XTYPE,+VTYPES).  

MAKEQN(+E,+N--S,+US,+SW) :- OLDEQN(+E,+N,+S), UNUSED(+N,+S,+US).  

MAKEQN(+E,+N--S,+US,+SW) :-  

    ASSERTD(CCFLAG(+SW)),  

    ISEQN(+E,+N--S,+US), CASSERTC(OLDEQN(+E,+N,+S)).
```

/\*THE EQUATIONS\*/

```

EQNSLIST([RESOLVE,STRACCEL,RELVEL,RELACCEL,  

    TIMESUM,DISTSUM,(CONSTACCEL-1),(CONSTACCEL-2),CONSTVEL,  

    (CONSVENERGY-1),(CONSVENERGY-2),AVERVEL]).  

  

RELATES(RESOLVE,[FORCE,ACCEL,MASS]) :- !.  

RELATES(STRACCEL,[ACCEL]) :- !.  

RELATES(RELVEL,[VEL]) :- !.  

RELATES(RELACCEL,[ACCEL]) :- !.  

RELATES(TIME SUM,[DURATION]) :- !.  

RELATES(DISTSUM,[DISTANCE]) :- !.  

RELATES(CONSTACCEL-1,[ACCEL,VEL,DURATION]) :- !.  

RELATES(CONSTACCEL-2,[ACCEL,DISTANCE,VEL,DURATION]) :- !.  

RELATES(CONSTVEL,[VEL,DISTANCE,DURATION]) :- !.
```

```

RELATES(CONSVENERGY-1,[VEL,DISTANCE]) :- !.
RELATES(CONSVENERGY-2,[VEL,DISTANCE]) :- !.
RELATES(AVERVEL,[VEL,DISTANCE,DURATION]) :- !.

ISEQN(←FORCESUM←M←A←COSTERM,RESOLVE-(←PART←PER←DIR1),←US)
:- PERIOD(←PER), PARTICLE(←PART),
  FIXDIR(←DIR1),
  PASS(RESOLVE,(←PART←PER←DIR1),←US),
  CC(MASS(←PART,←M,←PER)),
  CC(ACCEL(←PART,←A,←DIR2,←PER)),
  COSFACT(←DIR1,←DIR2,←COSTERM),
  SUMFORCES(←PART,←DIR1,←PER,←FORCESUM).

ISEQN(2*←A0←A1←A2,STRACCEL-(←SYS←TIME),←US) :- 
  PULLSYS(←SYS,←PULL,←STR,←P1,←P2,←TIME),
  PASS(STRACCEL,(←SYS←TIME),←US),
  CC(ACCEL(←PULL,←A0,270,←TIME)),
  CC(ACCEL(←P1,←A1,270,←TIME)),
  CC(ACCEL(←P2,←A2,90,←TIME)).

ISEQN(+V13=+V123,RELVEL-([+P1,+P2,+P3]←TIME),←US) :- 
  PARTICLE(←P1),PARTICLE(←P2),DIFF(←P1,←P2),
  PARTICLE(←P3),DIFF(←P1,←P3),DIFF(←P2,←P3),PERIOD(←TIME),
  PASS(RELVEL,[+P1,+P2,←V12,←DIR12,←TIME],←US),
  CC(RELVEL(←P1,←P2,←V12,←DIR12,←TIME)),
  CC(RELVEL(←P2,←P3,←V23,←DIR23,←TIME)),
  CC(RELVFL(←P1,←P3,←V13,←DIR13,←TIME)),
  VECADD(←V12,←DIR12,←V23,←DIR23,←V123,←DIR13).

ISEQN(←A13=←A123,RELACCEL-([+P1,+P2,+P3]←TIME),←US) :- 
  PARTICLE(←P1),PARTICLE(←P2),DIFF(←P1,←P2),
  PARTICLE(←P3),DIFF(←P1,←P3),DIFF(←P2,←P3),PERIOD(←TIME),
  PASS(RELACCEL,[+P1,+P2,←P3]←TIME,←US),
  CC(RELACCEL(←P1,←P2,←A12,←DIR12,←TIME)),
  CC(RELACCEL(←P2,←P3,←A23,←DIR23,←TIME)),
  CC(RELACCEL(←P1,←P3,←A13,←DIR13,←TIME)),
  VECADD(←A12,←DIR12,←A23,←DIR23,←A123,←DIR13).

ISEQN(←T←SUM,TIMESUM←P,←US) :- 
  PARTITION(←P,←PS), PASS(TIMESUM,←P,←US),
  CC(DURATION(←P,←T)), SUMDURS(←PS,←SUM).

ISEQN(←D←SUM,DISTSUM-(←P←OBJ),←US) :- PARTITION(←P,←PL),
  CC(DISTANCE(←OBJ,←D,←P)), PASS(DISTSUM,←P←OBJ,←US),
  SUMDIST(←OBJ,←PL,←SUM).

ISEQN(←V←U+(←A←T),(CONSTACCEL-1)-(←P←OBJ),←US)
:- PARTICLE(←OBJ), PERIOD(←P),
  ACCEL(←OBJ,←A,←DIR,←P), PASS(CONSTACCEL-1,(←P←OBJ),←US),
  ISQINVAR(←A), DIFF(←A,ZERO),
  CC(DURATION(←P,←T)), INITVEL(←OBJ,←U,←DIR,←P),
  FINVEL(←OBJ,←V,←DIR,←P).

ISEQN(←D=(←U←T)+((1/2)*←A*(←T:2)),(CONSTACCEL-2)-(←P←OBJ),←US)

```

```

:- PARTICLE(←OBJ), PERIOD(←P),
ACCEL(←OBJ, ←A, ←DIR, ←P), PASS(CONSTACCEL-2, (←P-←OBJ), ←US),
ISQINVAR(←A),
DIFF(←A, ZERO), CC(DURATION(←P, ←T)),
INITVEL(←OBJ, ←U, ←DIR, ←P), CC(DISTANCE(←OBJ, ←D, ←P)).

ISEQN(←V ←T = ←S, CONSTVEL-(←P-←OBJ), ←US)
:- PARTICLE(←OBJ), PERIOD(←P),
VEL(←OBJ, ←V, ←DIR, ←P), PASS(CONSTVEL, (←P-←OBJ), ←US),
ISQINVAR(←V), DIFF(←V, ZERO),
CC(DURATION(←P, ←T)), CC(DISTANCE(←OBJ, ←S, ←P)).

ISEQN((1/2)*←V : 2 - (1/2)*←U : 2 = G*←H, (CONSVENERGY-1) - (←P-←O), ←US)
:- PARTICLE(←O), PERIOD(←P),
PASS(CONSVENERGY-1, (←P-←O), ←US),
DBC(MOTION(←O, ←PATH, ←START, ←SIDE, ←P)),
FREE(←PATH, ←P, ←O),
DROP(←PATH, ←START, ←H),
FINVEL(←O, ←V, ←DIR1, ←P), INITVEL(←O, ←U, ←DIR2, ←P).

