

Parallel

Logic

Programming

Languages

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Contents

- Introduction and history
- PARLOG: the language
- Other parallel logic programming languages
- Applications
- Case study: PPS
- PARLOG implementations
- Some recent developments
- Conclusions

Parallel Logic Languages

Horn clause logic:

$$H \leftarrow B_1, B_2, \dots, B_n.$$

Declarative interpretation:

H is true if all B_i are true.

Procedural interpretation:

to prove H , prove all B_i

Process interpretation:

H reduces to a network of concurrent processes B_i .

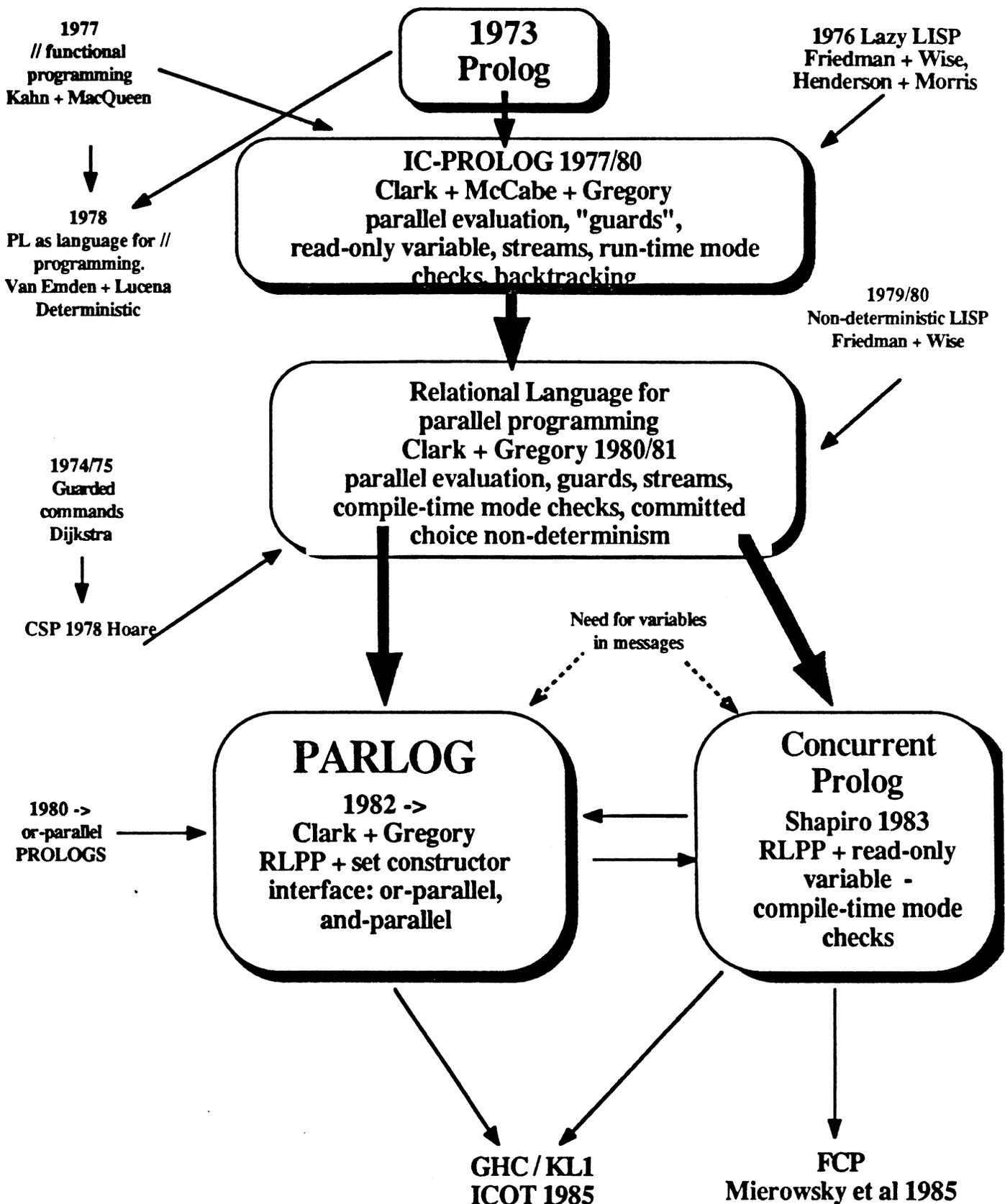
Parallel logic languages =

Horn clause logic + AND-parallelism
communication
synchronization
committed-choice non-determinism

They are interesting because they are:

logic programming languages
parallel languages
expressive

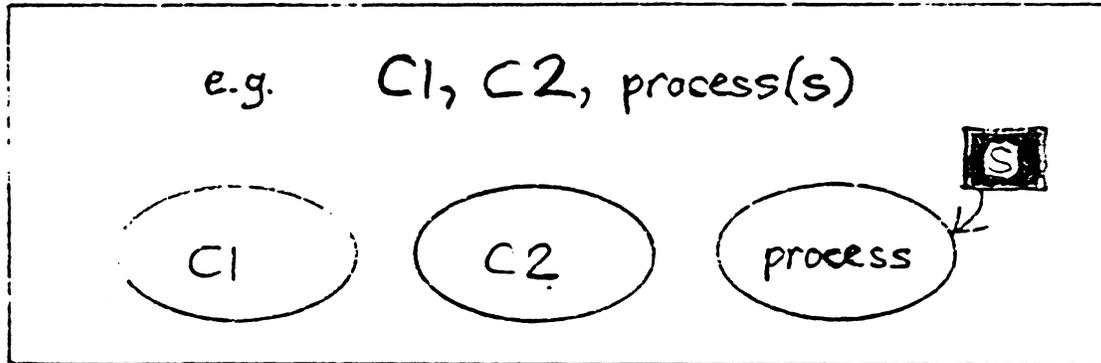
Parallel Logic Programming A Partial History



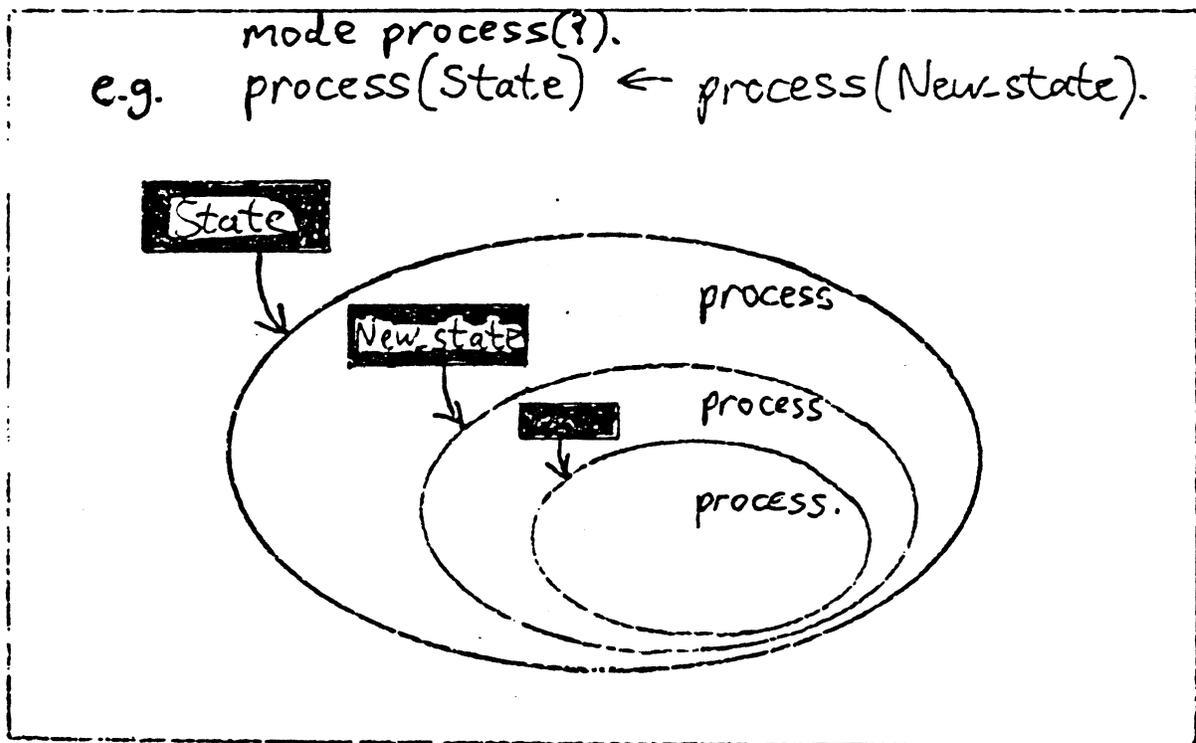
AND-PARALLELISM

Relation call = Process

Conjunction = Process network

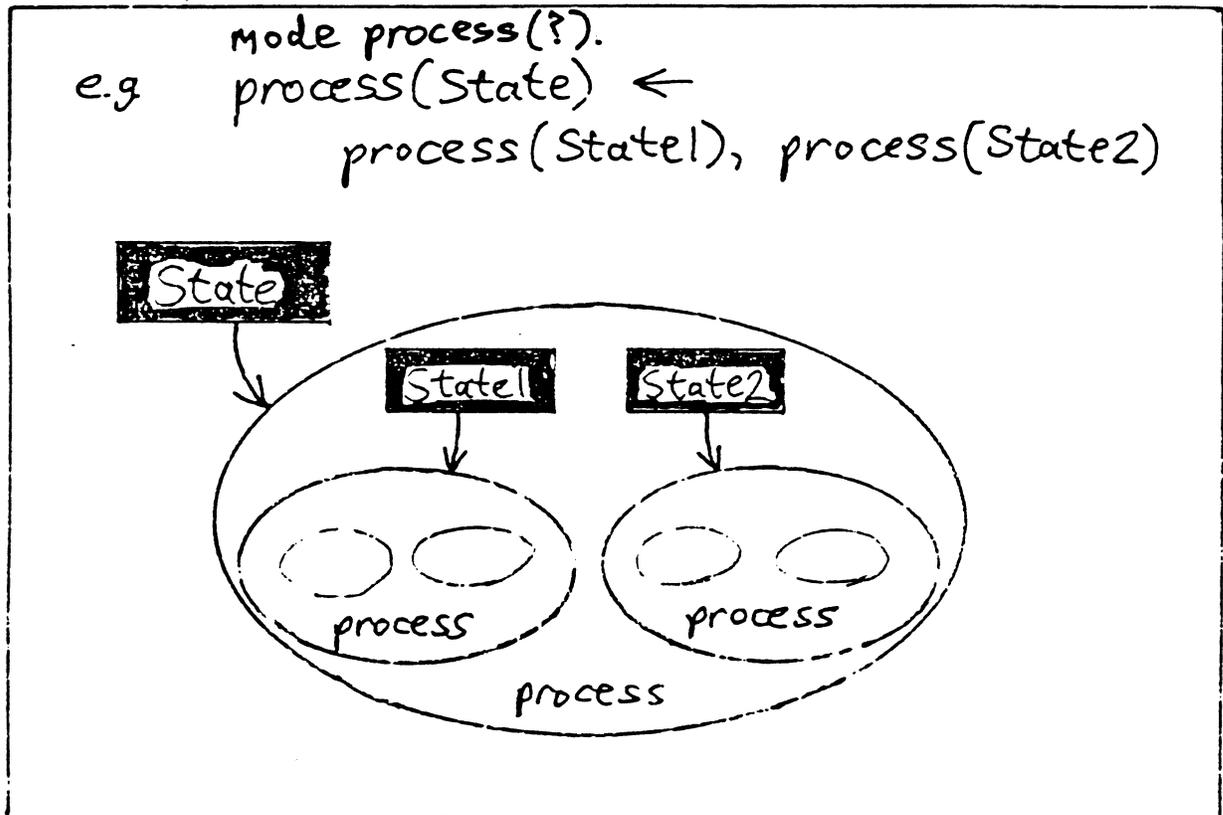


Clause with one call in body =
Change of process state



AND-PARALLELISM

Clause with > 1 calls in body =
Creation of new processes



Unit clause =
Process termination

e.g. process(State).

AND-PARALLELISM

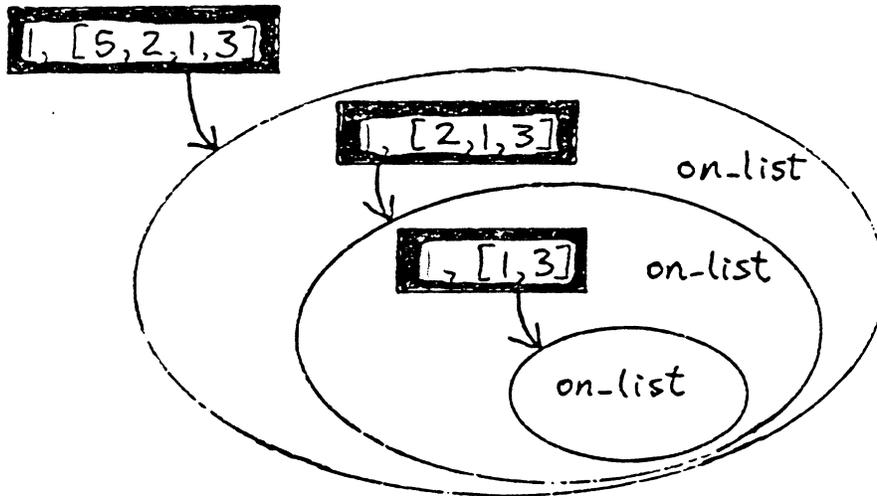
mode on-list(?,?).

on-list(Item, [Item|List]).

on-list(Item, [U|List]) \leftarrow Item \neq U:

on-list(Item, List).

e.g. on-list(1, [5, 2, 1, 3])



AND-PARALLELISM

mode off_tree(?,?).

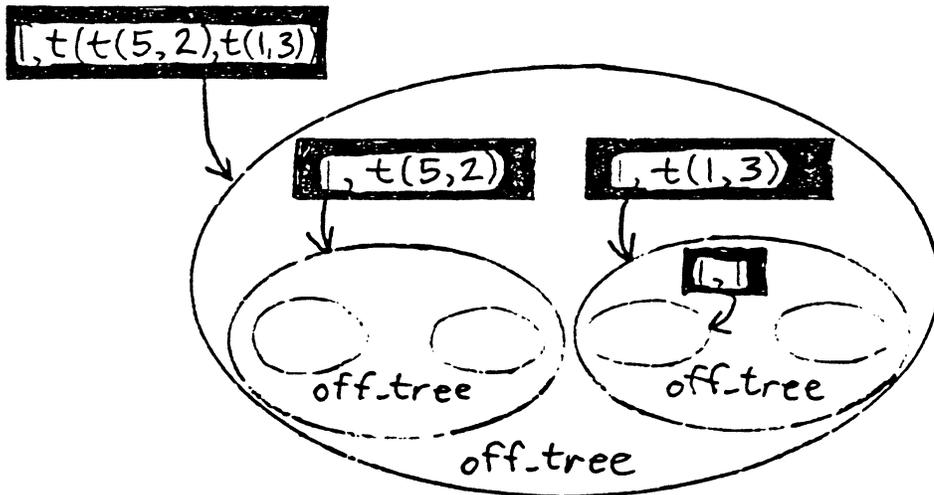
off_tree(Item, t(T1, T2)) ←

off_tree(Item, T1), off_tree(Item, T2).

off_tree(Item, L) ←

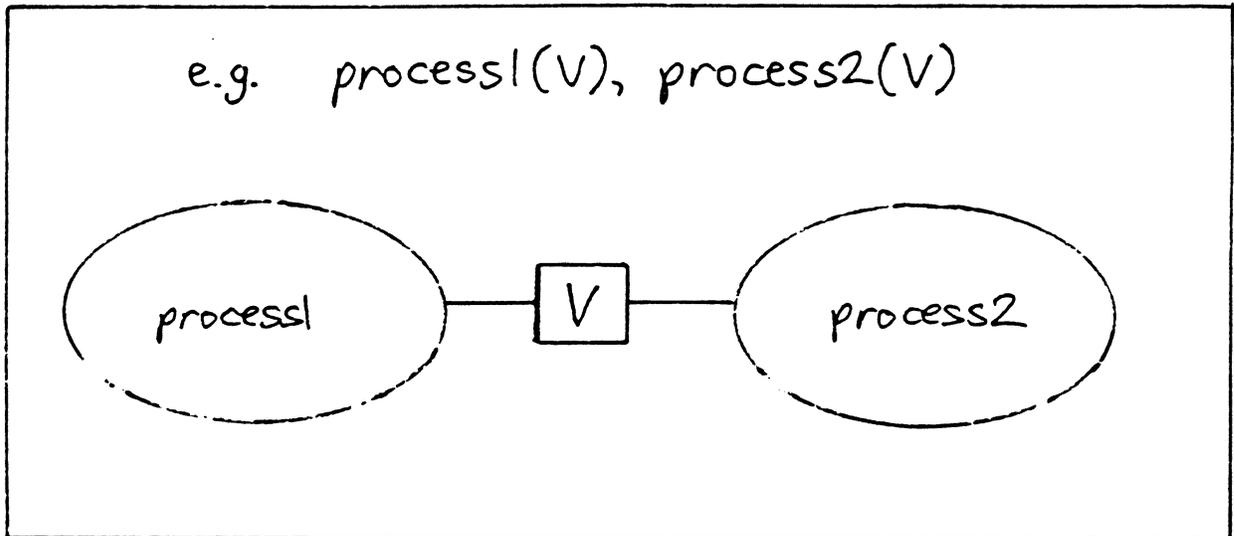
integer(L), Item \= L : true.

e.g. off_tree(1, t(t(5, 2), t(1, 3)))



COMMUNICATION

Shared variable = Communication channel or memory location



Binding shared variable = sending message

N.B. Single-assignment

COMMUNICATION

mode sum_tree(?, ↑).

sum_tree(t(T1, T2), V) ←

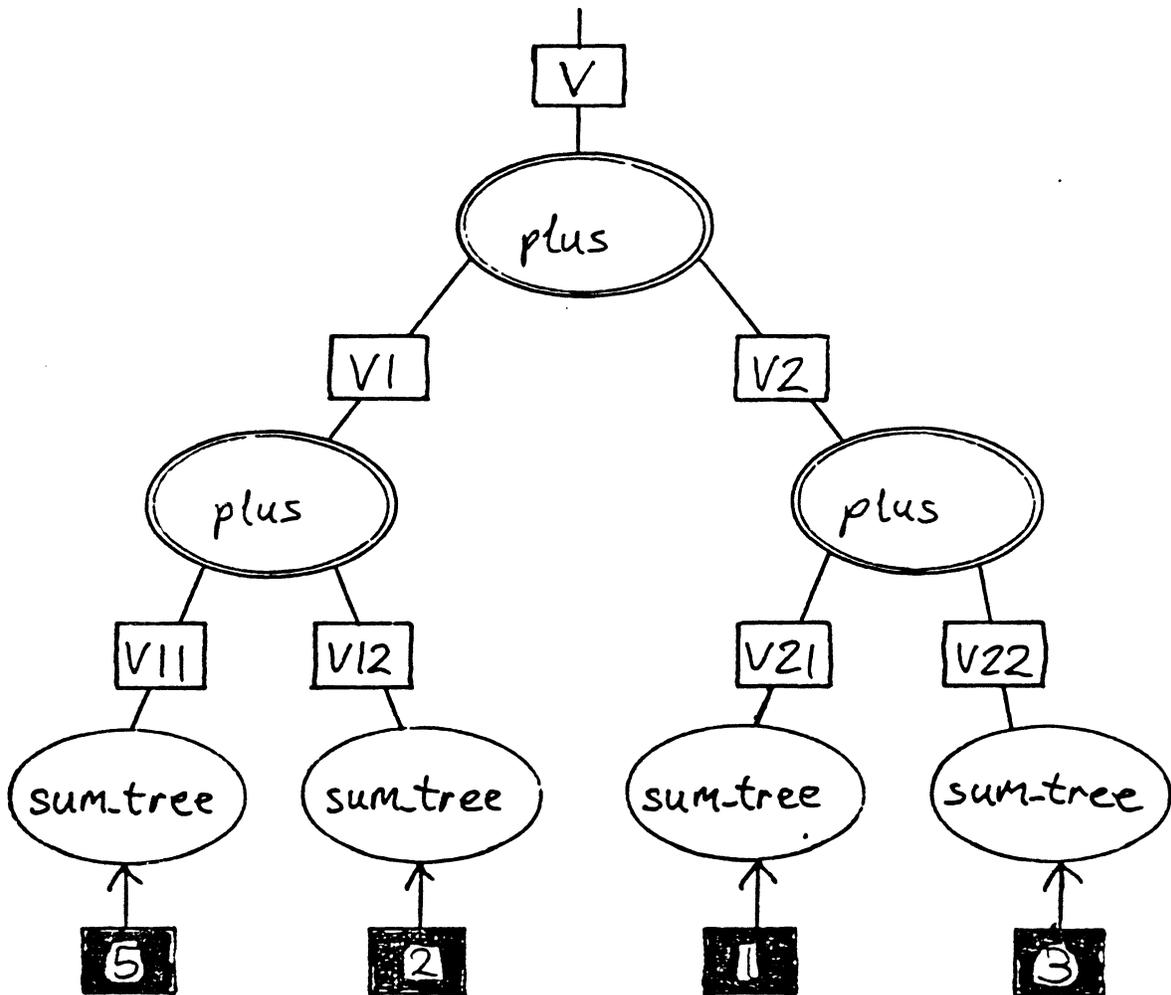
sum_tree(T1, V1), sum_tree(T2, V2),

plus(V1, V2, V).

sum_tree(L, V) ← integer(L) :

V = L.

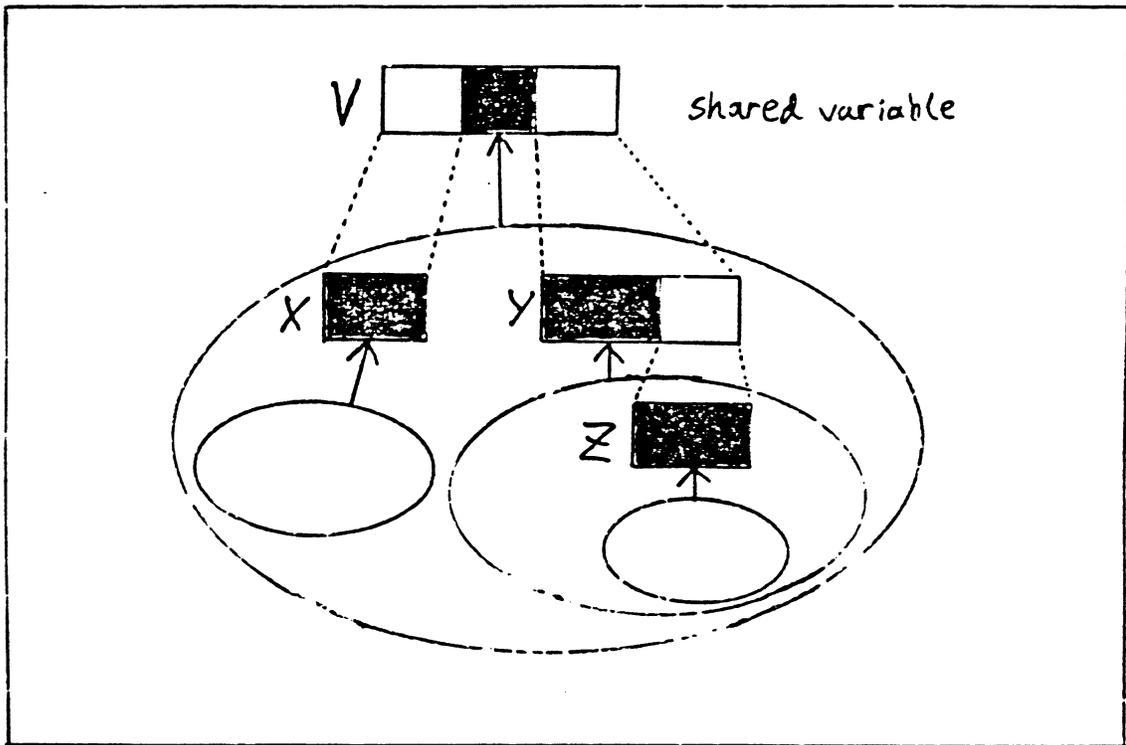
e.g. sum_tree(t(t(5, 2), t(1, 3)), V)



COMMUNICATION

Stream communication

Sequence of partial bindings to shared variable =
Stream of messages



$$V = f(X, Y) \quad X = t1 \quad Y = g(Z) \quad Z = t2$$

COMMUNICATION

mode flat_tree(?, ↑).

flat_tree(t(T1, T2), S) ←
flat_tree(T1, S1), flat_tree(T2, S2),
append(S1, S2, S).

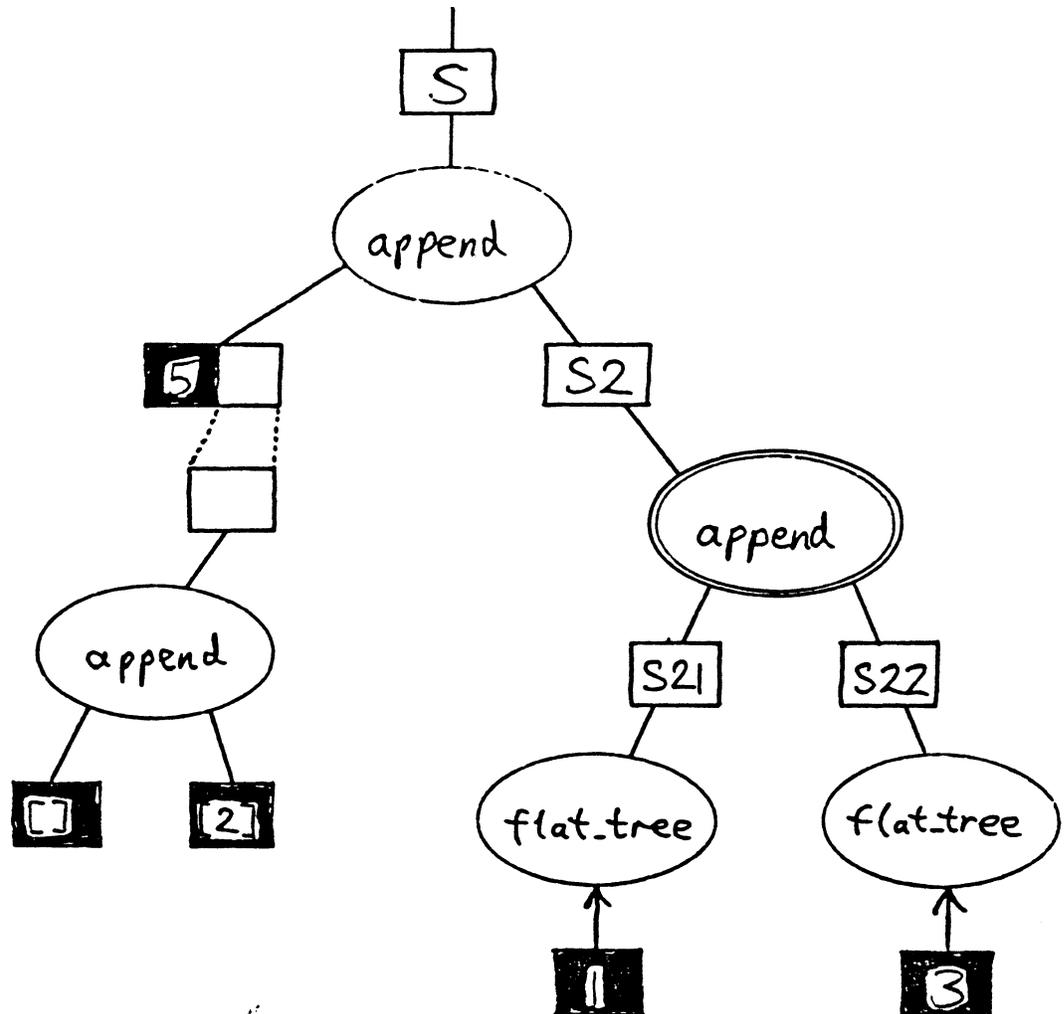
flat_tree(L, [L]) ← integer(L) : true.

mode append(?, ?, ↑).

append([U|X], Y, [U|Z]) ← append(X, Y, Z).

append([], Y, Y).

e.g. flat_tree(t(t(5, 2), t(1, 3)), S)



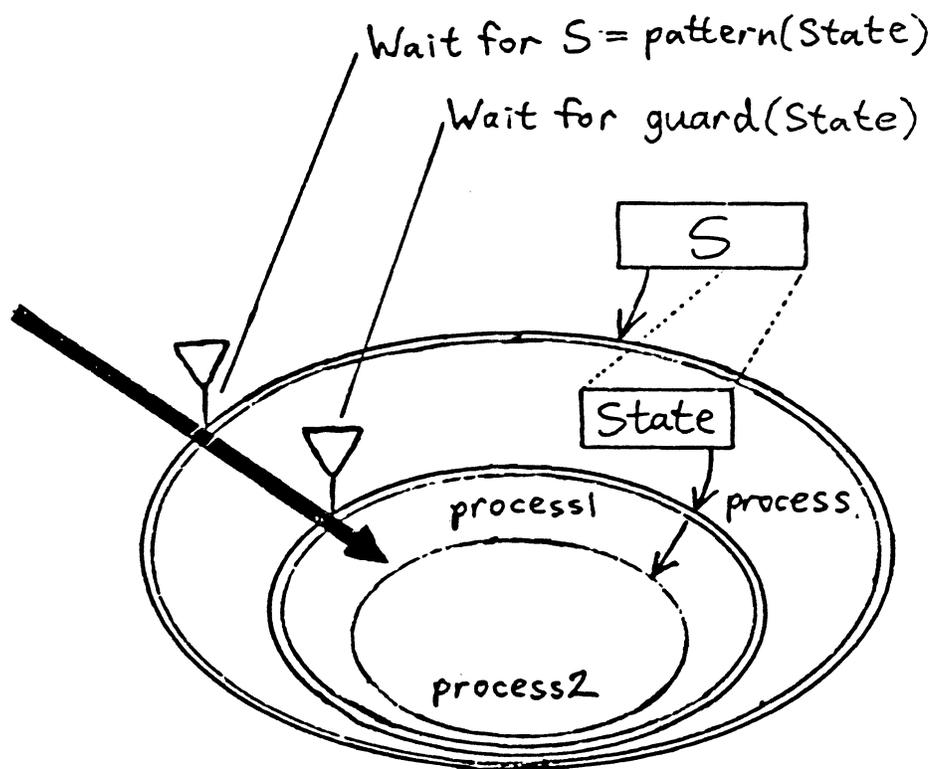
SYNCHRONIZATION

Delay reduction (call \rightarrow clause body) until:

1. Input arguments available, and
2. Guard succeeds

```
mode process(?), process1(?).  
process(pattern(State))  $\leftarrow$   
  process1(State).
```

```
process1(State)  $\leftarrow$  guard(State):  
  process2(State).
```



SYNCHRONIZATION

Before reduction

No access to output arguments of call.

Only input (read-only) access to input arguments of call.

1. One-way unification (matching)

Unification (call - clause head) cannot bind call variables:
suspends on attempt to do so.

Call	$r(t_1, \dots, t_k)$
	\downarrow \downarrow
Clause head	$r(t'_1, \dots, t'_k)$

2. Safe guards

Guard cannot bind call variables.

After reduction

Call arguments are unified with head arguments, in output positions.

May bind call variables.

SYNCHRONIZATION

Kernel PARLOG - make matching explicit

mode $p(?, \uparrow, ?, \uparrow)$.

$p(t_1, t_2, t_3, t_4) \leftarrow \text{guard} : \text{body}$.

can be written:

$p(x_1, x_2, x_3, x_4) \leftarrow t_1 \Leftarrow x_1, t_3 \Leftarrow x_3, \text{guard} : x_2 = t_2, x_4 = t_4, \text{body}$.

Matching primitive

$t_1 \Leftarrow t_2$

Unify t_1, t_2 but suspend on attempt to bind variables in t_2 .

SYNCHRONIZATION

1. mode $\text{append}(?, ?, \uparrow)$.

$\text{append}([u|x], Y, [u|z]) \leftarrow \text{append}(X, Y, Z)$.

$\text{append}([], Y, Y)$.

PARLOG
⇓
Kernel PARLOG

2. $\text{append}(T, Y, S) \leftarrow [u|x] \leq T :$
 $S = [u|z], \text{append}(X, Y, Z)$.

$\text{append}(T, Y, S) \leftarrow [] \leq T :$
 $S = Y$.