ISEQN((1/2)*←V : 2 - (1/2)*←U : 2 = G*←H, (CONSVENERGY-2) - (←P-←O), ←US)
:- DBC(MOTION(←O, ←PATH, ←START, ←SIDE, ←P)),
PASS(CONSVENERGY-2, (←P-←O), ←US),
FREE(←PATH, ←P, ←O),
TYPICAL DROP(←PATH, ←START, ←H),
CC(VEL(←O, ←V, ←DIR1, ←P)),
INITVEL(←O, ←U, ←DIR2, ←P).

ISEQN(←AV = ←D / ←T, AVERVEL-(←P-←OBJ), ←US)
:- PARTICLE(←OBJ), PERIOD(←P),
AVERVEL(←OBJ, ←AV, ←DIR, ←P), PASS(AVERVEL, (←P-←OBJ), ←US),
CC(DISTANCE(←OBJ, ←D, ←P)), CC(DURATION(←P, ←T)).

```

```

/*SYMBOLS*/
WORDSIM(←E, NIL) :- ISCONST(←E), !.
WORDSIM(←E, NIL) :- ISQCONST(←E), !.
WORDSIM(←E, ←E, NIL) :- WORD(←E), !.
WORDSIM(←E, ←VS) :- ←E = .., ←S, ←ARGS, SWORDSIM(←ARGS, ←VS),
SWORDSIM(NIL, NIL).
SWORDSIM(←ARG, ←ARGS, ←VS)
:- WORDSIM(←ARG, ←V1), SWORDSIM(←ARGS, ←V2), UNION(←V1, ←V2, ←VS).
ISCONST(ZERO) :- !.
ISCONST(←O) :- MEASURE(←O, ←M), ISCONST(←M).
ISCONST(←V) :- ISNUM(←V), !.

```

```
ISCONST(+V) :- CONST(+V), !.  
ISCONST(+V) :- +V =.. +S, NIL , !, FAIL.  
ISCONST(+V) :- +V =.. +S, +ARGS , !, LISCONST(+ARGS ).  
LISCONST(NIL).  
LISCONST(+V,+VL) :- ISCONST(+V), !, LISCONST(+VL),  
ISSYM(+E) :- +E =.. +S, NIL .  
COMP(+E) :- +E =.. +S, NIL , !, FAIL.  
COMP(+E).  
ISNUM(+E) :- INTEGER(+E).
```

```
/* INFERENCE */  
GIVENS(+GL) :- FINDALL(GIVEN,+GL),  
GIVEN(G).  
SOUGHTS(+SL) :- FINDALL(SOUGHT,+SL).  
SUMDURS(NIL,[]).  
SUMDURS(+P,+PS,+T+<SUM) :- CC(DURATION(+P,+T)), !, SUMDURS(+PS,+SUM),  
SUMDIST(+OBJ,NIL,[]).  
SUMDIST(+OBJ,+P,+PL,+D+<SUM) :- CC(DISTANCE(+OBJ,+D,+P)),  
!, SUMDIST(+OBJ,+PL,+SUM),  
COSFACT(+DIR,+DIR,1) :- !,  
COSFACT(+DIR1,+DIR2,COS(+ANS)) :-  
INTEGER(+DIR1), INTEGER(+DIR2),  
+ANS IS +DIR1-+DIR2, !,  
COSFACT(+DIR1,+DIR2,COS(+DIR1-+DIR2)).  
SUMFORCES(+PART,+DIR1,+PER,+FORCESUM) :-  
FORCE(+PART,+FORCE,+DIR2,+PER),  
COSFACT(+DIR1,+DIR2,+COSTERM),  
FORCESUM(+SOFAR), DENY(FORCESUM(+SOFAR)),  
ASSERT(FORCESUM(+FORCE*+COSTERM)++SOFAR)), FAIL,  
SUMFORCES(+PART,+DIR1,+PER,+FORCESUM) :-  
FORCESUM(+FORCESUM), DENY(FORCESUM(+FORCESUM)),  
ASSERT(FORCESUM([])).
```

FORCESUM( $\emptyset$ ).  
INITVEL( $\leftarrow$ OBJ, $\leftarrow$ U, $\leftarrow$ DIR, $\leftarrow$ P) :-  
CC(INITIAL( $\leftarrow$ P, $\leftarrow$ BEGIN)), CC(VEL( $\leftarrow$ OBJ, $\leftarrow$ U, $\leftarrow$ DIR, $\leftarrow$ BEGIN)).

FINVEL( $\leftarrow$ OBJ, $\leftarrow$ V, $\leftarrow$ DIR, $\leftarrow$ P) :-  
CC(FINAL( $\leftarrow$ P, $\leftarrow$ END)), CC(VEL( $\leftarrow$ OBJ, $\leftarrow$ V, $\leftarrow$ DIR, $\leftarrow$ END)).

VECADD( $\leftarrow$ MAG1, $\leftarrow$ DIR, $\leftarrow$ MAG2, $\leftarrow$ DIR, $\leftarrow$ MAG1% $\leftarrow$ MAG2, $\leftarrow$ DIR).

ISQINVAR(ZERO) :- !.

ISQINVAR( $\leftarrow$ Q) :- MEASURE( $\leftarrow$ Q, $\leftarrow$ M), ISINVAR( $\leftarrow$ M), !.

ISINVAR( $\leftarrow$ V) :- INVAR( $\leftarrow$ V), !.

ISINVAR( $\leftarrow$ V) :- ISNUM( $\leftarrow$ V), !.

ISINVAR( $\leftarrow$ V) :- ISSYM( $\leftarrow$ V), !, FAIL.

ISINVAR( $\leftarrow$ V) :-  $\leftarrow$ V = .., $\leftarrow$ S, $\leftarrow$ ARGS , !, LISINVAR( $\leftarrow$ ARGS).

LISINVAR(NIL) :- !.

LISINVAR( $\leftarrow$ V, $\leftarrow$ VL) :- ISINVAR( $\leftarrow$ V), LISINVAR( $\leftarrow$ VL), !.

FIXDIR( $\leftarrow$ DIR) :- NONVAR( $\leftarrow$ DIR), !.

FIXDIR(270).

FIXDIR( $\emptyset$ ).

ACCEL( $\leftarrow$ X,ZERO, $\leftarrow$ DIR, $\leftarrow$ TIME) :- FIXEDCONTACT( $\leftarrow$ X,EARTH, $\leftarrow$ TIME),

ACCEL( $\leftarrow$ PART,ZERO, $\leftarrow$ DIR, $\leftarrow$ PER) :-  
VEL( $\leftarrow$ PART, $\leftarrow$ V, $\leftarrow$ DIR, $\leftarrow$ PER), ISQINVAR( $\leftarrow$ V), PERIOD( $\leftarrow$ PER), !,

ACCEL( $\leftarrow$ PART, $\leftarrow$ A, $\leftarrow$ DIR, $\leftarrow$ TIME) :- NLC(RELACCEL( $\leftarrow$ PART,EARTH, $\leftarrow$ A, $\leftarrow$ DIR, $\leftarrow$ TIME)).

RELACCEL( $\leftarrow$ PART,EARTH, $\leftarrow$ A, $\leftarrow$ DIR, $\leftarrow$ TIME) :- NLC(ACCEL( $\leftarrow$ PART, $\leftarrow$ A, $\leftarrow$ DIR, $\leftarrow$ TIME)).

/\*GRAVITATIONAL FORCE\*/

FORCE( $\leftarrow$ PART, $\leftarrow$ M\*G,270, $\leftarrow$ TIME) :-  
PARTICLE( $\leftarrow$ PART), CC(MASS( $\leftarrow$ PART, $\leftarrow$ M, $\leftarrow$ TIME)).

/\*TENSION IN STRING\*/

FORCE( $\leftarrow$ PART, $\leftarrow$ T, $\leftarrow$ DIR, $\leftarrow$ TIME) :-  
PARTICLE( $\leftarrow$ PART), FIXEDCONTACT( $\leftarrow$ PART, $\leftarrow$ STR, $\leftarrow$ TIME),  
STRING( $\leftarrow$ STR), CC(DIRECTION( $\leftarrow$ STR, $\leftarrow$ DIR, $\leftarrow$ TIME)),  
CC(TENSION( $\leftarrow$ STR, $\leftarrow$ T, $\leftarrow$ TIME)).

STRING(LEFT( $\leftarrow$ STR)) :- STRING( $\leftarrow$ STR).

STRING(RIGHT( $\leftarrow$ STR)) :- STRING( $\leftarrow$ STR).

INITIAL( $\leftarrow$ P, $\leftarrow$ M) :-

```
PERIOD(+P), PARTITION(+E,+P,+REST), INITIAL(+E,+M), !.

INITIAL(+P,+M) :-  
    PERIOD(+P), PARTITION(+E,+PL),  
    NEXTTO(+P1,+P,+PL), NLC(FINAL(+P1,+M)), !.

FINAL(+P,+M) :-  
    PERIOD(+P), PARTITION(+E,+PLIST), LAST(+P,+PLIST),  
    FINAL(+E,+M), !.

FINAL(+P,+M) :-  
    PERIOD(+P), PARTITION(+E,+PLIST), NEXTTO(+P,+P1,+PLIST),  
    NLC(INITIAL(+P1,+M)), !.

DROP(+PATH,+START,-(+D*TAN(+ANG))) :-  
    CONCAVITY(+PATH,STLINE),  
    INCLINE(+PATH,+ANG,+START), GROUND(+PATH,+D),  
    !.

DROP(+PATH,+START,+HSUM) :-  
    PARTITION(+PATH,+PL), SUMDROPS(+PL,+START,+HSUM),  
    !.

SUMDROPS(NIL,+START,0).  
SUMDROPS(+P,+PL,+START,+H+SUM) :-  
    DROP(+P,+START,+H), !, FAREND(+P,+START,+FINISH),  
    SUMDROPS(+PL,+FINISH,+SUM),  
    !.

FREE(+PATH,+PER,+O) :- PARTICLE(+O), PERIOD(+PER),  
    PATH(+PATH), PROBTYPE(ROLLER-COASTER),  
    !.

VEL(+PART,+VEL,+DIR,+MOM) :-  
    INITIAL(+PER,+MOM), VEL(+PART,+VEL,+DIR,+PER), ISQINVAR(+VEL), !.

VEL(+PART,+VEL,+DIR,+MOM) :-  
    FINAL(+PER,+MOM), VEL(+PART,+VEL,+DIR,+PER), ISQINVAR(+VEL), !.

TIME(+T) :- PERIOD(+T), !.

TIME(+T) :- MOMENT(+T), !.

MEASURE(ZERO,0) :- !.

MEASURE(G,32) :- !.

CCMEASURE(+Q,+M) :- ASSERTD(CCFLAG(ON)), CC(MEASURE(+Q,+M)), !.

UNIT(ZERO,+U) :- !.

UNIT(G,FT/SECS:2) :- !.

UNIT(+Q,+U) :-  
    STANDSYS(+SYS), QUANTITY(+Q,+D,+T), STANDUNIT(+D,+U,+SYS), !.

QUANTITY(+Q,1,S) :- ISA(+Q,COFRI), !.

QUANTITY(+Q,1,S) :- ISA(+Q,ANG), !.
```

```
QUANTITY(+Q,T,S) :- ISA(+Q,DURATION), !.  
QUANTITY(+Q,L,S) :- ISA(+Q,DISTANCE), !.  
QUANTITY(+Q,M,S) :- ISA(+Q,MASS), !.  
QUANTITY(+Q,M*(L/(T:2)),V) :- ISA(+Q,FORCE), !.  
QUANTITY(+Q,M*(L/(T:2)),S) :- ISA(+Q,TENSION), !.  
QUANTITY(+Q,M*(L/(T:2)),V) :- ISA(+Q,REACTION), !.  
QUANTITY(+Q,M*(L/T(T:2)),V) :- ISA(+Q,FRICITION), !.  
QUANTITY(+Q,L/T,V) :- ISA(+Q,VEL), !.  
QUANTITY(+Q,L/T:2,V) :- ISA(+Q,ACCEL), !.  
QUANTITY(+Q,L/T:2,V) :- ISA(+Q,RELACCEL), !.  
QUANTITY(+Q,L/T,V) :- ISA(+Q,RELVEL), !.  
QUANTITY(+Q,1,S) :- ISA(+Q,DIRECTION), !.
```

```
TYPE(+Q,+QTYPE) :- QUANTITY(+Q,+DIM,+VS), NAME(+QTYPE,+DIM).
```

```
NAME(MASS,M).  
NAME(DISTANCE,L).  
NAME(DURATION,T).  
NAME(VEL,L/T).  
NAME(ACCEL,L/(T:2)).  
NAME(FORCE,M*(L/(T:2))).
```

```
ISVECT(+Q) :- QUANTITY(+Q,+D,V).  
ISSCAL(+Q) :- QUANTITY(+Q,+D,S).
```

```
/*DECLARATIONS*/
```

```
DECLARE(+L) :- +L =.. +LS,+ARGS,  
DECLARECHECKS(+ARGS), !, +PROP =.. +LS.NIL,  
MESS(+PROP,+ARGS), ASSERT(+L),
```

```
DECLARECHECKS(+ARGS):-  
SEPERATE(+ARGS,+PARGS,+FARGS,+NUM),  
CHECKLIST(BOUND,+PARGS),
```

```
MESS(~PROP,[~Q]) :-  
    MAKE(~PROP,~Q),  
    TRACE(LET-~Q-BE-A-~PROP,2).  
  