COMMITTED CHOICE NON-DETERMINISM

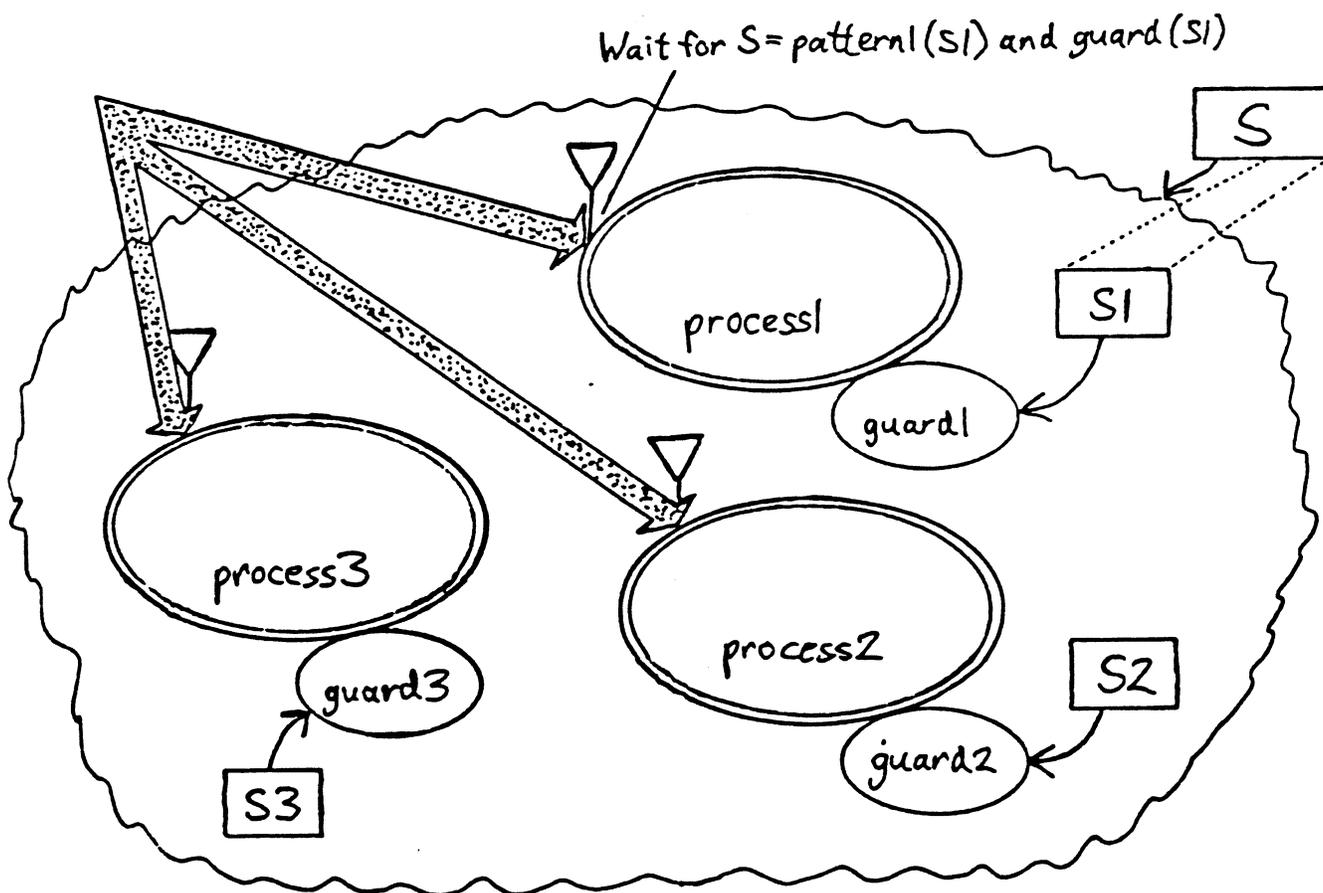
Clauses in procedure = alternative ways to reduce process

Committed choice of "candidate" clause

("candidate": successful input matching and guard)

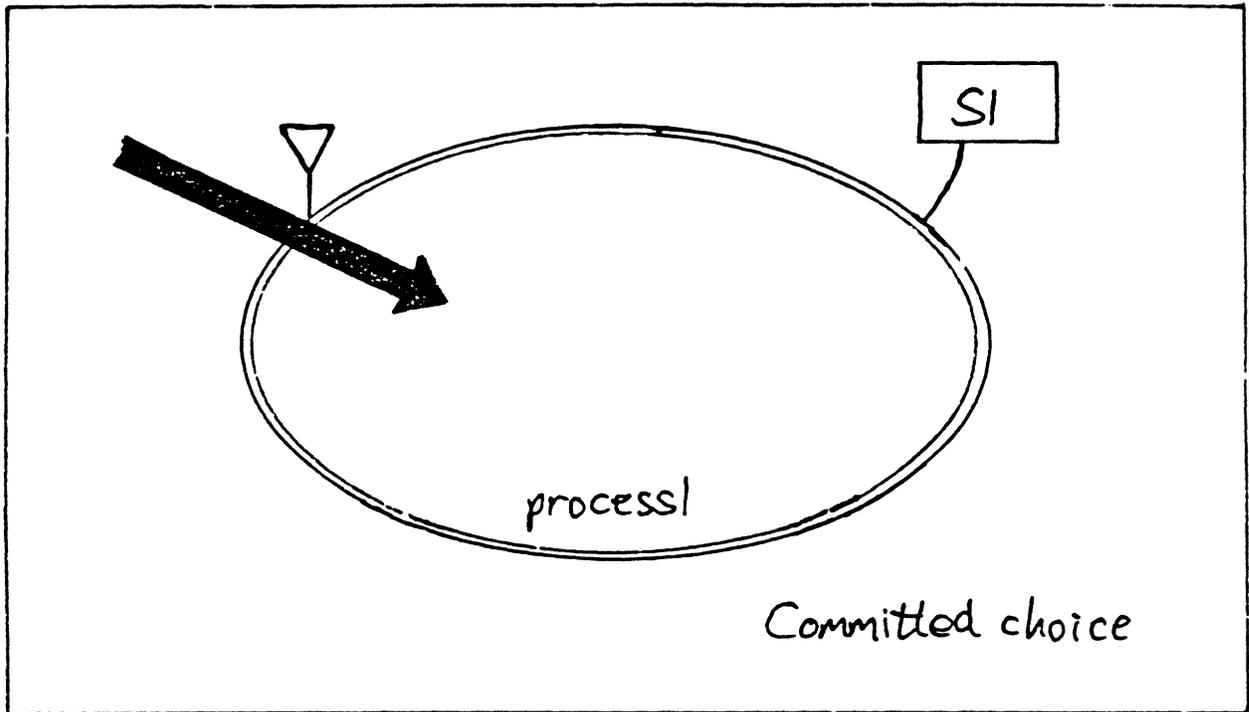
mode process(?).

e.g. $\text{process}(\text{pattern1}(S1)) \leftarrow \text{guard1}(S1) : \text{process1}(S1).$
 $\text{process}(\text{pattern2}(S2)) \leftarrow \text{guard2}(S2) : \text{process2}(S2).$
 $\text{process}(\text{pattern3}(S3)) \leftarrow \text{guard3}(S3) : \text{process3}(S3).$



Parallel search

COMMITTED CHOICE NON-DETERMINISM



Read-only access to arguments during search
- "safe" guards.

Output only after "commitment".
- committed to output.

May be many candidate clauses.
- time dependency.

Parallel search for clause.
- "committed" or-parallelism.

COMMITTED CHOICE NON-DETERMINISM

Committed on-parallelism

mode on_tree(?,?).

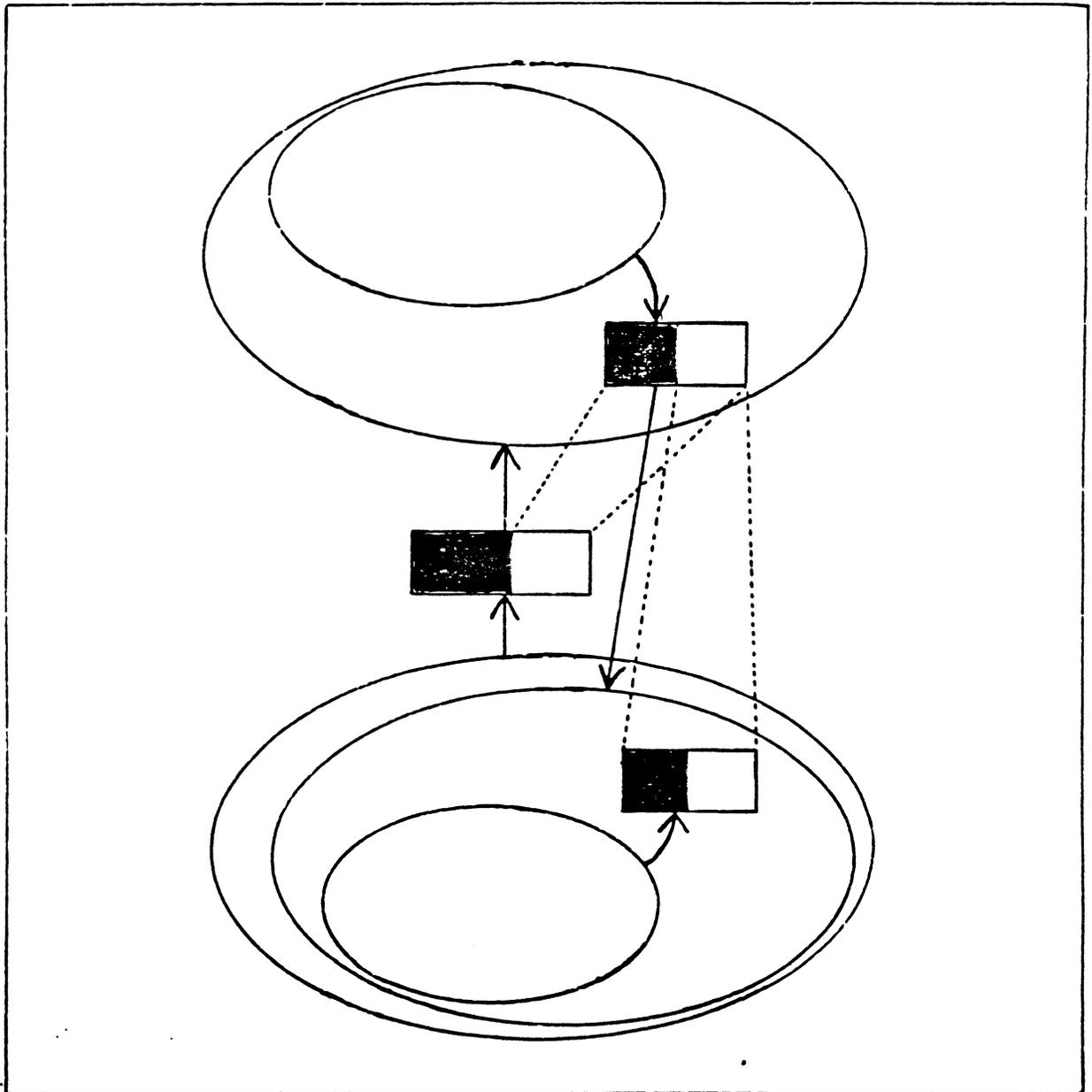
on_tree(Item, t(T1, T2)) ← on_tree(Item, T1):
true.

on_tree(Item, t(T1, T2)) ← on_tree(Item, T2):
true.

on_tree(Item, Item).

THE LOGICAL VARIABLE

Sequence of partial bindings to shared variable can be made by different processes.



Cooperative construction of data.

THE LOGICAL VARIABLE

Back communication

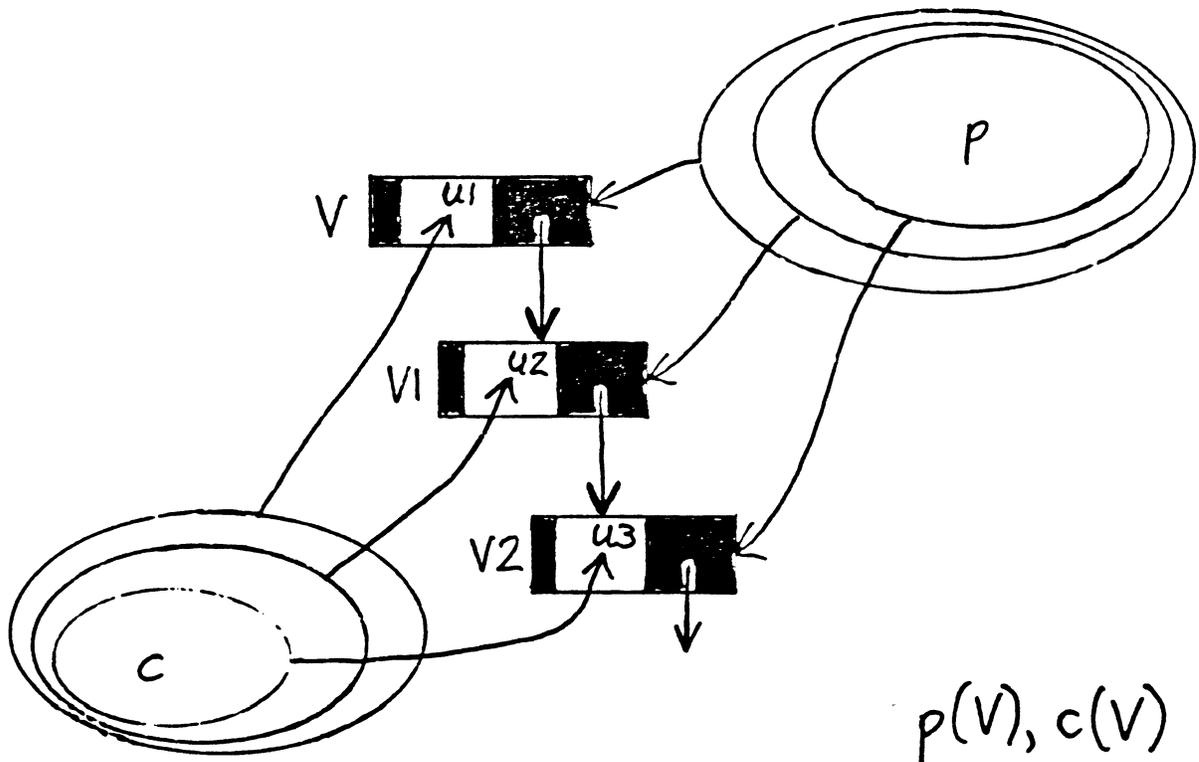
Sequence of partial bindings to shared variable, some by this process, some by others.

e.g. $p: V = [t(u_1) | v_1]$

$v_1 = [t(u_2) | v_2]$

$c: u_1 = t_1$

$u_2 = t_2$



Back communication + merge = monitors

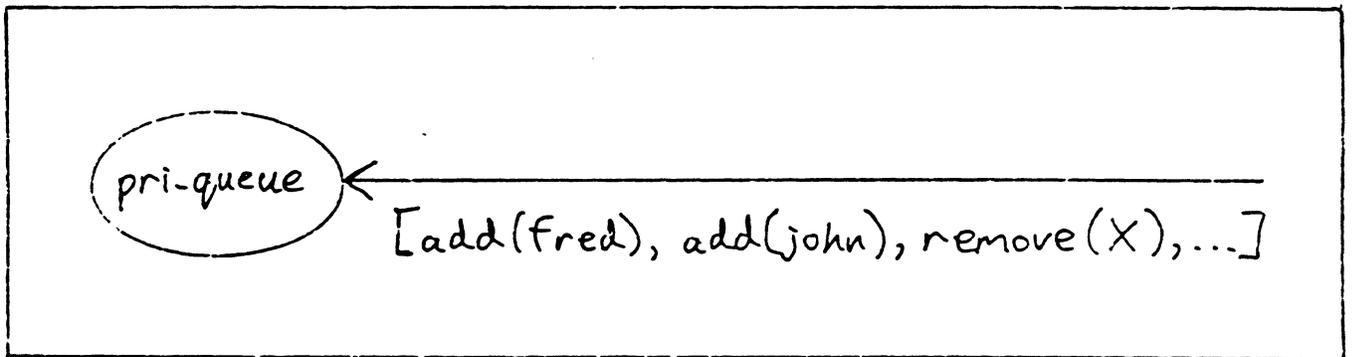
Back communication \rightarrow lazy (demand-driven) evaluation

THE LOGICAL VARIABLE

mode pri-queue(?), pri-queue(?,?).
pri-queue(M) ← pri-queue(M, []).

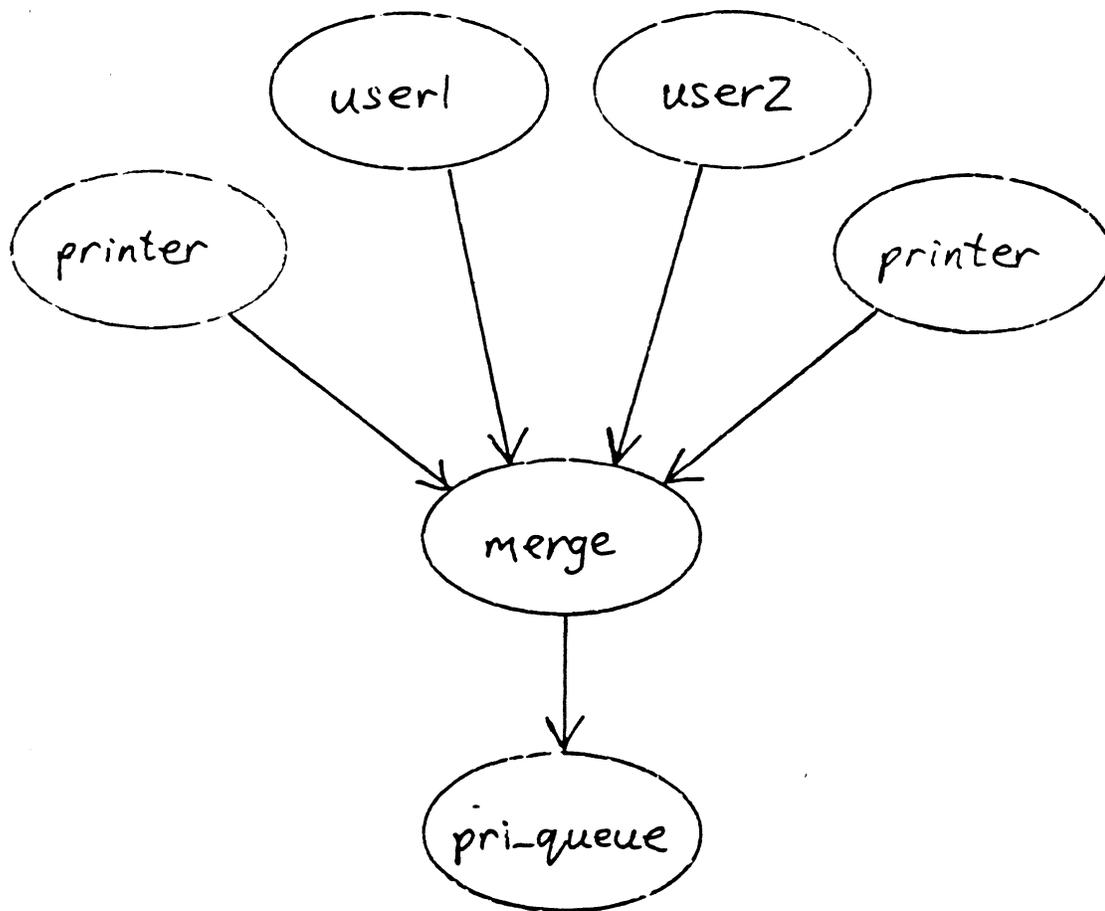
pri-queue([add(Item)|M], Q) ←
insert(Item, Q, New-q),
pri-queue(M, New-q).

pri-queue([remove(Item)|M], [H|Q]) ←
Item = H,
pri-queue(M, Q).