MESS(~PROP,[~OBJ,~Q]) :-  
    MAKE(~PROP,~Q),  
    TRACE(LET-~Q-BE-THE-~PROP-OF-~OBJ,2),  
  
MESS(~PROP,[~OBJ,~Q,~TIME]) :-  
    MAKE(~PROP,~Q),  
    TRACE(LET-~Q-BE-THE-~PROP-OF-~OBJ-IN-~TIME,2),  
  
MESS(~PROP,[~OBJ,~Q,~DIR,~TIME]) :-  
    MAKE(~PROP,~Q), MAKE(DIRECTION,~DIR),  
    TRACE(LET-~Q-BE-THE-~PROP-OF-~OBJ,2),  
    TRACE(IN-DIRECTION-~DIR-AND-TIME-~TIME,2).  
  
MESS(~PROP,[~OBJ1,~OBJ2,~Q,~DIR,~TIME]) :-  
    MAKE(~PROP,~Q), MAKE(DIRECTION,~DIR),  
    TRACE(LET-~Q-BE-THE-~PROP-OF-~OBJ1-RELATIVE-TO-~OBJ2,2),  
    TRACE(IN-DIRECTION-~DIR-AND-TIME-~TIME,2).  
  
MAKE(~PROP,~Q) :- GENSYM(~PROP,~Q), !, ASSERT(isa(~Q,~PROP)).  
MAKE(~PROP,~Q).
```

XXXXX

%%%%MOTION . OLD @16:55 19-APR-1977 <055> (1754)

/\*MOTION INFERENCE RULES\*/  
/\*ALAN BUNDY 29/12/76\*/

/\*GENERAL QUESTION ANSWERING ROUTINE\*/  
QA(-QUAL,+QUAN) :-  
 -QUAL, FINDALL(PROVISO,+CONDLIST),  
 TRACE(-QUAL-OK-PROVIDED-+CONDLIST,2),  
 SOLVEALL(-CONDLIST,-SOLNS),  
 SUBST(-SOLNS,+CONDLIST,-NCONDLIST),  
 TRACE(NEW-CONDITIONS-ARE--NCONDLIST,2),  
 APPLY(-QUAN,+NCONDLIST,NIL).

/\*MAKING CONDITIONS\*/  
/\*SEE IF ITS TRUE\*/  
CONDITION(+L) :- +L,!.

/\*SEE IF ITS FALSE\*/  
CONDITION(+L) :- NOT(+L), !, FAIL.

/\*OTHERWISE NOTE IT FOR LATER\*/  
CONDITION(+L) :- POSTULATE(PROVISO(+L)),  
 TRACE(STORING-PROVISO-+L,6).

/\*NEGATION\*/  
NOT(X>Y) :- Y>=X.  
NOT(X>=Y) :- Y>X.

/\*MOTION CHECK\*/  
MOTION(-PART,+PATH,-START,-SIDE,+PER) :-  
 INPLACE(-PART,+PATH,-START,-SIDE,+BEGIN),  
 CUE(TIMESYS(-PER,-BEGIN,+END)),  
 TRACE(CHECKING-MOTION-OF--PART-ON--PATH-FROM--START,7),  
 TRACE(ON--SIDE-DURING--PER,7),  
 MOTION1(-PART,+PATH,-START,-SIDE,-PER),  
 CUE(MOTSYS(-PART,-PATH,-START,-SIDE,-PER)),

/\*GENERAL MOTION ON PATH\*/ /\*LETS THROUGH TOO MANY POSSIBILITIES\*/  
MOTION1(-PART,+PATH,-START,-SIDE,-PER) :-  
 INITIAL(-PER,-BEGIN),  
 GETSTARTED(-PART,+PATH,-START,-SIDE,-BEGIN),  
 NOSTOPPING(-PART,+PATH,-START,-SIDE,-PER),  
 NOTAKEOFF(-PART,+PATH,-START,-SIDE,-PER),  
 NOFALLOFF(-PART,+PATH,-START,-SIDE,-PER).

/\*BREAK INTO SUBPATHS\*/

```
MOTION1(+PART,+PATH,+START,+SIDE,+PER) :-  
    ARRANGE PATH(+PATH,+START,+NPATHLIST),  
    MAKEPERIODS(+NPATHLIST,+PER,+PERLIST),  
    MULTIMOTION(+PART,+NPATHLIST,+START,+SIDE,+PERLIST).  
  
ARRANGE PATH(+PATH,+START,+NPATHLIST) :-  
    PARTITION(+PATH,+PATHLIST),  
    END(+PATH,+START,+END),  
    CONDREV(+END,+PATHLIST,+NPATHLIST),  
  
MAKEPERIODS(+NPATHLIST,+PER,+PERLIST) :-  
    MAPLIST(MAKEONE,+NPATHLIST,+PERLIST),  
    ASSERT(PARTITION(+PER,+PERLIST)),  
    TRACE(LET-+PER-BE-DIVIDED-INTO-+PERLIST,2).  
  
/*DEAL WITH EACH SUBPATH*/  
MULTIMOTION(+PART,NIL,+START,+SIDE,NIL).  
  
MULTIMOTION(+PART,+PATH,+PATHL,+START,+SIDE,+PER,+PERL) :-  
    MOTION(+PART,+PATH,+START,+SIDE,+PER),  
    FAREND(+PATH,+START,+FINISH),  
    MULTIMOTION(+PART,+PATHL,+FINISH,+SIDE,+PERL).  
  
/*MAKE ONE PERIOD*/  
MAKEONE(+PATH,+PER) :- DECLARE(PERIOD(+PER)),  
  
GETSTARTED(+PART,+PATH,+START,+SIDE,+BEGIN) :-  
    VEL(+PART,ZERO,+DIR,+BEGIN), !,  
    COND(INCLINE(+PATH,ZERO,+START),  
        NUDGE(+PART,ZERO,+BEGIN),TOP(+PATH,+START)).  
  
/*HEADED IN RIGHT DIRECTION*/  
GETSTARTED(+PART,+PATH,+START,+SIDE,+BEGIN) :-  
    INCLINE(+PATH,+ANG,+START),  
    VEL(+PART,+V,+ANG,+BEGIN),  
    CONDITION(+V>ZERO).  
  
/*DOWNHILL RUN*/  
NOSTOPPING(+PART,+PATH,+START,+SIDE,+PER) :-  
    END(+PATH,+START,+END), OPPOSITE(+END,+OEND),  
    SLOPE(+PATH,+HEND), DIFF(+OEND,+HEND), !.  
  
/*MAKES IT TO THE TOP*/  
NOSTOPPING(+PART,+PATH,+START,+SIDE,+PER) :-  
    FINVEL(+PART,+V,+DIR,+PER), CONDITION(REAL(+V)).  
  
/*BELOW PATH*/  
NOTAKEOFF(+PART,+PATH,+START,+SIDE,+PER) :-  
    BELOW(+PATH,+START,+SIDE), !.  
  
/*SLOPE DOES NOT DROP AWAY*/  
NOTAKEOFF(+PART,+PATH,+START,+SIDE,+PER) :-  
    CONCAVITY(+PATH,+CONC), DIFF(+CONC,RIGHT), !.  
  
/*INSUFFICIENT VEL TO TAKE OFF*/  
NOTAKEOFF(+PART,+PATH,+START,+SIDE,+PER) :-  
    CONCAVITY(+PATH,RIGHT),  
    NORMAL(+PATH,+DIR),  
    CC(REACTION(+PATH,+PART,+N,+DIR,+PER)),
```

CONDITION( $\neg N \neq 0$ ) .

/\* SUPPORTED \*/  
NOFALLOFF( $\neg PART, \neg PATH, \neg START, \neg SIDE, \neg PER$ ) :-  
ABOVE( $\neg PATH, \neg START, \neg SIDE$ ), !.

/\* VERTICAL FALL \*/  
NOFALLOFF( $\neg PART, \neg PATH, \neg START, \neg SIDE, \neg PER$ ) :-  
SLOPE( $\neg PATH, \neg START$ ), CONCAVITY( $\neg PATH, STLINE$ ),  
INCLINE( $\neg PATH, 270, \neg START$ ), !.

/\* STICKS ON \*/  
NOFALLOFF( $\neg PART, \neg PATH, \neg START, \neg SIDE, \neg PER$ ) :-  
CONCAVITY( $\neg PATH, RIGHT$ ),  
NORMAL( $\neg PATH, \neg DIR1$ ),  
CC(VEL( $\neg PART, \neg V, \neg DIR2, \neg PER$ )),  
RADIUS( $\neg PATH, CURVATURE, \neg R$ ),  
CONDITION( $(\neg V:2) * SIN(\neg DIR1) \geq \neg R * G$ ), !.

/\* FREEFALL \*/  
NOFALLOFF( $\neg PART, \neg PATH, \neg START, \neg SIDE, \neg PER$ ) :-  
CONCAVITY( $\neg PATH, \neg CONC$ ), DIFF( $\neg CONC, RIGHT$ ),  
ASSERT(FALLSFALL( $\neg PART, \neg PATH, \neg START, \neg SIDE, \neg PER$ )),  
!, FAIL.

/\* DESCRIBING PATHS \*/

/\* PATH WITH MONOTONIC SLOPE \*/  
MONOPATH( $\neg PATH$ ) :- SLOPE( $\neg PATH, LEFT$ ),  
MONOPATH( $\neg PATH$ ) :- SLOPE( $\neg PATH, RIGHT$ ),  
MONOPATH( $\neg PATH$ ) :- SLOPE( $\neg PATH, HOR$ ).

/\* POINT1 AND POINT2 ARE OPPOSITE ENDS OF PATH \*/  
FAREND( $\neg PATH, \neg POINT1, \neg POINT2$ ) :-  
END( $\neg PATH, \neg POINT1, \neg END1$ ), OPPOSITE( $\neg END1, \neg END2$ ),  
END( $\neg PATH, \neg POINT2, \neg END2$ ).

/\* UPPER SIDE OF PATH \*/  
ABOVE( $\neg PATH, \neg START, \neg SIDE$ ) :-  
MONOPATH( $\neg PATH$ ), END( $\neg PATH, \neg START, \neg SIDE$ ).

/\* LOWER SIDE OF PATH \*/  
BELOW( $\neg PATH, \neg START, \neg SIDE1$ ) :-  
MONOPATH( $\neg PATH$ ),  
END( $\neg PATH, \neg START, \neg SIDE2$ ), OPPOSITE( $\neg SIDE1, \neg SIDE2$ ).

/\* START IS THE TOP OF PATH \*/  
TOP( $\neg PATH, \neg START$ ) :- END( $\neg PATH, \neg START, \neg END$ ), SLOPE( $\neg PATH, \neg END$ ).

/\* PARTICLE IS IN PLACE AT START OF PATH \*/  
INPLACE( $\neg PART, \neg PATH1, \neg FINISH, \neg SIDE, \neg END$ ) :-  
DBC(MOTION( $\neg PART, \neg PATH2, \neg START, \neg SIDE, \neg PER$ )),  
FAREND( $\neg PATH2, \neg START, \neg FINISH$ ),  
FINAL( $\neg PER, \neg END$ ), !.

INPLACE( $\neg PART, \neg PATH, \neg START, \neg SIDE2, \neg TIME$ ) :-  
DBC(AT( $\neg PART, \neg START, \neg TIME$ )),  
SIDE( $\neg PART, \neg START, \neg SIDE1, \neg TIME$ ),  
END( $\neg PATH, \neg START, \neg END$ ),

```

CONDVAL(←END, ←SIDE1, ←SIDE2).

/* CONSECUTIVE PATHS HAVE THE SAME INCLINATION
(ADD SMOOTHNESS CONDITION) */
INCLINE(←PH2, ←ANG, ←PT) :-  

    PARTITION(←PH0, ←PHL),  

    NEXTTO(←PH1, ←PH2, ←PHL),  

    NLC(INCLINE(←PH1, ←ANG, ←PT)).

/* YOU CAN'T BE IN TWO PLACES AT ONCE */
AT(←M, ←P1, ←T) :-  

    CHECKLIST(BOUND, [←M, ←P1, ←T]), DBC(AT(←M, ←P2, ←T)),  

    DIFF(←P1, ←P2), !, FAIL.

/* YOU GET TO YOUR DESTINATION BY TRAVELING THERE */
AT(←PART, ←PLACE2, ←MOM2) :-  

    FARENDE(←PATH, ←PLACE2, ←PLACE1),  

    INPLACE(←PART, ←PATH, ←PLACE1, ←SIDE, ←MOM1),  

    CUE(TIMESYS(←PER, ←MOM1, ←MOM2)),  

    NLC(MOTION(←PART, ←PATH, ←PLACE1, ←SIDE, ←PER)).

/* CONDITIONAL REVERSE */
CONDREV(LEFT, ←LIST, ←LIST),
CONDREV(RIGHT, ←LIST, ←RLIST) :- REV(←LIST, ←RLIST).

/* CONDITIONAL VALUE */
CONDVAL(LEFT, ←SIDE, ←SIDE),
CONDVAL(RIGHT, ←SIDE1, ←SIDE2) :- OPPOSITE(←SIDE1, ←SIDE2).

/* PARITY CHANGER */
OPPOSITE(LEFT, RIGHT),
OPPOSITE(RIGHT, LEFT).

/* CALL MARPLES TO UNPACK PROVISOS */
SOLVEALL(←CONDLIST, ←ANS) :-  

    SETUP(←CONDLIST, ←ES, ←XS1), CRUNCH(←ES, ←XS1, ←ANS).

SETUP(←CONDLIST, ←ES, ←XS1) :- SWORDSIN(←CONDLIST, ←VARS),
    GIVENS(←GS), SUBTRACT(←VARS, ←GS, ←XS),
    TRACE(ATTEMPTING-TO-SOLVE-FOR-←XS-IN-TERMS-OF--GS, 5),
    GETEQNS(←XS, ←GS, NIL, ←ES, ←XS1),
    TRACE(EQUATIONS-EXTRACTED, 2), PPR(←ES).