THE LOGICAL VARIABLE

e.g. priority spooler



THE LOGICAL VARIABLE

Eager "read list":

mode eager-read(\uparrow).

eager-read($[]$) \leftarrow end-of-file : true ;

eager-read($[u|x]$) \leftarrow
read(u) &
eager-read(x).

Lazy "read list":

mode lazy-read(?).

lazy-read($[u|x]$) \leftarrow end-of-file :
 $u = \text{end-of-file}$;

lazy-read($[u|x]$) \leftarrow
read(u) &
lazy-read(x).

METALEVEL PROGRAMMING

Problem:

To allow a process ("metaprogram") to examine and control evaluation of another ("object program").

Solution 1:

Transform the object program to signal its status and respond to control messages.

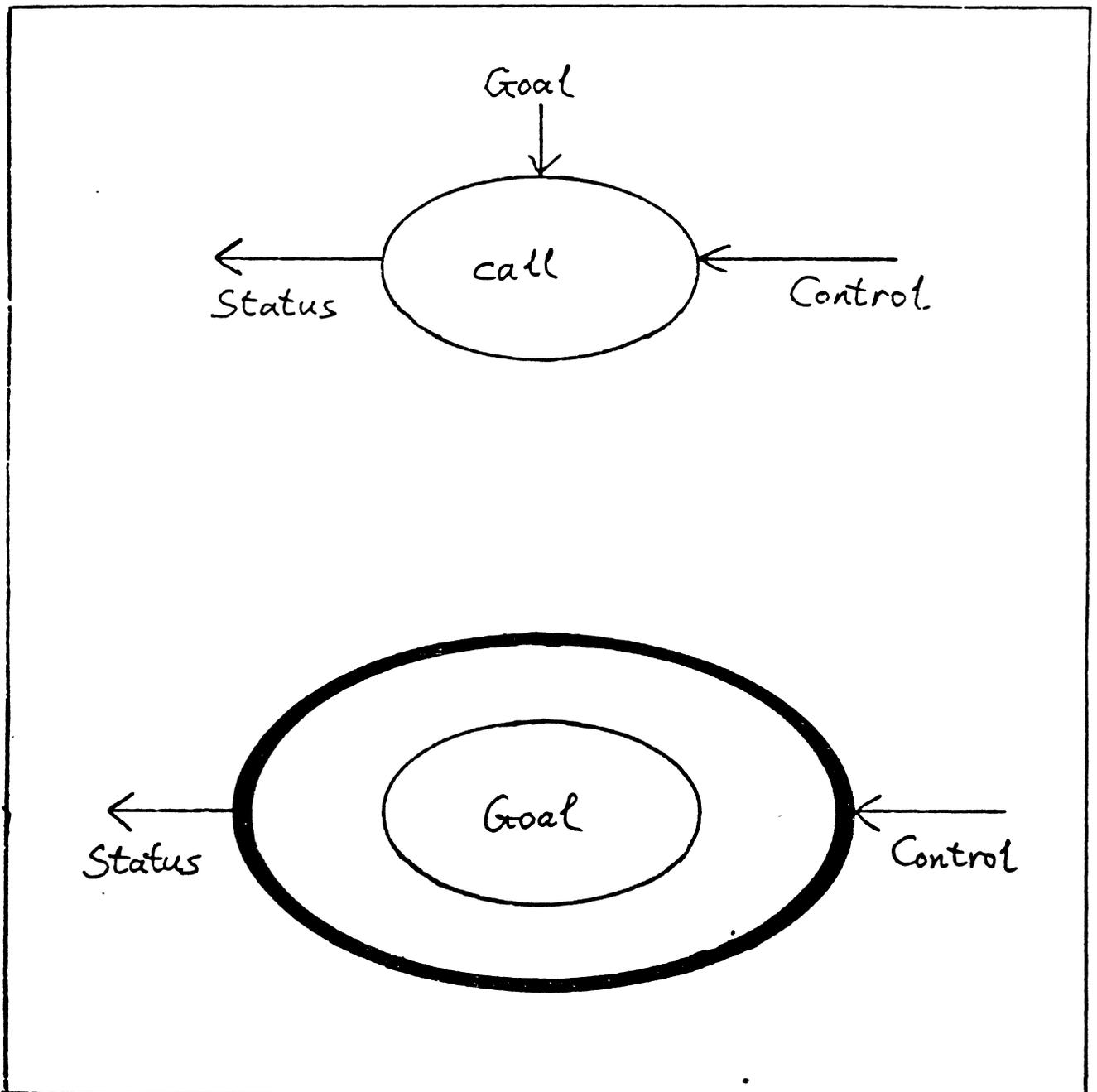
Solution 2:

Encapsulate object program in special metacall to achieve same effect.

METALEVEL PROGRAMMING

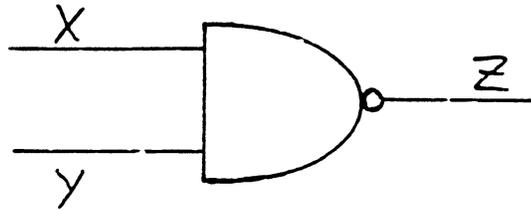
The PARLOG metacall!

$call(\text{Goal?}, \text{Status}\uparrow, \text{Control?})$



EXAMPLE: SR LATCH

PARLOG specification of NAND gate



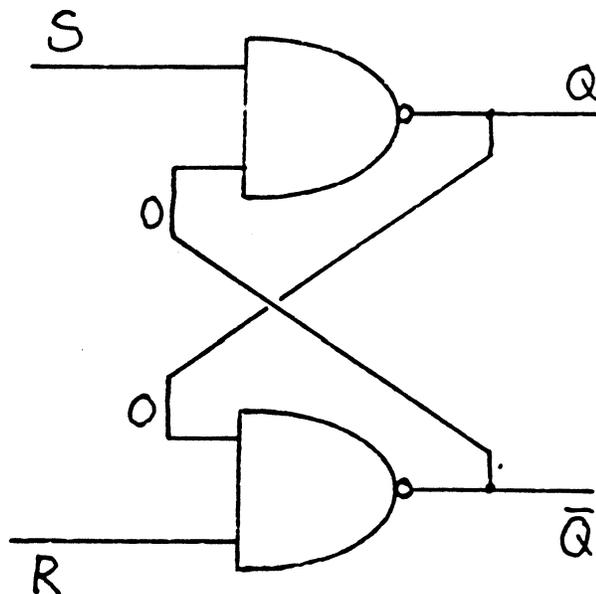
mode nand(?, ?, ↑).

nand([1|X], [1|Y], [0|Z]) ← nand(X, Y, Z).

nand([0|X], [V|Y], [1|Z]) ← nand(X, Y, Z).

nand([U|X], [0|Y], [1|Z]) ← nand(X, Y, Z).

SR latch using NAND gates



mode sr-latch(?, ?, ↑, ↑).

sr-latch(S, R, Q, Q-) ←

EXAMPLE: PARSER

Grammar

Expr \rightarrow Term Rest_expr

Rest_expr \rightarrow Add_op Expr .

Rest_expr \rightarrow empty

Term \rightarrow Number

Term \rightarrow '(' Expr ')'

PARLOG

mode expr(?, \uparrow), rest_expr(?, \uparrow), term(?, \uparrow).

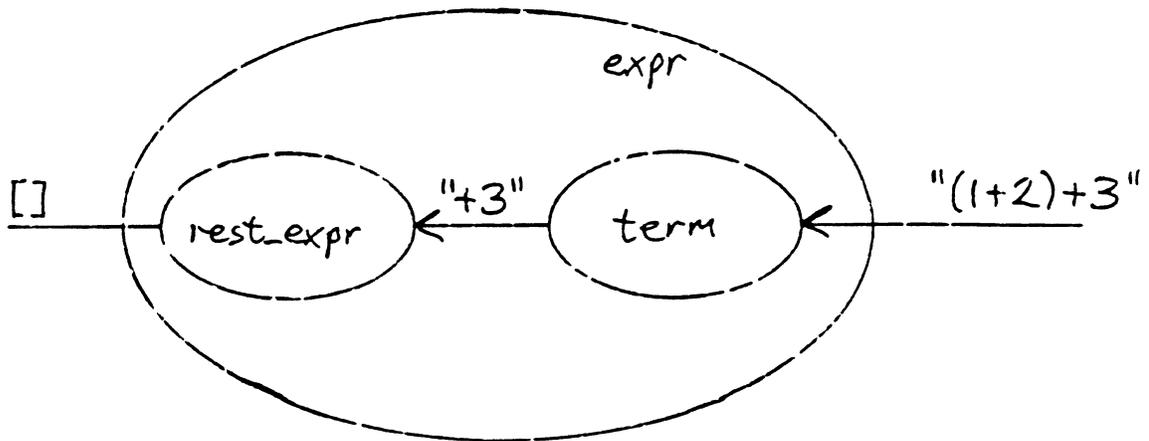
expr(Tokens-h, Tokens-t) \leftarrow
term(Tokens-h, Tokens), rest_expr(Tokens, Tokens-t).

rest_expr([Op|Tokens-h], Tokens-t) \leftarrow add_op(Op) :
expr(Tokens-h, Tokens-t) ;
rest_expr(Tokens, Tokens).

term([N|Tokens], Tokens) \leftarrow number(N) : true.
term(['(|Tokens-h], Tokens-t) \leftarrow
expr(Tokens-h, [')|Tokens-t]).

EXAMPLE: PARSER

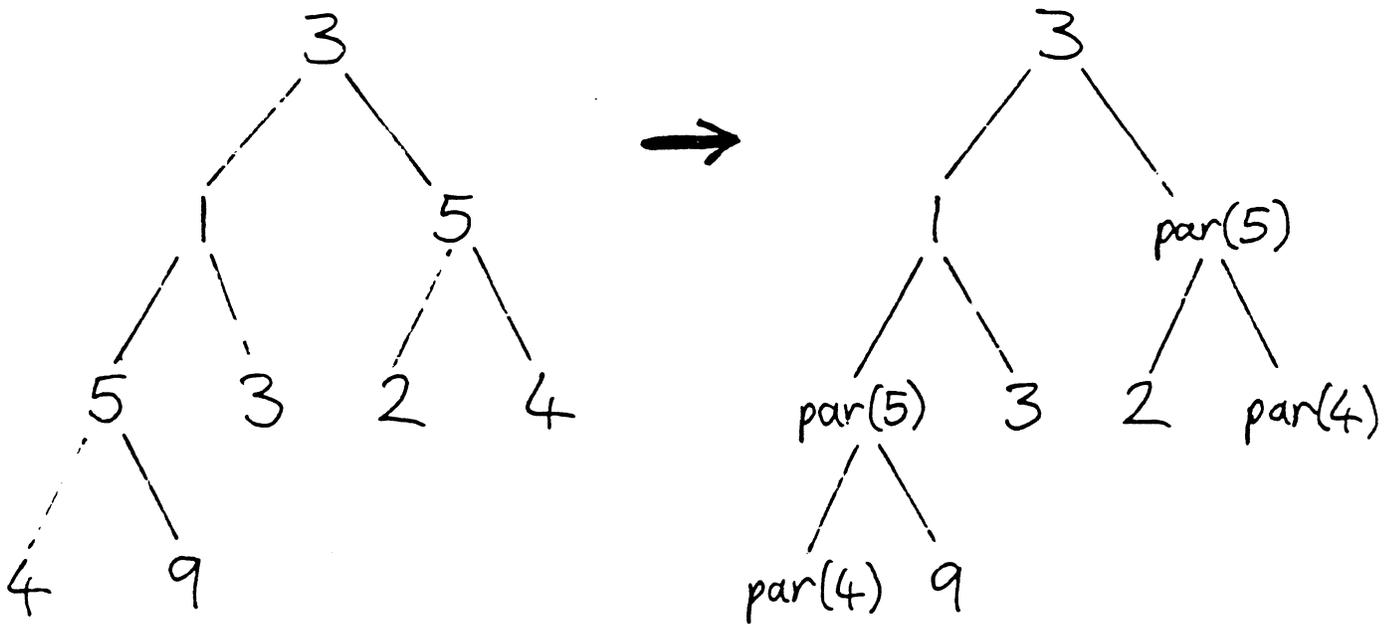
Process interpretation



EXAMPLE: LABEL TREE

Problem:

Mark nodes of a labelled binary tree that occur on parallel branches.



EXAMPLE: LABEL TREE

mode labeltree(I_tree?, O_tree↑, Par_this?, In_this↑).

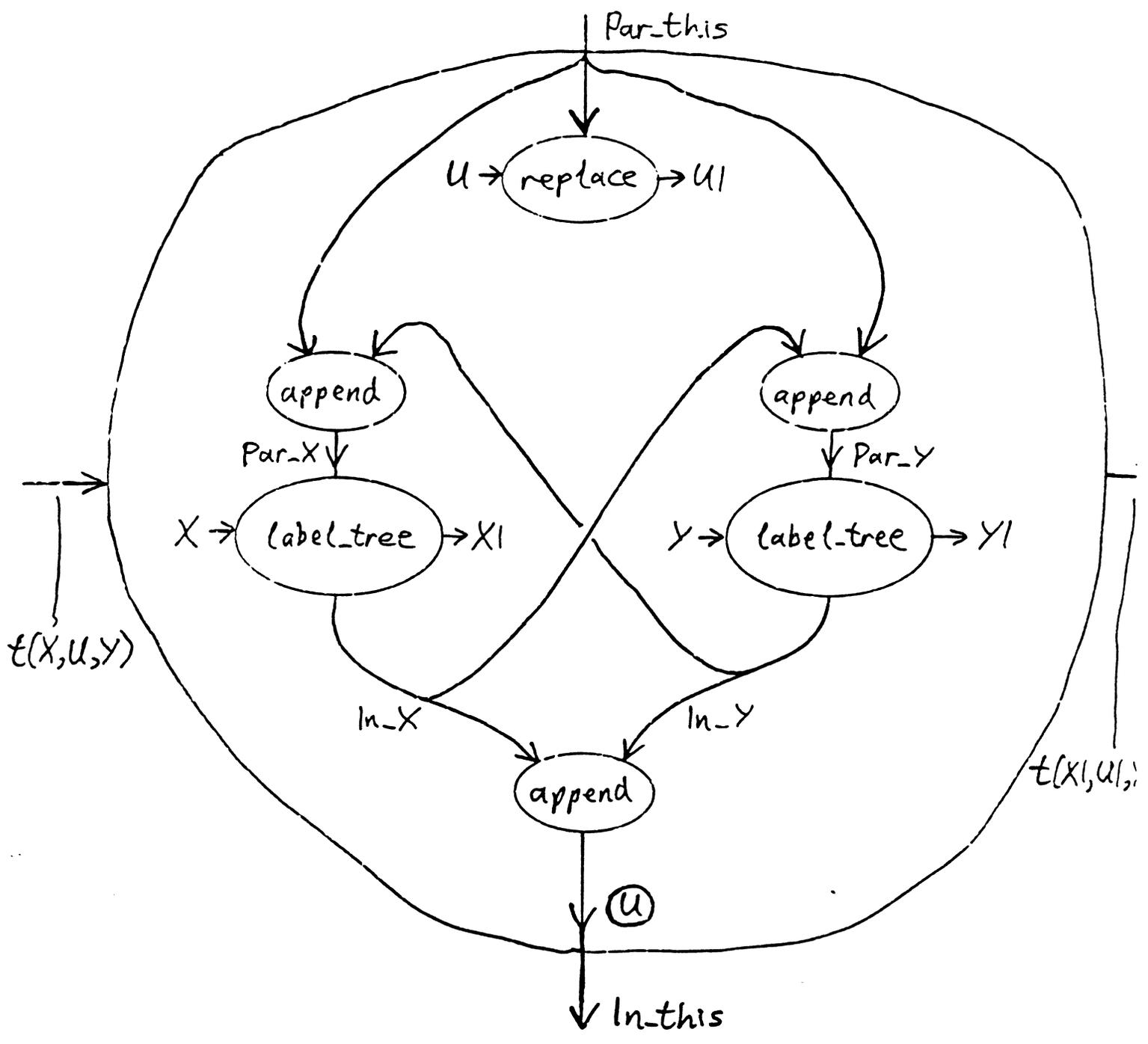
```
labeltree(t(X,U,Y), t(X1,U1,Y1), Par_this, [U|In_this]) ←  
  replace(U,U1, Par_this),  
  labeltree(X,X1, Par_X, In_X),  
  labeltree(Y,Y1, Par_Y, In_Y),  
  append(Par_this, In_Y, Par_X),  
  append(Par_this, In_X, Par_Y),  
  append(In_X, In_Y, In_this).
```

labeltree(empty, empty, Par_this, []).

mode replace(Node?, New_node↑, Par_nodes?).

```
replace(Node, par(Node), Par_nodes) ←  
  on_list(Node, Par_nodes) : true ;  
replace(Node, Node, Par_nodes).
```

EXAMPLE: LABEL TREE



EXAMPLE: COMMUNICATION PROTOCOLS

mode dev(State?, In?, Out↑).

dev(s0, In, [syn|out]) ← dev(s1, In, Out).
% Establish

dev(t0, [syn|In], [syn-ack|Out]) ← dev(t1, In, Out).
% Acknowledge

dev(t0, [syn|In], [syn-nack|Out]) ← dev(t2, In, Out).
% Decline

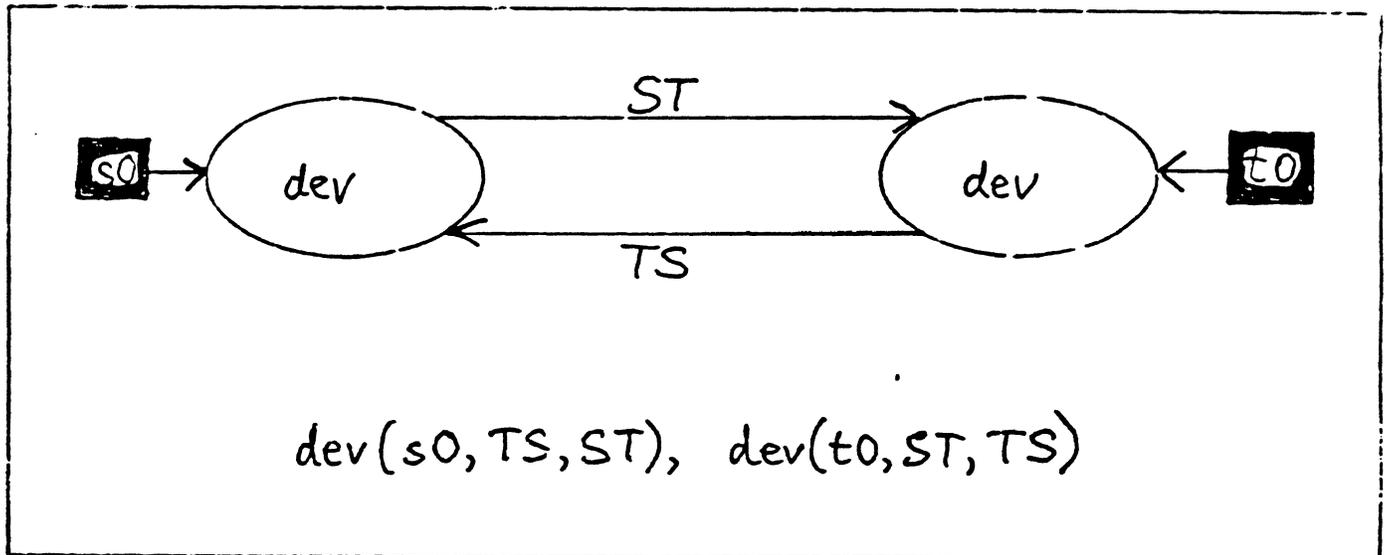
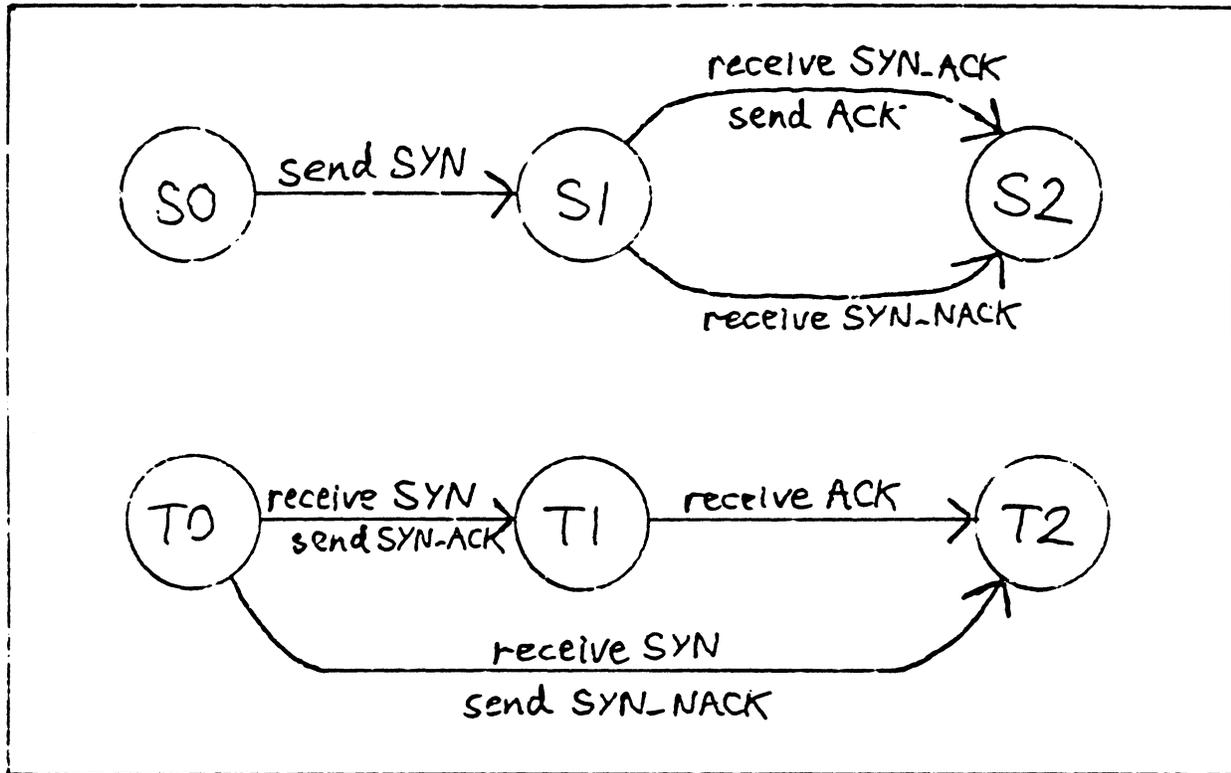
dev(s1, [syn-ack|In], [ack|Out]) ← dev(s2, In, Out).
% Confirm

dev(s1, [syn-nack|In], Out) ← dev(s2, In, Out).
% Abandon

dev(t1, [ack|In], Out) ← dev(t2, In, Out).
% Connect

EXAMPLE: COMMUNICATION PROTOCOLS

PARLOG specification of simple connection establishment protocol



EXAMPLE: PARLOG FOR SPECIFICATION

CSP specification of (illogical?) variable

$$\text{var}_x = \left(\begin{array}{l} \text{update?}Y \rightarrow \text{var}_y \mid \\ \text{read!}X \rightarrow \text{var}_x \end{array} \right)$$

Advantage: calculus for reasoning about behaviour

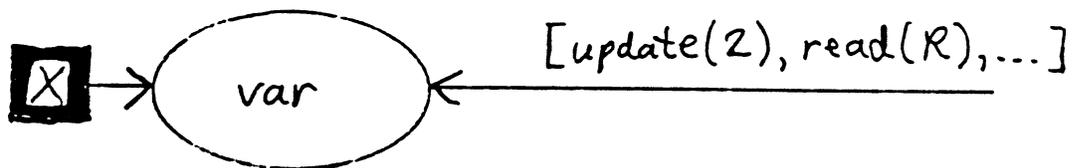
PARLOG specification

mode var(?,?).

$\text{var}(X, [\text{update}(Y) \mid M]) \leftarrow \text{var}(Y, M).$

$\text{var}(X, [\text{read}(R) \mid M]) \leftarrow R=X, \text{var}(X, M).$

$\text{var}(X, []).$



Advantage: some properties clear from logical reading

EXAMPLE: SYNCHRONIZED COMMUNICATION

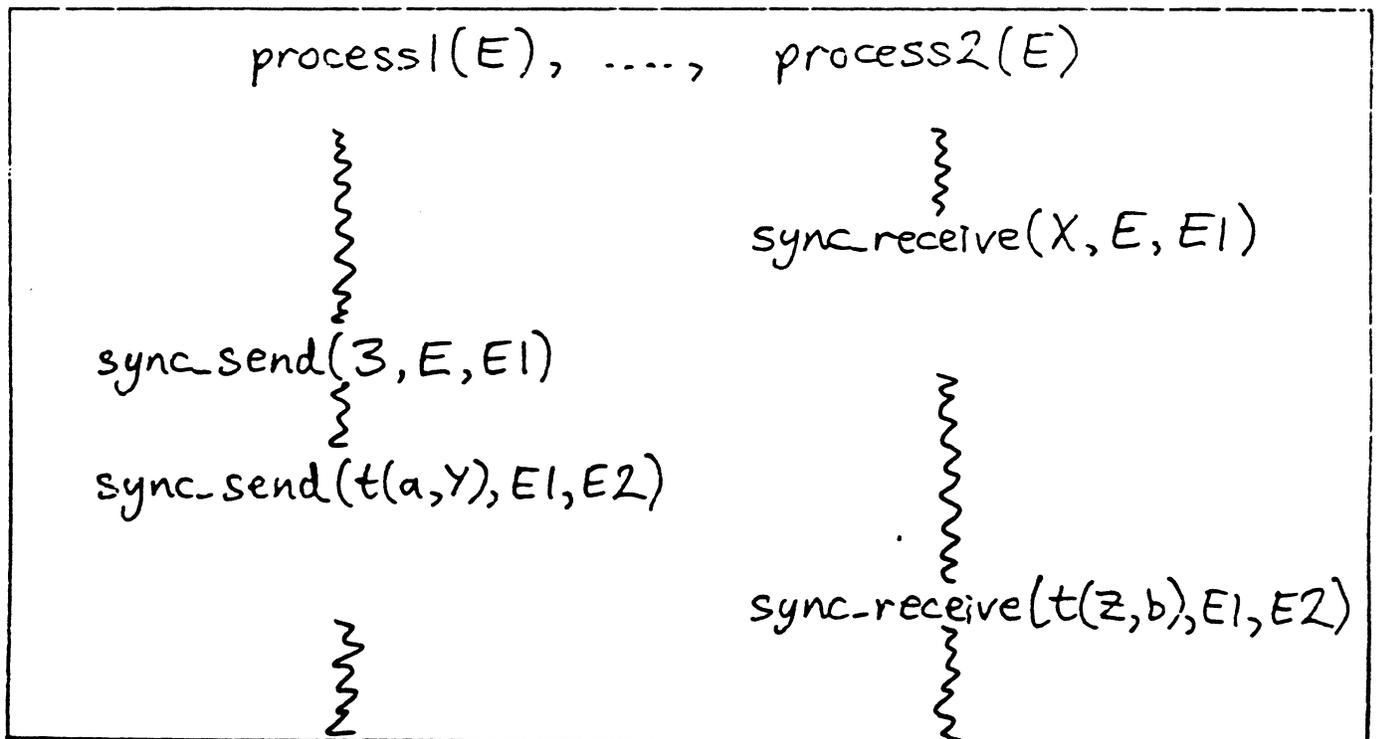
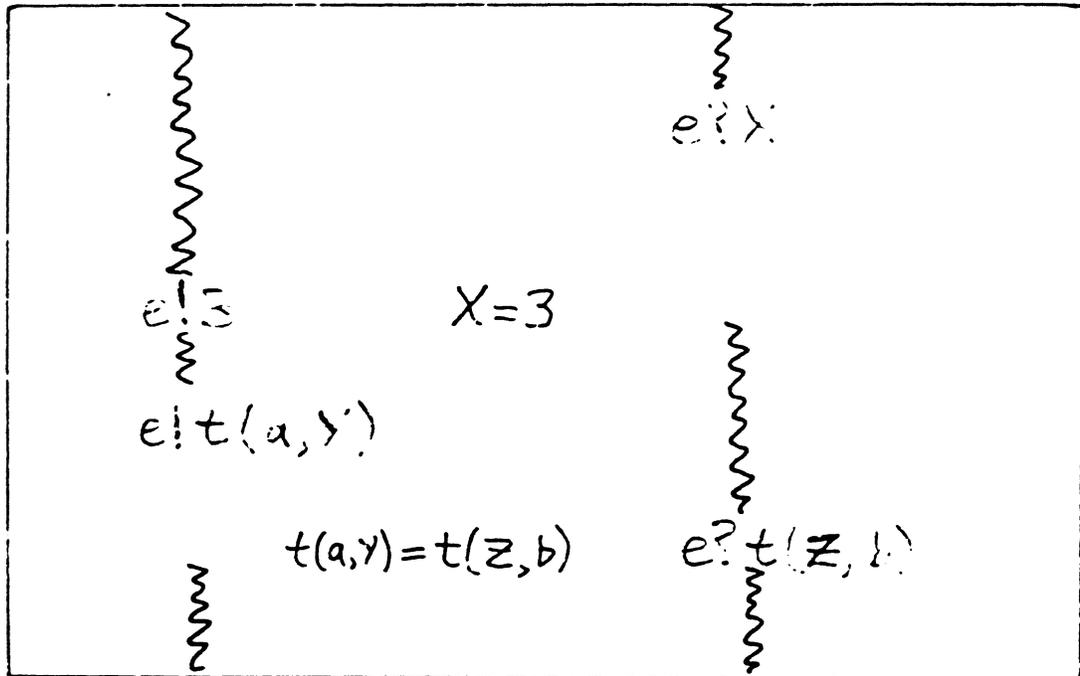
mode sync_send(?, ↑, ?), sync_receive(?, ?, ↑),
succeeded(?).

sync_send(Term, [(Term, Ack) | Ch], Ch) ←
succeeded(Ack).

succeeded(succeeded).

sync_receive(R_term, [(Term, Ack) | Ch], Ch) ←
R_term = Term &
Ack = succeeded.

EXAMPLE: SYNCHRONIZED COMMUNICATION



Page 38 missing: more of "Example: Synchronized Communication"?

Concurrent Prolog Differences

Synchronization: read-only variable

- Read-only annotation ('?') on consumer occurrences of variables.
- Suspend on attempt to bind a variable via a read-only occurrence.
- No other restrictions on variable bindings made by unification or guards; call variables may be bound before commitment

=> multiple environments

e.g. `append([U|X],Y,[U|Z]) :- append(X?,Y?,Z).
append([],Y,Y).`

"mode" depends on annotations in call.

- Difficulties implementing multiple environments

=> serious implementation work thus far restricted to
Flat Concurrent Prolog (FCP)

- Flat: only calls to system primitives in guards

GHC Differences

Syntax

Assumed mode (?, ..., ?).

Output unification done explicitly.

e.g. PARLOG

```
mode append(?,?,^).
append([U|X],Y,[U|Z]) <- append(X,Y,Z).
append([],Y,Y).
```

GHC

```
append([U|X],Y,Z1) :- Z1 = [U|Z],
    append(X,Y,Z).
append([],Y,Z1) :- Z1 = Y.
```

Synchronization

1. One-way unification (matching):

Call/head unification cannot bind call variables
(like PARLOG).

2. Guard suspends on attempt to bind call variables

(PARLOG: guard must be "safe").

N.B. Flat GHC = Flat PARLOG.

Applications of Parallel Logic Languages

Why use parallel logic languages?

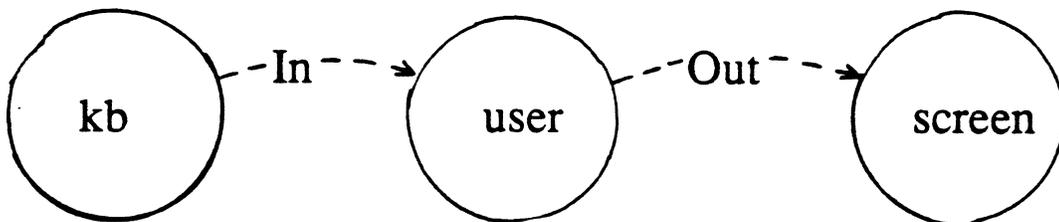
- Parallel logic languages =
Horn clause logic + concurrent, committed-choice proof procedure
- Horn clause logic: (declarative content)
parallel logic programs can be read as executable specifications
- Proof procedure: (parallel execution)
declarative programs can be executed in AND-parallel
- Proof procedure: (process interpretation)
can be exploited to provide useful operational behaviour

Useful Operational Behaviour

The proof procedure of parallel logic languages permits them to implement many useful 'real-world' behaviours

- Concurrent, communicating entities

..., *keyboard(In), user(In, Out), screen(Out), ...*



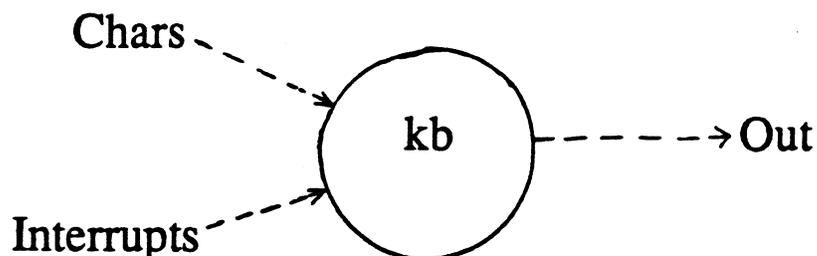
- Side-effects in the external world

screen([display(X) | In]) ← output(X) & screen(In).