CRUNCH(←ES, ←XS1, ←ANS) :-  

    CONVERT(←ES, ←ES1), TRACE(CONVERTED-TO, 2), PPR(←ES1),
    SIMPLIFY(←ES1, ←ES2), TRACE(SIMPLIFIED-TO, 2), PPR(←ES2),
    MAPLIST(COMEASURE, ←XS1, ←XS2), TRACE(UNKNOWNNS-ARE-←XS2, 2),
    SIMSOLVE(←ES2, ←XS2, ←ANS), TRACE(ANSWER-IS, 2), PPR(←ANS).

/* APOLOGIES FOR ABSENCE */
CRUNCH(←ES, ←XS1, ←ES) :- TRACE(CRUNCH-NOT-LOADED, 2).

SUBST(←SOLNS, ←CL, ←CL) :- TRACE(SUBST-NOT-LOADED, 2).

```

```
EVAL(+COND) :- TRACE(EVAL-NOT-LOADED,2).  
MIN(+Q,+MV,-COND) :- TRACE(MIN-NOT-LOADED,2).  
  
/*DETAILED INFERENCES FOR PROVISOS*/  
  
/*RADIUS OF CURVATURE OF CIRCLE SEGMENT*/  
RADIUS_OF_CURVATURE(+PATH,+R) :-  
    PARTOF(+PATH,+CIRCLE), CIRCLE(+CIRCLE),  
    CC(RADIUS(+CIRCLE,+R)),  
  
/*PART-WHOLE RELATIONSHIP*/  
PARTOF(+WHOLE,+WHOLE).  
PARTOF(+PART,+WHOLE) :- BITOF(+PART,+WHOLE).  
  
BITOF(+PART,+WHOLE) :- PARTITION(+WHOLE,+PARTS),  
    MEMBER(+PART,+PARTS).  
  
/*VERTICAL DROP OF CIRCLE SEGMENT*/  
DROP(+PATH,+START,+R*(SIN(+DIR1)-SIN(+DIR2))) :-  
    PARTOF(+PATH,+CIRCLE), CIRCLE(+CIRCLE),  
    FAREND(+PATH,+START,+FINISH),  
    ANGLE(+START,+DIR1,+CIRCLE), ANGLE(+FINISH,+DIR2,+CIRCLE),  
    RADIUS(+CIRCLE,+R),  
  
/*TYPICAL DROP WITHIN CIRCLE SEGMENT*/  
TYPICAL_DROP(+PATH,+START,+R*(SIN(+DIR1)-SIN(+DIR2))) :-  
    PARTOF(+PATH,+CIRCLE), CIRCLE(+CIRCLE),  
    CC(ANGLE(+START,+DIR1,+CIRCLE)),  
    NORMAL(+PATH,+DIR2),  
    RADIUS(+CIRCLE,+R).  
  
/*NORMAL TO PATH*/  
  
/*ALWAYS USE NORMAL OF LARGEST PATH*/  
NORMAL(+PATH,+DIR) :-  
    BITOF(+PATH,+SUPERPATH), NORMAL(+SUPERPATH,+DIR).  
  
/*NORMAL IS ANGLE AT TYPICAL POINT*/  
NORMAL(+PATH,+DIR) :-  
    CC(TYPICAL_POINT(+PATH,+X)),  
    CC(ANGLE(+X,+DIR,+PATH)).  
  
/*AN OBJECT IS IN CONTACT WITH THE PATH IT MOVES ON*/  
CONTACT(+PART,+PATH,+PER) :-  
    DBC(MOTION(+PART,+PATH,+START,+SIDE,+PER)),  
  
/*PATHS ARE FIXED IN THE ROLLER-COASTER WORLD*/  
FIXED_CONTACT(+PATH,EARTH,+PER) :-  
    PATH(+PATH), PERIOD(+PER),  
    PROB_TYPE(ROLLER-COASTER).  
  
/*PATHS ARE SMOOTH IN THE ROLLER-COASTER WORLD*/  
COEFF(+PATH,ZERO) :-  
    PATH(+PATH), PROBTYPE(ROLLER-COASTER).
```

```
/*THE MASS OF A PARTICLE IS CONSTANT*/
MASS( $\leftarrow$ PART, $\leftarrow$ M, $\leftarrow$ PER1) :-  
    PARTICLE( $\leftarrow$ PART), PERIOD( $\leftarrow$ PER2),  
    DIFF( $\leftarrow$ PER1, $\leftarrow$ PER2), NLC(MASS( $\leftarrow$ PART, $\leftarrow$ M, $\leftarrow$ PER2)).  
  
/*ACCEL TOWARDS THE CENTRE OF A CURVE*/
ACCEL( $\leftarrow$ PART, $\leftarrow$ ( $\leftarrow$ V:2), $\leftarrow$ R, $\leftarrow$ DIR2, $\leftarrow$ TIME) :-  
    DBC(MOTION( $\leftarrow$ PART, $\leftarrow$ PATH, $\leftarrow$ START, $\leftarrow$ SIDE, $\leftarrow$ TIME)),  
    CC(VEL( $\leftarrow$ PART, $\leftarrow$ V, $\leftarrow$ DIR1, $\leftarrow$ TIME)),  
    RADIUS_OF_CURVATURE( $\leftarrow$ PATH, $\leftarrow$ R),  
    CC(NORMAL( $\leftarrow$ PATH, $\leftarrow$ DIR2)).  
  
/*REACTION*/
FORCE( $\leftarrow$ PART, $\leftarrow$ N, $\leftarrow$ DIR, $\leftarrow$ TIME) :-  
    CONTACT( $\leftarrow$ PART, $\leftarrow$ OBJ, $\leftarrow$ TIME),  
    CC(REACTION( $\leftarrow$ OBJ, $\leftarrow$ PART, $\leftarrow$ N, $\leftarrow$ DIR, $\leftarrow$ TIME)).  
  
/*FRICTION*/
FORCE( $\leftarrow$ PART, $\leftarrow$ F, $\leftarrow$ DIR, $\leftarrow$ TIME) :-  
    CONTACT( $\leftarrow$ PART, $\leftarrow$ OBJ, $\leftarrow$ TIME),  
    THNOT(COEFF( $\leftarrow$ OBJ,ZERO)),  
    CC(FRICTION( $\leftarrow$ OBJ, $\leftarrow$ PART, $\leftarrow$ F, $\leftarrow$ DIR, $\leftarrow$ TIME)).
```

\\\\\\

\*\*\*\*\*SCHEMA . OLD @16:56 19-APR-1977 <055> (170)

```
/*SCHEMATA (AND CUES)*/  
/*ALAN BUNDY 28/2/77 */  
  
/*CUE IN SCHEMA*/  
CUE(~KEY) :- SCHEMA(~KEY,~DECL,~ASS,~DEF),  
    TRACE(PUL_ING_IN_SCHEMA--~KEY,6),NEWLINE,  
    TRACE(DECLARATIONS,7),CHECKLIST(CALL,~DECL),NEWLINE,  
    TRACE(ASSERTIONS,7), CHECKLIST(PASSERT,~ASS),NEWLINE,  
    TRACE(DEFAULTS,7), CHECKLIST(PASSERTC,~DEF),NEWLINE, !,  
  
SCHEMA(TIMESYS(~PER,~MOM1,~MOM2),  
    [DECLARE(PERIOD(~PER)),CC(INITIAL(~PER,~MOM1)),  
     CC(FINAL(~PER,~MOM2))],  
    [MOMENT(~MOM1), MOMENT(~MOM2)],  
    [] ).  
  