- Time dependent treatment of events:

*keyboard([Ch | Chars], Interrupts, Out) ←
 handle_char(Ch, Out, NewOut),
 keyboard(Chars, Interrupts, NewOut).*

*keyboard(Chars, [Int | Interrupts] Out) ←
 handle_interrupt(Int, Out, NewOut),
 keyboard(Chars, Interrupts, NewOut).*



Applications of Parallel Logic Languages

(Some Examples)

- (a) **Behavioural:** describe, implement concurrent systems

(emphasis on operational behaviour)

operating systems / programming environments
telephone exchange control
simulation

- (b) **Algorithmic:** describe, implement parallel algorithms

(emphasis on declarative content)

parallel parsers
parallel router
compilers
image processing
qualitative reasoning

- (c) **Language Implementation:**

concurrent implementations of other language formalisms

Vulcan)	Concurrent object-oriented languages
POLKA)	
LOTOS		Formal description language for concurrent systems

A Large Application: PARLOG Programming System (PPS)

- An operating system designed to support logic programming on parallel machines
- A prototype implemented on SUN workstations is a major PARLOG application
- Uses some UNIX facilities but implements computation control, secondary storage management etc in PARLOG
- Implementation exploits extended PARLOG metacall:
 - an exception handling mechanism
 - modularity
 - computation priorities
- Implementation demonstrates:
 - Use of PARLOG to implement a complex system
 - PARLOG programs as executable specifications
 - Use of PARLOG control metacall
 - PARLOG programming techniques:
 - back communication, synchronization variables

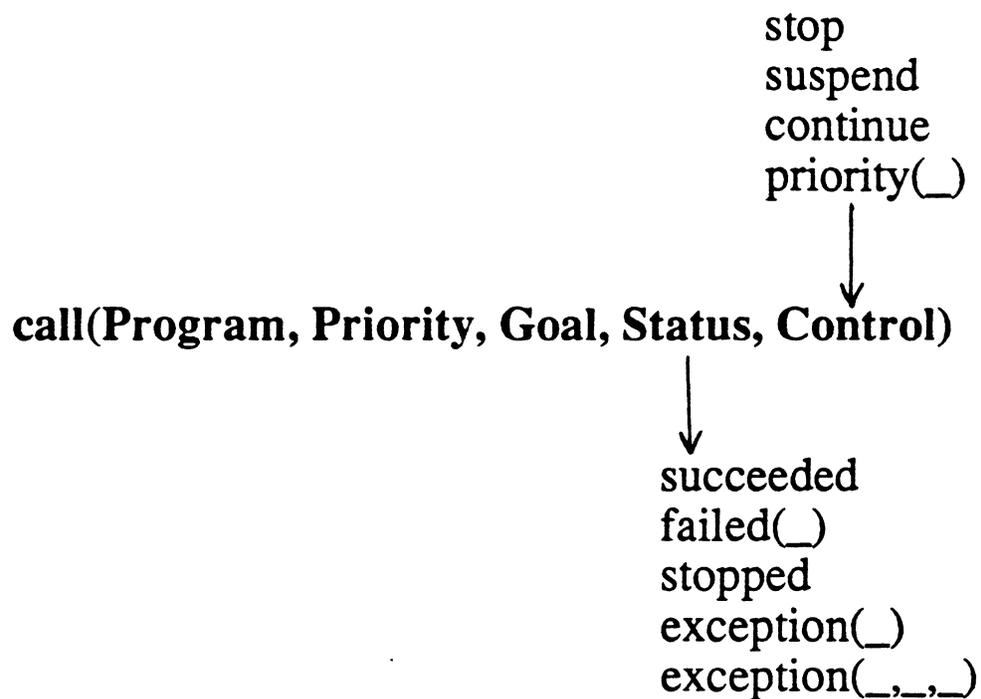
PPS Facilities

PPS provides:

- modularity: programs are divided into databases
- persistence: file system is invisible
databases persist between PPS invocations
- declarative environment:
user view: system = {databases}
user interaction: execute queries wrt databases
queries calculate relations over system states
- metaprogramming:
programs can:
 - reason about other programs
 - generate new versions of other programsprograms define relations over system states.
- multiprogramming:
task control
concurrency control
- user-definable inference mechanisms:
inheritance
query-the-user

An Extended PARLOG Metacall

- Primitive for describing initiation, monitoring and control of a computation
- Efficient implementation techniques developed



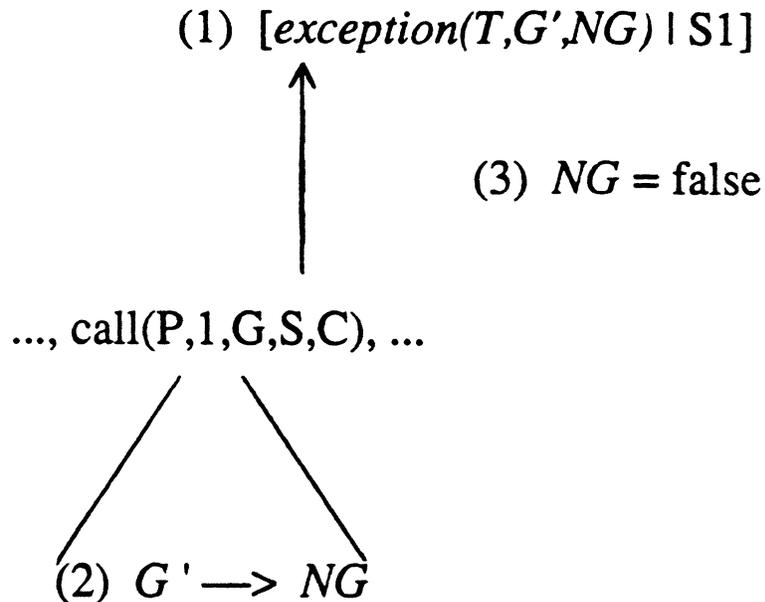
Program: names a module

Priority: programmer control of underlying scheduling mechanism

Status and Control: interfaces to monitoring and control functions of underlying machine

Exception Handling

- (1) The $exception(T,G,NG)$ message indicates an unsolvable goal G ; T indicates why the goal was unsolvable (undefined, div-by-zero, ...)



- (2) The unsolvable goal is replaced with a continuation variable NG
- (3) The monitoring program can instantiate NG to a new goal (in the example, false)

Applications:

- implement alternative exception handlers (including inheritance, query-the-user, ...)
- enhance expressive power of language by implementing system calls

A Simple Exception Handler

- Reports termination
- Aborts program if any run-time errors reported
- Closed world: fails all goals unsolvable in program

..., call(Db,1,G,S,C), monitor(S,C,Output), ...

mode initiate(Db?,G?,Output↑).

initiate(Db,G,O) ← call(Db,1,G,S,C), monitor(S,C,O).

mode monitor(Status?,Control↑,Output↑).

monitor(failed(_),C,[failed]).

monitor(succeeded,C,[succeeded]).

monitor([exception(T)|_],stop,[exception(T)]).

*monitor([exception(T,G,NG) | S],C,[exception(T,G) | O]) ←
NG = false, monitor(S, C, O).*

Concurrency Control in PPS

- PPS is a multiprogramming system: several queries can execute concurrently
- PPS supports metarelations that permit a program to:
 - access terms representing system state (*definition, ...*)
 - generate new states (*new_definition, ...*)
 - specify a new state, to apply on success

State is the set of all databases defined in PPS

- A PPS program may thus access a database in three ways:
 - to execute its code
 - to read its source
 - to assert new versions of predicates
- Control mechanisms are required to:
 - avoid contention due to concurrent access/update
 - maintain declarative semantics: a PPS program is a relation over states
- Implementation of these mechanisms illustrates use of PARLOG for systems programming

Metarelations

current(State ↑)
definition(State?, Db?, Relation?, Definition ↑)
new_definition(State?, Db?, Definition?, NewState ↑)
next(State?)
etc ...

1. Program transformation

Apply a transformation to all predicates in *Db*.

transform_db(Db) ←
 current(S),
 dict(S, Db, Dict),
 transform_db(S, Db, Dict, S'),
 next(S').

mode transform_db(State?, Db?, Dict?, NewState ↑).
transform_db(S, Db, [R/Dict], S'') ←
 definition(S, Db, R, Defn),
 transform(Defn, Defn'),
 new_definition(S, Db, Defn', S'),
 transform_db(S', Db, Dict, S'').
transform_db(S, Db, [], S).

2. Alternative Worlds

Simulate execution of *Q* in *Db* and in {*Db* + *Fact*}

try(Db, Q, Fact) ←
 current(S),
 add_fact(S, Db, Fact, S'),
 demo(S, Q),
 demo(S', Q).

Concurrency Control: Implementation

- For each query, PPS must:
 - maintain alternative states
 - commit modifications on successful termination of query
 - abort commitment if conflicting accesses
- Queries and databases are represented as goals in a parallel conjunction: that is, as processes.
- Queries communicate with databases by query (q) and metaquery (mq) messages:

message(To,q(Q,Done),Result)
message(To,mq(Q,Done),Result)

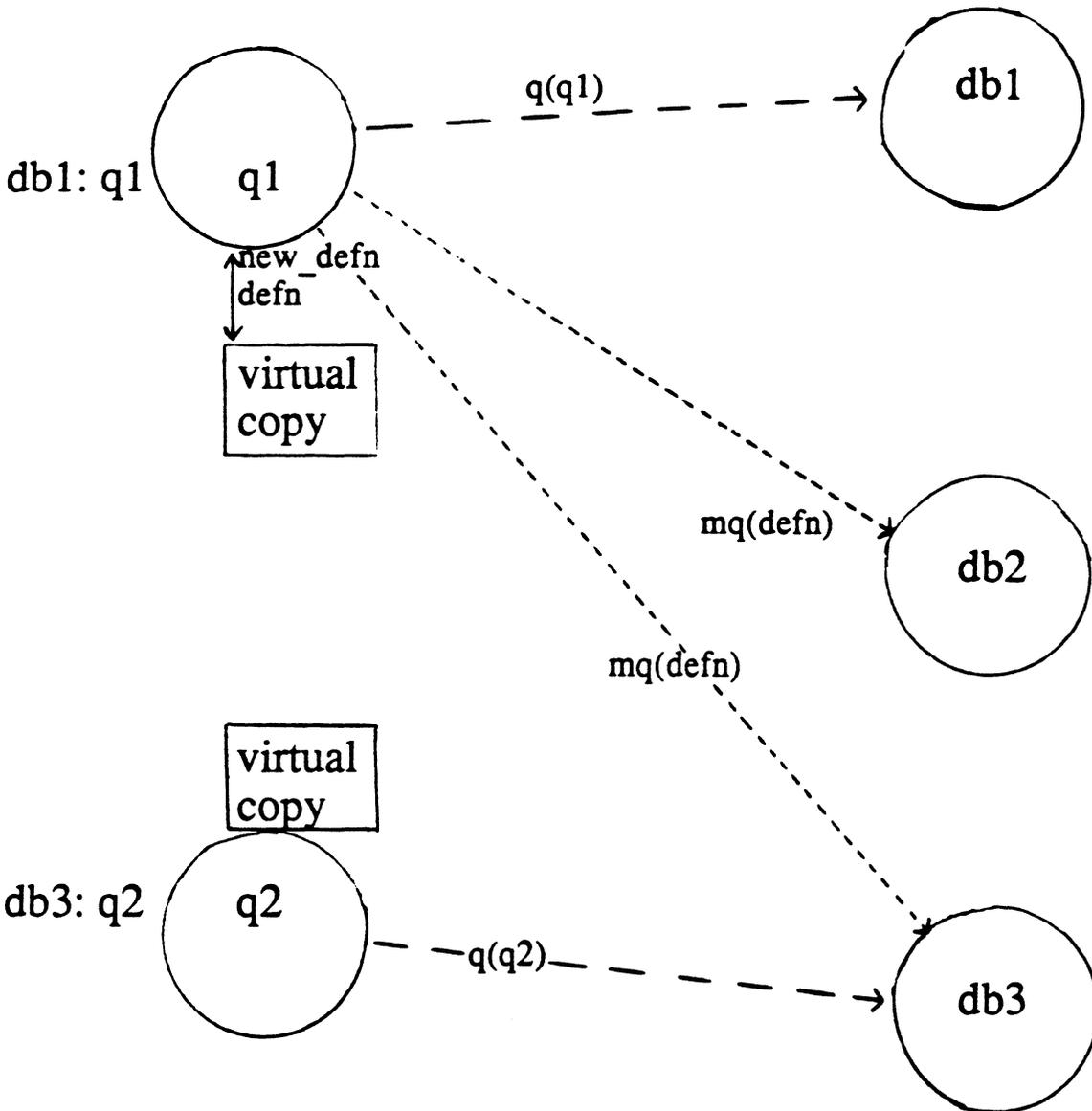
- Incomplete messages are used to return results of requests

Result = true, Result = error(Q)

- A *Done* variable associated with a query is included in all messages. This is bound when query terminates. This is an example of a synchronization variable.
- Updates (new states) are cached in the query process and applied to databases on success using a two-stage commit procedure

Concurrency Control: Implementation

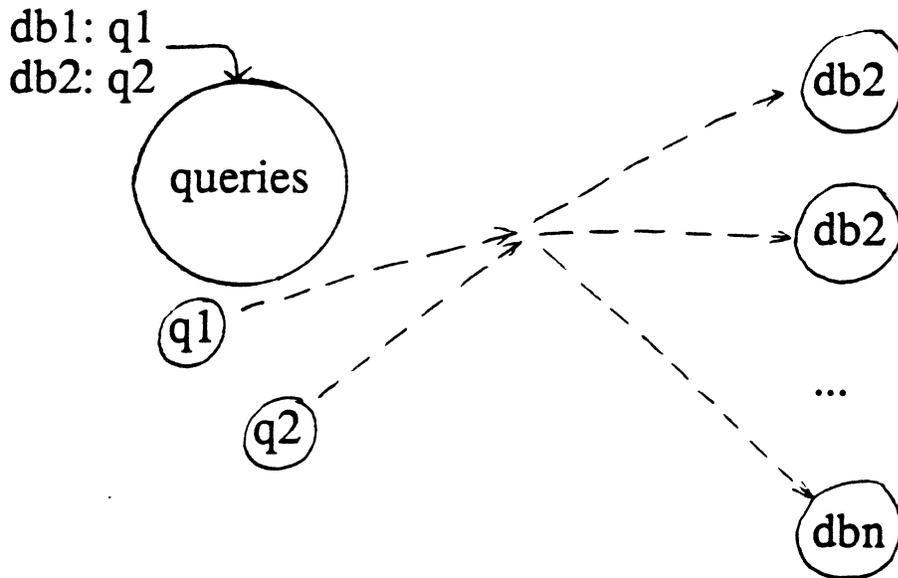
Assume three databases, db1, db2, db3.
Two concurrent queries, db1: q1 and db3: q2



- Virtual copies record modifications to databases
- PPS applies updates if query succeeds
- Updates are not applied if concurrent queries active in any database modified by query

PPS Structure

$init(Qs) \leftarrow queries(Qs, DbRs), databases(DbRs).$



$mode\ queries(Queries?, DbRequests \uparrow).$

$queries([(Db : Q) | Queries], DbRs) \leftarrow$
 $query(Db, Q, QRs),$
 $merge(QRs, Rs, DbRs),$
 $queries(Queries, Rs).$

- *queries* process waits for query messages
- Spawns a *query* process to control query evaluation
- Merges *query*'s database request stream into general stream

The Query Process

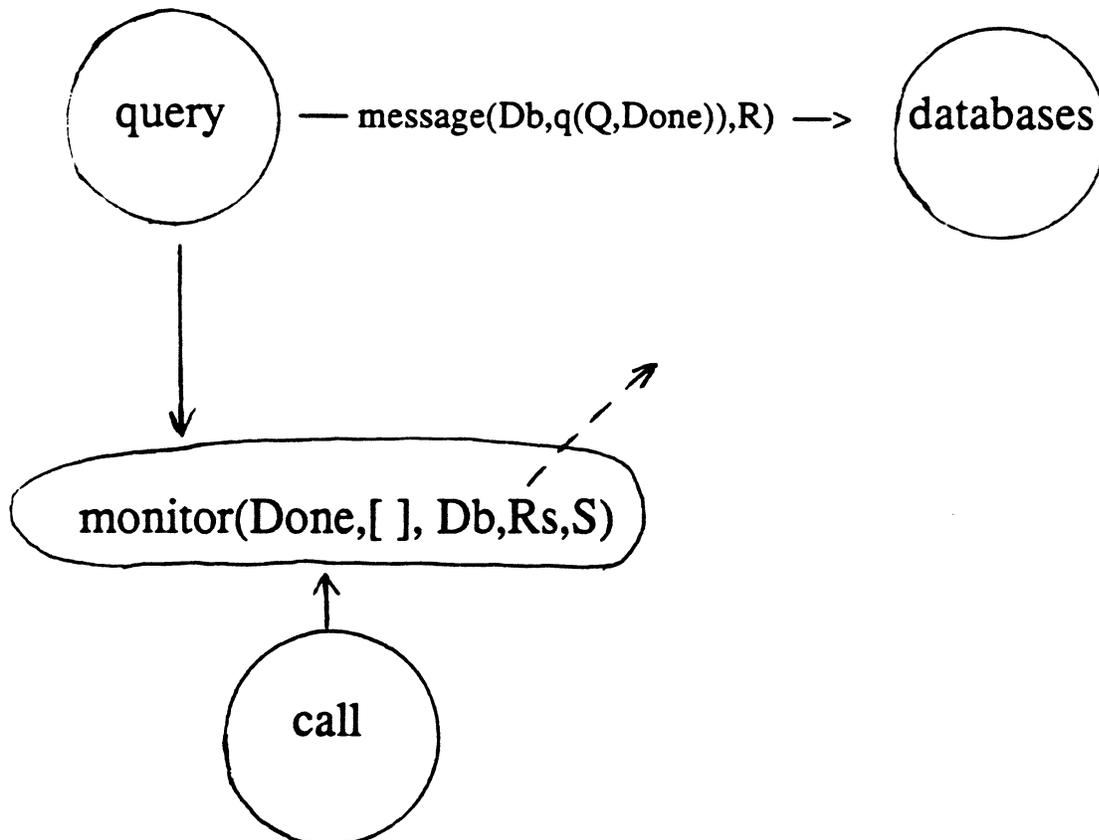
- Generates a query request message to the specified database
- Starts computation using the metacall
- Spawns a monitor process to control evaluation

mode query(Db?,Query?,DbRequests ↑).

query(Db,Q,[message(Db,q(Q,Done)),R) | Rs] ←

monitor(Done,[],Db,Rs,S),

call(Db,I,R,S,C).



The Monitor Process

- The monitor process controls a query evaluation
- It responds to query status messages by accessing *States* and, if necessary, generating messages to databases

mode monitor(Done?, States?, Db?, Requests ↑, Status?).

Failure:

monitor(D, States, Db, [], failed(_)) ← D = failed.

Success:

*monitor(D, States, Db, Requests, succeeded) ←
commit(States, Requests) & D=done.*

Metarelations: (definition and new_definition)

*monitor(D, States, Db, Rs, [exception(meta, G, R) / S]) ←
meta_relation(D, States, Rs, G, R, States', Rs'),
monitor(D, States', Db, Rs', S).*

Calls to relations in other databases:

*monitor(D, States, Db, [message(ODb, q(G, D), R) / Rs],
[exception(undef, ODb#G, NG) / S]) ←
NG = call(ODb, R),
monitor(D, States, Db, Rs, S).*

On Success, Two-Stage Commit

(1) Generate a commit message to each database to be updated

commit(Updates,Oki,Go), *Oki* and *Go* variables

(2) If all *Oki = ok*, instantiate *Go* to *go*

If any *Oki = abort*, instantiate *Go* to *abort*

mode commit(States?, Requests↑).

commit(States,Requests) ←
updates_required(States,Updates) ,
request_commit(Updates,Requests,Go,Oks),
confirm_commit(Oks,Go).

mode request_commit(Updates?, Rs↑,Go↑, Oks↑).

request_commit([db(Db,Us) | Updates],
[message(Db,commit(Us,Ok,Go),R) | Rs], Go,
[Ok | Oks]) ←
request_commit(Updates,Rs,Go,Oks).
request_commit([], [], Go, []).

mode confirm_commit(?, ↑).
confirm_commit([ok | Oks],Go) ←

confirm_commit(Oks,Go).
confirm_commit([abort | Oks], abort).
confirm_commit([], go).

Database Processes

- Each PPS database is represented by a database process
- Each has a stream connection to a disk process, which it can request to retrieve and store source and object code
- A database accepts queries, metaqueries and commits.
- Queries and metaqueries are processed at any time, and their *Done* variable recorded
- Commits are only processed if there are no concurrent accesses to database (all *Done* variables are bound).

mode database(Rs?,Db?,Source?,DoneVars?).

database([message(Db,q(Q,D),R) / Rs],Db,S,DVs) ←

R = Q, database(Rs,Db,S,[D / D's]).

database([message(Db,mq(Q,D),R) / Rs],Db,S,DVs) ←

handle_mq(Q,S, R),

database(Rs,Db,S,[D / DVs]).

database([message(Db,commit(Us,Ok,Go),R) / Rs]

Db,S,DVs) ←

try_commit(Us,Ok,Go,DVs,DVs',S,S') &

database(Rs,Db,S',DVs').

Commit ment: Databases

- A *commit(Us,Ok,Go)* message indicates a query wishes to commit
- If no concurrent executes or reads to database, signal that commit may proceed (*Ok = ok*)
- If query signals that commit should proceed (*Go = go*) apply updates *Us*

```
mode try_commits(Us?,Ok↑,Go?,DVs?,DVs'?,S?,S'↑).
try_commits(Us,ok,Go,DVs,[ ],S,S') ←
    check(DVs),
    valid_updates(Us) :
    try_commits2(Us,Go,S,S');      % Note sequential OR
try_commits(Us,abort,Go,DVs, DVs,S,S).
```

```
mode try_commits2(Updates?,Go?,Source?,Source'↑).
try_commits2(Us,go,S,S') ← apply_updates(Us,S,S').
try_commits2(Us,abort,S,S).
```

```
check([D | DVs]) ← not(var(D)) : check(DVs).
check([ ]).
```

PPS: Summary

- The PPS is a sophisticated programming environment / operating system for PARLOG, written in PARLOG
- Individual relations in its implementation can be read as specifications of programming environment components
- Components execute concurrently
- Directional unification (dataflow) is used to constrain reduction to obtain desired operational behaviour
- Back communication and synchronization variables provide a succinct representation of a parallel algorithm: distributed database update
- The control metacall is used to initiate, monitor and control user computation
- Exception messages provide for communication between user tasks and operating system

PARLOG Implementation

Two approaches: *Shallow or-parallel (non-flat)* and *flat*.

- *Non-flat*: user defined predicates in guards \Rightarrow *AND-OR tree*.
- *Flat*: only simple tests in guards \Rightarrow *process pool*.

Non-flat implementation work: restricted to PARLOG.

Flat implementation work: Flat PARLOG; FCP; FGHC.

(Flat PARLOG + metacall = Full PARLOG)

- **Non-flat PARLOG:** *AND-OR tree* computational model

Sequential PARLOG Machine (SPM)	Sequential
PARLOG on Prolog	Sequential
**Shared Memory Multiprocessors	Parallel

- **Flat PARLOG:** *Process pool* computational model

ALICE packet rewrite machine	Parallel
**Flat PARLOG Machine (FPM)	Sequential/ (Distributed)

- **PARLOG control metacall**

Sequential PARLOG Machine
**Flat PARLOG Machine

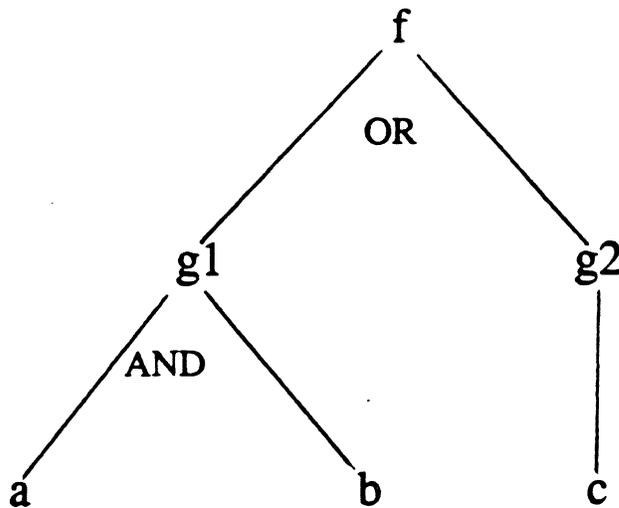
(** = *described here*)

Shallow Or-Parallelism in PARLOG

Deep guards mean that program execution may create an *AND-OR tree*.

PARLOG's *guard safety* mean that multiple environments are *not* required during OR-parallel evaluation

$f \leftarrow g1 : b1.$ $g1 \leftarrow a, b.$ $g2 \leftarrow c.$
 $f \leftarrow g2 : b2.$



AND/OR Tree

Nodes may be regarded as processes

Non-leaf nodes await evaluation of offspring

Leaf nodes correspond to reducible or suspended processes

Crammond's Process Model

Two types of process:

Goal processes - (AND processes)
responsible for creating child clause processes

Clause processes - (OR processes)
responsible for executing a single clause

Process States:

Runnable, executing
Runnable, queued

Suspended on variable
Suspended on child

Execution:

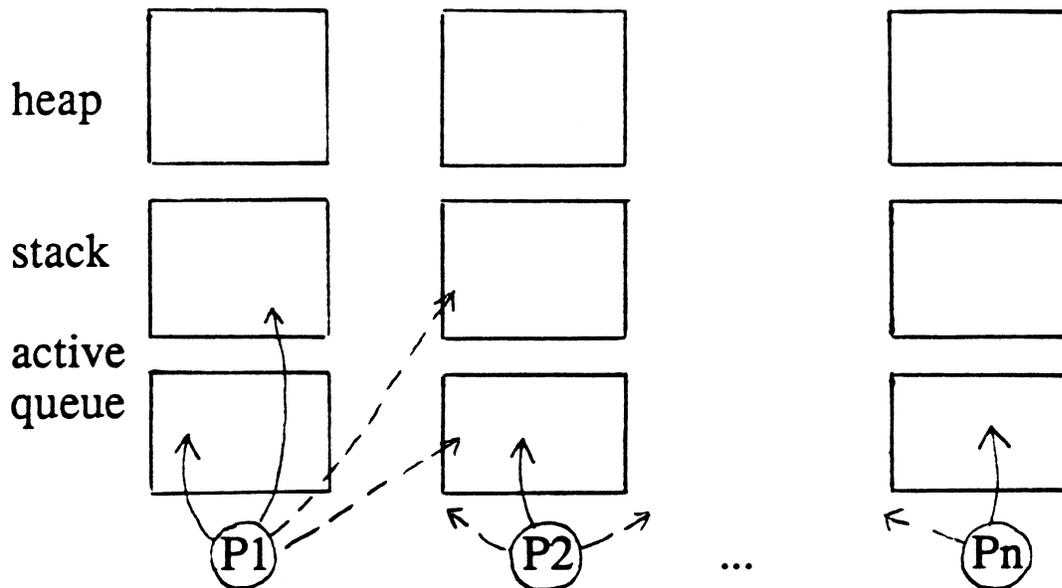
- A goal process creates a clause process for each clause
- Each clause process spawns goal processes to solve guard goals
- First clause process to succeed with guard commits and spawns goal processes to solve body goals
- Processes communicate by signals

Process Signals: DONE + QUIT

Goal process succeeds	—————>	DONE
Goal process fails	—————>	QUIT
Clause process succeeds	—————>	QUIT
Clause process fails	—————>	DONE

Implementation: Sequent Multiprocessor

- Sequent: shared memory multiprocessor with hardware locks
- One Unix process / processor; executes PARLOG processes
- Each processor has its own data areas
- Locks used when writing shared data areas
- Procedures are encoded using Warren-like code
- Processes are represented as data structures



- Processors 'steal' processes from neighbours when necessary
- Optimisations for flat programs:
 - do not generate clause processes if a test on a single argument can reduce choice to a single clause
- Significant speedups achieved: 4.6 times on 5 processors

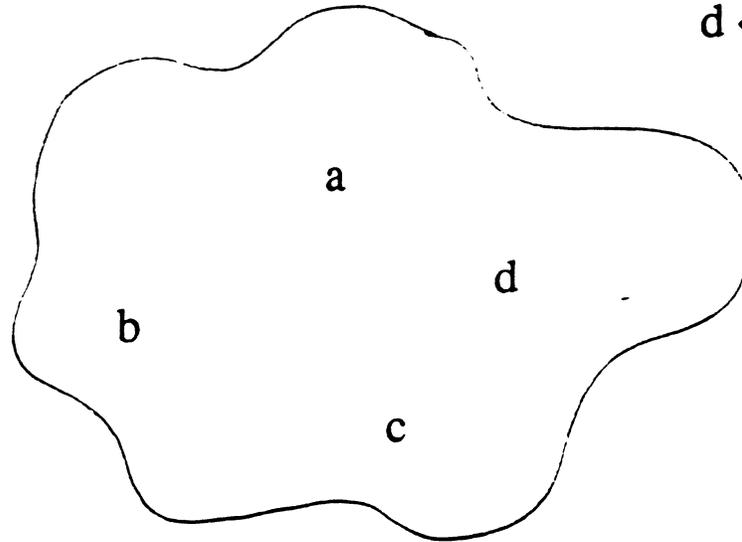
Flat PARLOG Computational Model

- Computation = process pool

$p \leftarrow a, b, c, d.$

$d \leftarrow g1 : b1, u, v.$

$d \leftarrow g2 : b2.$

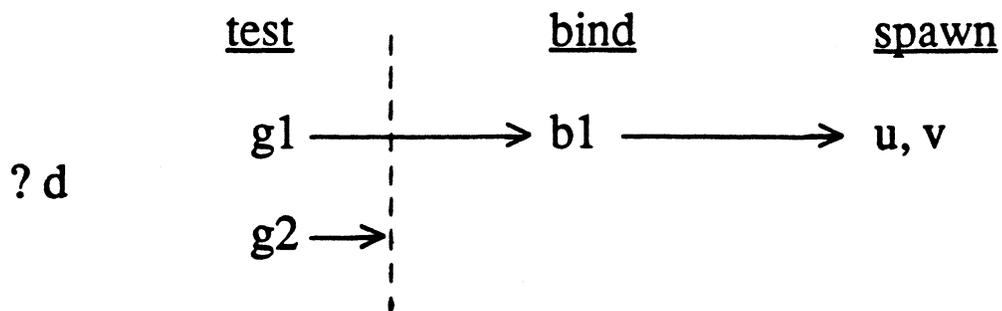


- Repeatedly select and attempt to reduce processes using clauses defining procedure
- Three phase reduction cycle:

test then bind then spawn.

Input mode arguments + guard calls define *tests*

Output mode arguments + '=' calls define *binds*



- A process try may succeed, fail or suspend.

Compilation of Flat Parlog

Flat Parlog:

mode lookup(Key?, Data[^], Dict?, NewDict[^]).

lookup(K, D, [{K,D} | Ds], [{K,D} | Ds]).

Standard Form:

lookup(K,D, A3,A4) ←

[{K1,D1} | Ds] ← A3, K == K1 : D = D1, A4 = [{K1,D1} | Ds].

<test>

<bind>

(<spawn>)

Compiled Form:

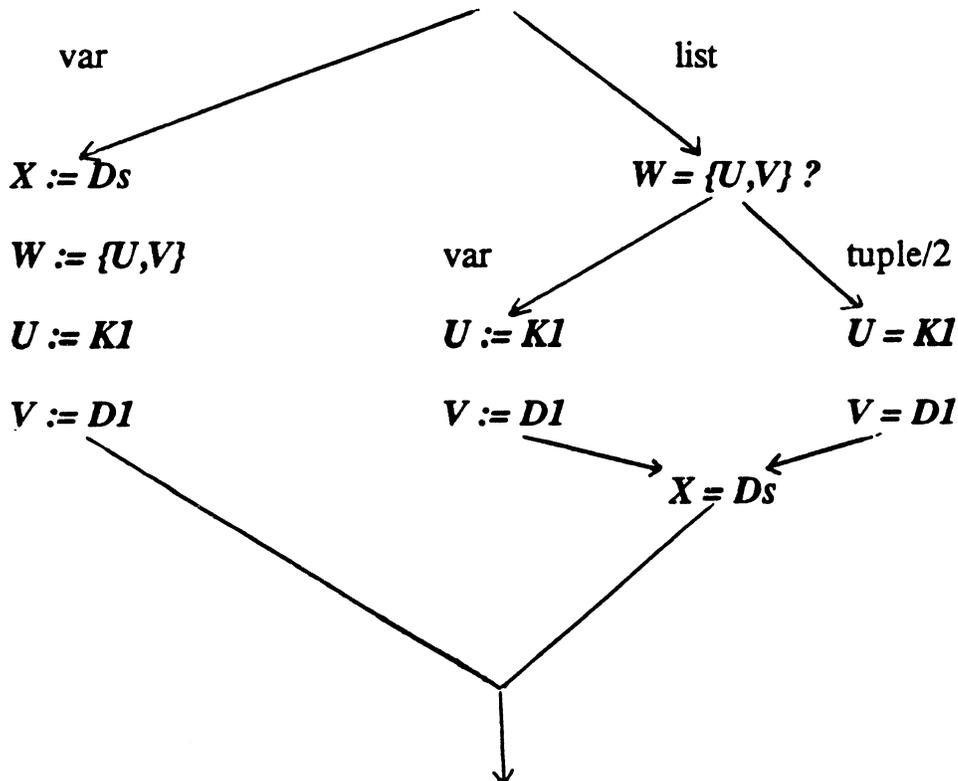
[P | Ds] ← A3

{K1, D1} ← P

K == K1

D = D1

A4 = [W | X]?