SCHEMA(MOTSYS(~PART,~PATH,~START,~SIDE1,~PER),  
    [CC(FAREND(~PATH,~FINISH,~START)), CC(FINAL(~PER,~END)),  
     CC(INCLINE(~PATH,~ANG,~FINISH)), CC(VEL(~PART,~V,~ANG,~END))],  
    [DBC(MOTION(~PART,~PATH,~START,~SIDE1,~PER)),  
     DBC(AT(~PART,~FINISH,~END)) ],  
    [(+V>ZERO :- TOP(~PATH,~START), PROBTYPE(ROLLER-COASTER))] ).  
  
CALL(~L) :- ~L.  
  
\\\\\\\\
```

%%%%%FUNCC , OLD @16:56 19-APR-1977 <055> (180)

```
/*FUNC*/
/*FUNCTION CALL PREDICATE CALL*/
/*ALAN BUNDY FEB 1977*/

/*DECIDE TYPE OF CALL*/
FPC(+L) :- TRACE(CALLING+L,7),FAIL.
FPC(+L) :- CHECKARGS(+L), !, FC(+L).
FPC(+L) :- +L.

/*FUNCTION CALL*/
FC(+L) :- SILLY(+L), !, FAIL,
FC(+L) :- +L, !.

/*PREDICATE ARGS ALL BOUND*/
CHECKARGS(+L) :- +L=.., +PROP,+ARGS, SEPERATE(+ARGS,+PARGS,+FARGS,+NUM),
                CHECKLIST(BOUND,+PARGS).

/*IS CALL SILLY?*/
SILLY(+L) :- +L=.., +PROP,+ARGS, SEPERATE(+ARGS,+PARGS,+FARGS,+NUM),
            CHECKLIST(BOUND,+FARGS), SEPERATE(+NARGS,+PARGS,+NFARGS,+NUM),
            +NL = .., +PROP,+NARGS, DBC(+NL), DIFF(+FARGS,+NARGS).

/*SEPERATE FUNCTION AND PREDICATE ARGS*/
SEPERATE([+Q],[],[+Q],1),
SEPERATE([+OBJ,+Q],[+OBJ],[+Q],2),
SEPERATE([+OBJ,+Q,+TIME],[+OBJ,+TIME],[+Q],3),
SEPERATE([+OBJ,+Q,+DIR,+TIME],[+OBJ,+TIME],[+Q,+DIR],4),
SEPERATE([+OBJ1,+OBJ2,+Q,+DIR,+TIME],[+OBJ1,+OBJ2,+TIME],[+Q,+DIR],5),
```

XXXXX

%%%%%CONVERT . OLD @10:34 20-APR-1977 <055> (818)

/\*CONVERT\*/  
/\*MECHANICS UNIT CONVERSION ROUTINES\*/  
/\*GATHERED TOGETHER BY ALAN BUNDY ON 8/9/76\*/

/\*UNIT CONVERSION\*/

CONVERT(+ES,+ES1) :- STANDSYS(+SYS),  
 ASSERTD(CCFLAG(ON)), ECONV(+ES,+ES1).  
  
SCONV(NIL,NIL).  
  
SCONV(+E,+ES,+E1,+ES1) :- ECONV(+E,+E1), SCONV(+ES,+ES1).  
  
ECONV(TRUE,TRUE) :- !.  
  
ECONV(+E,+E) :- ISCONST(+E), !.  
  
ECONV(+E,+E) :- WORD(+E), QUANTITY(+E,1,ND).  
  
ECONV(+E,+E1) :- WORD(+E), !, VCONV(+E,+E1),  
  
ECONV(+E,+E1) :- +E =.. +S.+ARGS , SCONV(+ARGS,+ARGS1),  
 +E1 =.. +S.+ARGS1 .  
  
VCONV(+E,+E1) :- VCONV1(+E,+E1),!.  
  
VCONV(+E,+E1) :- VCONV2(+E,+E1),!,  
 CASSERTC(VCONV1(+E,+E1)), TRACE(+E-GOES-TO+ +E1,4),  
  
VCONV2(+V,+M) :- UNIT(+V,+U) , STANDARD(+U,+U),  
 !, CC(MEASURE(+V,+M)).  
  
VCONV2(+V,+M2) :- UNIT(+V,+U)  
, STANDARD(+U,+U1) , CC(MEASURE(+V,+M)),  
 MCNV(+M,+U,+M1,+U1), SIMPLIFY(+M1,+M2).  
  
STANDARD(+U,+U1) :- STANDSYS(+SYS), DIMENSIONS(+U,+D),  
 STANDUNIT(+D,+U1,+SYS).  
  
DIMENSIONS(LBS,M) :- !.  
DIMENSIONS(TONS,M) :- !.  
  
DIMENSIONS(HRS,T) :- !.  
DIMENSIONS(MINS,T) :- !.

```
DIMENSIONS(SECs,T) :- !.
DIMENSIONS(MLS,L) :- !.
DIMENSIONS(YDS,L) :- !,
DIMENSIONS(FT,L) :- !,
DIMENSIONS(INS,L) :- !,
DIMENSIONS(~U,~U) :- ISCONST(~U), !.
DIMENSIONS(~U,~D) :- ~U =,,~S,~ARGS ,
LDIMENSIONS(~ARGS,~DARGS), ~D =,,~S,~DARGS .

LDIMENSIONS(NIL,NIL).
LDIMENSIONS(~U,~UL,~D,~DL) :- DIMENSIONS(~U,~D) ,
LDIMENSIONS(~UL,~DL).

MCONV(~M,~U,+C,+M,+U1) :- FACTOR(+C,+U1,+U).

INA(2240,LBS,TONS).
INA(60,MINS,HRS),
INA(60,SECS,MINS),
INA(1760,YDS,MLS),
INA(3,FT,YDS),
INA(12,INS,FT).

FACTOR(1,~U,~U) :- ISUNIT(~U), !,
FACTOR(~U,~U,~U) :- ISCONST(~U), !. /*FOR SQUARES ETC*/
FACTOR(~C,+U1,~U) :- INA(~C,+U1,~U), !,
FACTOR(~C,+U1,~U) :- COMP(~U1),
~U1 =,,~,~ARGS1 , ~U =,,~,~S,~ARGS ,
SFACTOR(~CS,~ARGS1,~ARGS), ~C =,,~,~S,~CS , !.

FACTOR(1/~C,+U1,~U) :- BEFORE(~U,+U1), FACTOR(~C,+U,+U1), !.

FACTOR(~C1,~C2,+U2,~U) :- INA(~C1,+U1,~U),
FACTOR(~C2,+U2,+U1), !.

SFACTOR(NIL,NIL,NIL) :- !.
SFACTOR(~C,~CS,~U1,~US1,~U,~US) :- FACTOR(~C,+U1,+U),
SFACTOR(~CS,~US1,~US),
BEFORE(~U,+U1) :- DIMENSIONS(~U,+D), POSN(+D,+U,+P),
POSN(+D,+U1,+P1), ~P<~P1, !.

POSN(M,LBS,1),
```

```
POSN(H,TONS,2).  
POSN(T,SECS,1).  
POSN(T,MINS,2).  
POSN(T,HRS,3).  
POSN(L,INS,1).  
POSN(L,FT,2).  
POSN(L,YDS,3).  
POSN(L,MLS,4).  
ISUNIT(+U) :- POSN(+D,+U,+N),
```

#### /\*FIXING UNIT SYSTEM\*/

```
STANDSYS(+SYS) :-  
    NOLOOP, SOUGHTS(+SL), CONVLIST(UNIT,+SL,+UL1),  
    SWORDSDIN(+UL1,+PUL1), FIX(T,L,M,NIL,+PUL1,+REM1,+SYS),  
    GIVENS(+GL), CONVLIST(UNIT,+GL,+UL2),  
    SWORDSDIN(+UL2,+PUL2), FIX(+REM1,+UL2,+REM2,+SYS),  
    FIXREST(+REM2,+SYS), DECLARE(STANDSYS(+SYS)),  
    SYSFOUND.
```

```
NOLOOP :- SYSSOUGHT, !, FAIL.  
NOLOOP :- ASSERT(SYSSOUGHT).
```

```
SYSFOUND :- DENY(SYSSOUGHT).
```

```
FIX(NIL,+UL,NIL,+SYS) .
```

```
FIX(+D1,+DL1,+UL,+DL2,+SYS) :-  
    SUBLIST(DIMENSIONS(+D1),+UL,+CANDL), DIFF(+CANDL,NIL),  
    !, VOTE(+CANDL,+WIN),  
    GENSYM(SYS,+SYS), DECLARE(STANDUNIT(+D1,+WIN,+SYS)),  
    FIX(+DL1,+UL,+DL2,+SYS).
```

```
FIX(+D1,+DL1,+UL,+D1,+DL2,+SYS) :-  
    FIX(+DL1,+UL,+DL2,+SYS).
```

```
VOTE(+CANDL,+WIN) :-  
    LISTTOSET(+CANDL,+CANDS),  
    MAPLIST(SCOREEACH(+CANDL),+CANDS,+PAIRSL),  
    FAVOURITE(+PAIRSL,+WIN,+SCORE).
```

```
SCOREEACH(+U,+U,0,NIL).  
SCOREEACH(+U,+U,+N1,+U,+REST) :-  
    !, SCOREEACH(+U,+U,+N,+REST), +(+N,1,+N1).  
SCOREEACH(+U,+U,+N,+HD,+TL) :- SCOREEACH(+U,+U,+N,+TL).
```

```
FAVOURITE((+U,+S),NIL,+U,+S) :- !.  
FAVOURITE((+U1,+S1),+PL,+U2,+S2) :-  
    FAVOURITE(+PL,+U2,+S2), +S1<+S2 , !,  
FAVOURITE((+U,+S),+PL,+U,+S),  
  
FIXREST(NIL,+SYS).  
  
FIXREST(T,L,M,NIL,+SYS) :- !, DEFAULT(+SYS).  
  
FIXREST(T,D,L,+DL,+SYS) :-  
    DEFAULT(+SYS2) , STANDUNIT(+D,+U,+SYS2),  
    DECLARE(STANDUNIT(+D,+U,+SYS)), FIXREST(+DL,+SYS).  
  
DEFAULT(FLS).  
  
STANDUNIT(T,SECS,FLS) :- !.  
STANDUNIT(L,FT,FLS) :- !,  
STANDUNIT(M,LBS,FLS) :- !.  
  
STANDUNIT(+U,+U,+SYS) :- ISCONST(+U) , !.  
  
STANDUNIT(+D,+U,+SYS) :- ISSYM(+D), !, FAIL.  
  
STANDUNIT(+D,+U,+SYS) :- +D=..,(+S,+DARGS) ,  
    MAPLIST(STANDUNIT(+SYS),+DARGS,+UARGS), +U=..(+S.+UARGS) .
```

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%%%I I

@11:44 7-JAN-1977 <057> (4)

: - I I.

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%%%%%OLDXRT .

@13:39 2-MAR-1977 <055> (287)

/\* FRAMES AND GO, OLD BITS OF XTRACT \*/

/\* FRAMES \*/

FRAME1(PULLSYS(+SYS,+PULL,+STR,+P1,+P2,+TIME),  
[ PROBTYPE(PULLEY),  
CONTACT(+P1,LEFT(+STR),+TIME),  
CONTACT(+P2,RIGHT(+STR),+TIME),  
(DIRECTION(LEFT(+STR),90,+TIME) :- !),  
(DIRECTION(RIGHT(+STR),90,+TIME) :- !),  
STRING(+STR),  
PARTICLE(+PULL) ]).

FRAME2(PULLSYS(+SYS,+PULL,+STR,+P1,+P2,+TIME),  
[(TENSION(LEFT(+STR),+T,+TIME) :- TENSION(+STR,-T,-TIME),  
COEFF(+PULL,ZERO),ELASTIC(+STR,ZERO)),  
(TENSION(RIGHT(+STR),+T,+TIME) :- TENSION(+STR,-T,-TIME),  
COEFF(+PULL,ZERO),ELASTIC(+STR,ZERO))]).

FRAME3(PULLSYS(+SYS,+PULL,+STR,+P1,+P2,+TIME),  
[FIXED+CONTACT(+PULL,EARTH,+TIME),  
COEFF(+PULL,ZERO),  
ELASTIC(+STR,ZERO),  
MASS(+PULL,ZERO,+TIME),  
MASS(+STR,ZERO,+TIME) ]).

FRAME(+CUE,+L,+DEFAULTS) :-  
FRAME1(+CUE,+L1), FRAME2(+CUE,+L2), APPEND(+L1,+L2,+L),  
FRAME3(+CUE,+DEFAULTS).

/\* MARPLES ALGORITHM \*/

GO :- SOUGHTS(+XS), GIVENS(+GS),  
TRACE(ATTEMPTING-TO-SOLVE-FOR-+XS-IN-TERMS-OF--GS,5),  
GETEONS(+XS,+GS,NIL,+ES,+XS1),  
TRACE(EQUATIONS-EXTRACTED,2), PPR(+ES) ,  
CONVERT(+ES,+ES1), TRACE(CONVERTED-TO,2), PPR(+ES1),  
SIMPLIFY(+ES1,+ES2), TRACE(SIMPLIFIED-TO,2), PPR(+ES2) ,  
MAPLIST(CCMEASURE,+XS1,+XS2), TRACE(UNKNOWN-ARE--XS2,2),  
SIMSOLVE(+ES2,+XS2,+ANS), TRACE(ANSWER-IS,2), PPR(+ANS). |||

|||||