Compilation of Flat Parlog *contd*

- Compile unification to basic operations:

$T \Leftarrow V$	Input matching	<i>test_integer, test_list</i>
$V := T$	Assignment	<i>put_integer</i>
$V = T$	Binding	<i>bind_integer, bind_list</i>
$V = V$	General unification	<i>unify</i>
$V == V$	Equality	<i>equals</i>

- All instructions single mode (alternative: moded instructions)
- Input matching *and* output unification compiled

Lookup/4:

load(4)

try_me_else(Lookup4)

test_list(2,4)

$[P | D] \Leftarrow A3$

test_tuple(4,2,6)

$\{K1, D1\} \Leftarrow P$

<test>

equal(6,0)

$K == K1$

unify(1,7)

bind_list(3)

get(8)

put_value(5)

put_tuple(2,8)

<bind>

put_value(0)

put_value(7)

halt

Lookup1:

get(2,8,11)

bind_tuple(8,2,Lookup3)

put_value(0)

put_value(7)

Lookup2:

unify(11,5)

halt

Lookup3:

get(2,9,10)

unify(9,0)

unify(10,7)

goto(Lookup2)

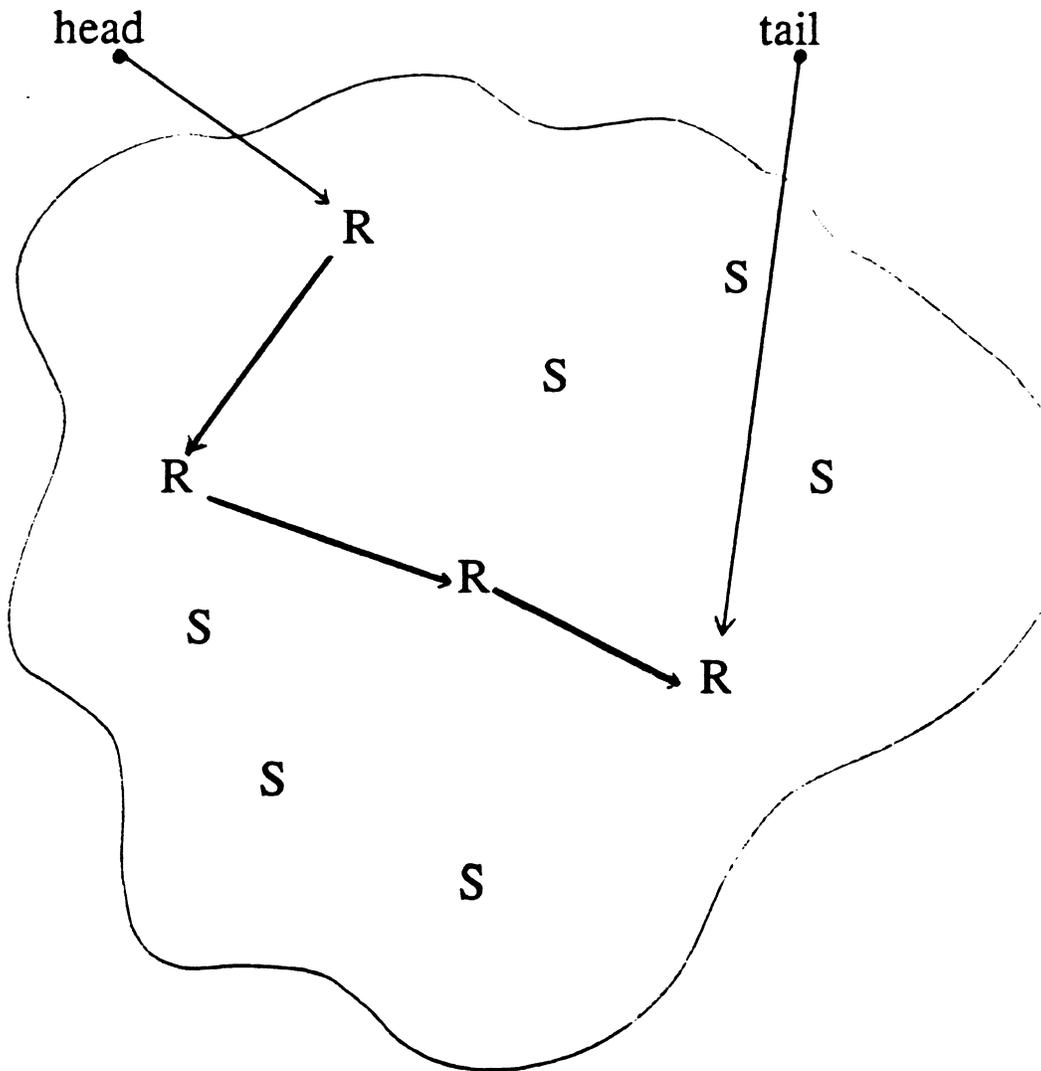
Lookup4:

Note absence of a commit operator

Flat Parlog Machine

Process pool computational model +

- scheduling structure:
to avoid selecting suspended processes
- tail recursion:
to avoid repeated selection of processes



PARLOG Control Metacall

call(Module,Priority,Goal,Status,Control)

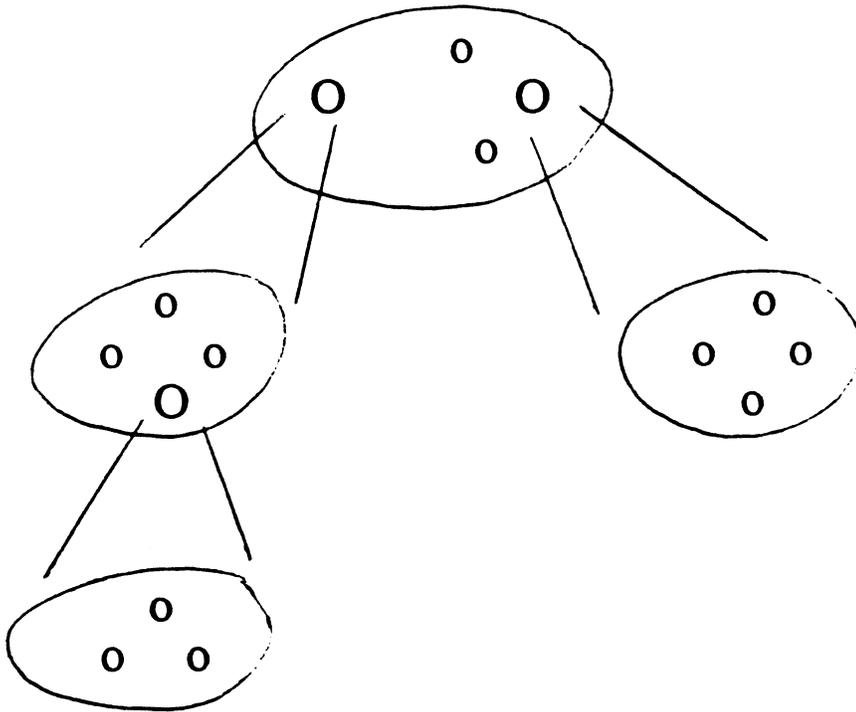
- Initiate a computation
- Signal termination of a computation
- Allow control of a computation
- Provide fair and prioritized scheduling of a computation

Implementation via extensions to Flat PARLOG Machine

(a) New computational model

Flat PARLOG + metacall = computation tree

A process pool may contain subpools



- A subpool is a computation or task
- Reduction repeatedly selects {computation,process} pair

Extensions to Flat PARLOG Machine, contd:

(b) Allow for termination of a computation

- process failure = success of computation + failed status message
- no processes in a computation = success of computation
- no reducible processes in a computation = computation deadlock

(c) Fair and prioritized computation scheduling

- fairness = bounded depth-first round-robin scheduling
- priorities = directed selection of {computation, process} pair

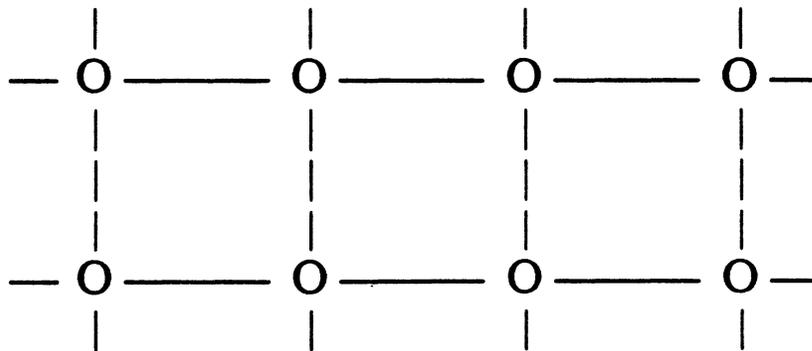
Benchmarks on uniprocessors (SUN-3) show only 2-3 % performance degradation when FPM is extended to support control metacall.

Parallel Execution of Flat PARLOG

(Based on Taylor's FCP Implementation)

Assume:

- many processors connected by regular interconnection topology (mesh, hypercube)
- no global memory; each processor has local memory
- processors may communicate by message passing
- Flat PARLOG computation (process pool) distributed over many processors
- each processor executes Flat PARLOG Machine



Three issues:

- distributed unification (discussed here)
- distributed computation control (metacall)
- load balancing, code mapping

Distributed Unification

PARLOG:

```
mode f(?,^).  
f(1,2) <- g.
```

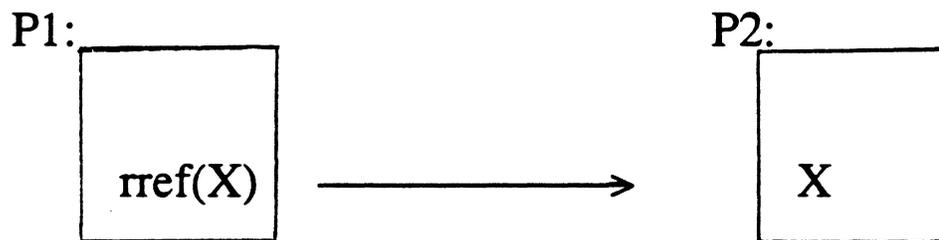
Standard form:

$$f(X_0, X_1) \leftarrow X_0 \leftarrow 1 : X_2 = 2, g.$$

Reduction Cycle:

test:	$X_0 \leftarrow 1 ?$	(read)	} may encounter
			} remote references
bind:	$X_1 = 2$	(write)	}
spawn:	g		

Remote reference = processor number + address.



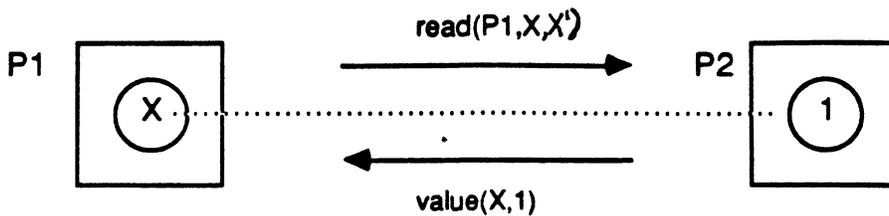
Unification + remote refs = extended unification algorithm:

- test phase: generate read messages and suspend process if remote references encountered (e.g. X_0 is remote)
- bind phase: generate unify message if remote reference encountered (e.g. X_1 is remote)

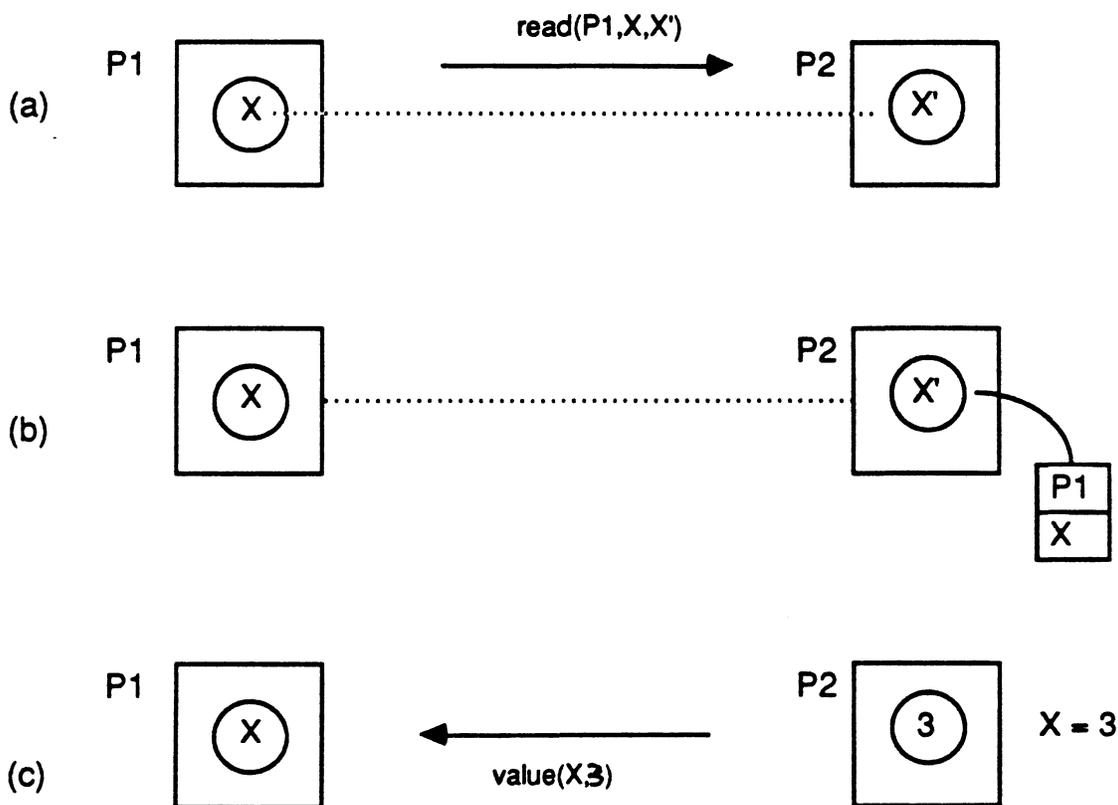
Messages dereference remote references until values or variables found

Distributed Unification: Reading

1. $X \leftarrow 1$: value is available.

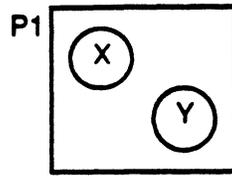


2. $X \leftarrow 1$: value is not available



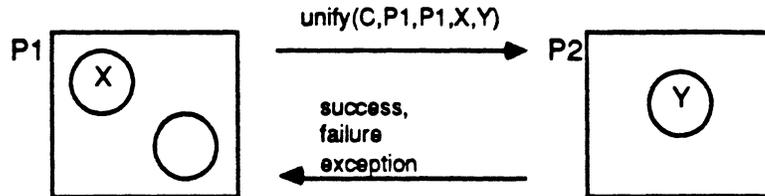
Distributed Unification: Writing

(a) Both local



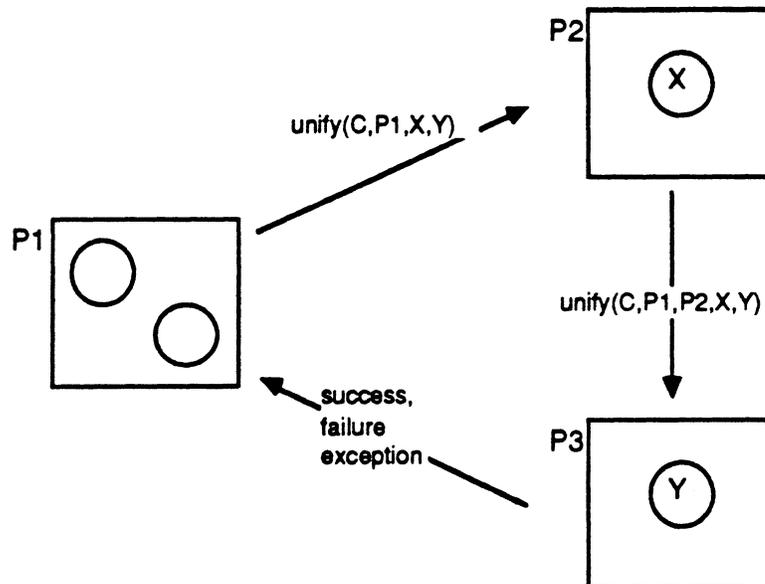
$X = Y$

(b) One local,
One remote



$\text{value}(X) = Y$

(c) Both remote



$\text{value}(X) = Y$

Recent Developments

1. Move to Flat Languages

Recall: A flat parallel logic language only permits calls to system primitive predicates in clause guards.

Why flat?

(a) Necessity

CP	—>	FCP)	appears
)	essential for
GHC	—>	FGHC)	implementation

(b) Convenience

PARLOG —> Flat PARLOG simplicity + efficiency

(Recall: Flat PARLOG + metacall = PARLOG)

Justification: two suppositions:

"Most programs are flat"

"Flat languages can be implemented more efficiently"

Both of which are true ... some of the time

- certain applications (e.g. AI) make extensive use of PARLOG's shallow OR-parallelism
- clever PARLOG implementations (e.g. Crammond's) can approach flat language efficiency

Recent Developments

2. Restoring Completeness

PARLOG and GHC are correct but incomplete logic languages

In certain applications, this lack of completeness is a disadvantage

2.1. P-Prolog

- incorporates exclusive relations
- synchronization mechanism: an exclusive relation cannot reduce until at most one clause is applicable

Example:

$$\begin{aligned} & \text{append}([X / Xs], Ys, [X / Zs]) \leftarrow \text{append}(Xs, Ys, Zs). \\ & \text{append}([], Ys, Ys). \end{aligned}$$

This cannot reduce until its first OR second and third arguments are instantiated.

- Permits multi-moded relations
- Alternative syntax permits non-exclusive relations
- Not clear that P-Prolog can be efficiently implemented

Recent Developments

2.2 PARLOG & Prolog United

- PARLOG has two set constructor interfaces to pure Horn clauses:

set(Solutions ↑, Term?, Conjunction?)

incrementally binds *Solutions* to a list of solutions

subset(Solutions?, Term?, Conjunction?)

generates solutions as *Solutions* is bound to a list of variables

- Recently, Clark and Gregory propose linking PARLOG and Prolog more tightly
- General two-way communication between Prolog and PARLOG computations
- Applications and implementation not yet clear

2.3 Compiling Prolog to Parallel Logic Languages

- Ueda, Tamaki describe techniques for compiling Horn clause programs to GHC
- Can handle exhaustive search programs and generate and test
- Restrictive: modes must be specified at compile-time

Who's Using Parallel Logic Languages?

(Partial list)

Research groups:

PARLOG Group, Imperial College, London.
ICOT Research Centre, Tokyo.
Weizmann Institute, Israel
Vulcan Group, Xerox PARC

Industry in Uk, Sweden, Japan, ...

Implementations

Distribution

PARLOG Group:	PARLOG on Unix and Prolog
Weizmann:	FCP on Unix
ICOT:	FGHC on Prolog

Experimental

PARLOG Group:	Sequent, ALICE, Flat Parlog Machine
Weizmann:	Hypercube
ICOT:	multi-PSI
others in UK, Sweden, Japan, ...	

Directions for Future Development

- Fast parallel implementations

On custom hardware:

ICOT: multi-PSI 100K RPS/PSI-II x 100 = ...

Conventional machines

native code compilation of FCP: 75K RPS on SUN-3s

- Formal semantics

facilitating:

program transformation

program analysis and debugging

- Declarative programming environments

- Language extensions and new languages

restoring completeness

constraints

typing

- New applications

distributed systems

AI

- Commercial exploitation

as a specification and implementation language for distributed systems

for parallel symbolic processing

Conclusions

- Parallel logic languages =
Horn clause logic + concurrent evaluation
dataflow synchronization
committed-choice non-determinism
- Declarative content makes parallel logic programs:
easy to understand
easy to transform and analyze
- Parallel evaluation permits parallel symbolic processing
- Operational characteristics make parallel logic languages a powerful programming formalism
- Efficient parallel implementations are being developed
- Broad range of applications
- Parallel logic languages are a viable language for expressing and implementing parallel algorithms

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